



DRV8871 3.6A ブラシ付きDCモータ・ドライバ、電流センス内蔵(PWM制御)

1 特長

- Hブリッジ・モータ・ドライバ
 - 1台のDCモータ、ステッピング・モータの1つの巻線、またはその他の負荷を駆動
- 6.5V～45Vの広い動作電圧範囲
- 標準値565mΩの直流オン抵抗(ハイサイドとローサイド)
- 3.6Aのピーク駆動電流
- PWM制御インターフェイス
- センス抵抗不要の電流レギュレーション
- 低消費電力のスリープ・モード
- 小さなパッケージと占有面積
 - 8ピンHSOP: PowerPAD™
 - 4.9 × 6 mm
- 保護機能を内蔵
 - VM低電圧誤動作防止(UVLO)
 - 過電流保護(OCP)
 - サーマル・シャットダウン(TSD)
 - エラーからの自動復旧

2 アプリケーション

- プリンタ
- 家電製品
- 産業用機器
- その他のメカトロ用途

3 概要

DRV8871デバイスは、プリンタ、家電機器、産業用機器、その他小型機械用のブラシ付きDCモータ・ドライバです。2つのロジック入力(Hブリッジ・ドライバ)を制御します。ドライバは4つのNチャネルMOSFETで構成され、最大ピーク電流3.6Aまでのモータを双方向制御します。入力をパルス幅変調(PWM)し電流減衰モードを選択してモータ回転数を制御できます。両方の入力を“L”にすると低消費電力スリープ・モードになります。

DRV8871デバイスには、高度な電流レギュレーション回路が搭載されており、アナログ基準電圧や、外付けのセンス抵抗を必要としません。この新たなソリューションは、標準の低コストで低消費電力の抵抗を使用して、電流スレッシュホールドを設定できます。電流を既知のレベルに制限できるため、システムに必要な電力を大幅に低減でき、特にモータの始動時やストール時に、安定した電圧を維持するため必要なバルク容量も低減できます。

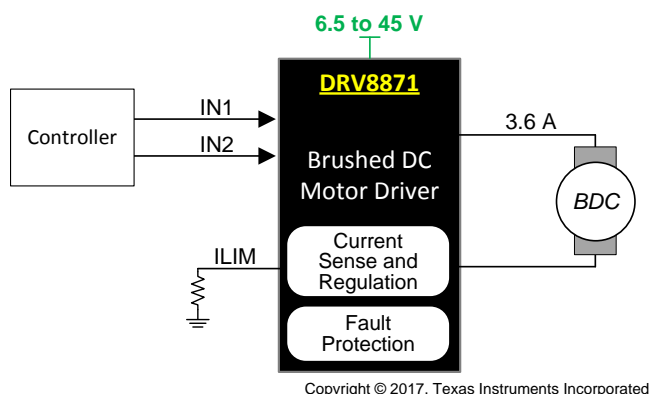
このデバイスは、低電圧(UVLO)、過電流(OCP)、過熱(TSD)などのフォルトや短絡から完全に保護されています。エラー状態が解消されると、デバイスは自動的に通常動作状態に復帰します。

製品情報 (1)

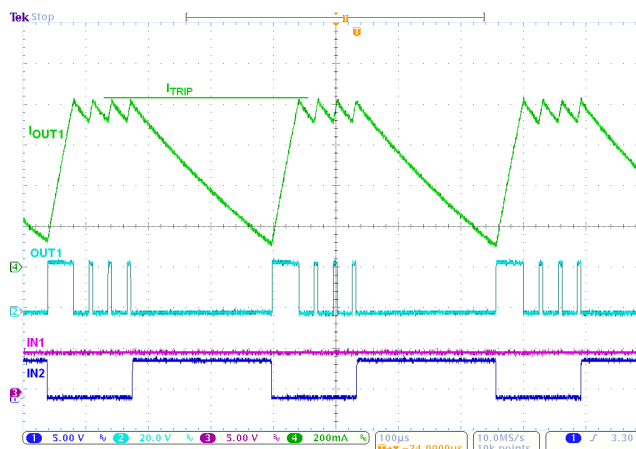
型番	パッケージ	本体サイズ(typ)
DRV8871	HSOP (8)	4.90mm×6.00mm

(1) 提供されているすべてのパッケージについては、巻末の注文情報を参照してください。

概略回路図



ピーク電流のレギュレーション



目次

1	特長	1	8	Application and Implementation	11
2	アプリケーション	1	8.1	Application Information	11
3	概要	1	8.2	Typical Application	11
4	改訂履歴	2	9	Power Supply Recommendations	14
5	Pin Configuration and Functions	3	9.1	Bulk Capacitance	14
6	Specifications	3	10	Layout	15
6.1	Absolute Maximum Ratings	3	10.1	Layout Guidelines	15
6.2	ESD Ratings	3	10.2	Layout Example	15
6.3	Recommended Operating Conditions	4	10.3	Thermal Considerations	15
6.4	Thermal Information	4	10.4	Power Dissipation	15
6.5	Electrical Characteristics	5	11	デバイスおよびドキュメントのサポート	17
6.6	Typical Characteristics	6	11.1	ドキュメントのサポート	17
7	Detailed Description	7	11.2	ドキュメントの更新通知を受け取る方法	17
7.1	Overview	7	11.3	コミュニティ・リソース	17
7.2	Functional Block Diagram	7	11.4	商標	17
7.3	Feature Description	8	11.5	静電気放電に関する注意事項	17
7.4	Device Functional Modes	10	11.6	Glossary	17
			12	メカニカル、パッケージ、および注文情報	17

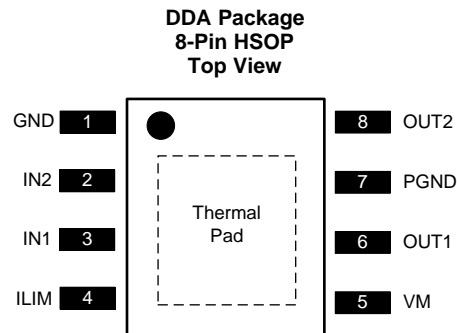
4 改訂履歴

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

Revision A (January 2016) から Revision B に変更	Page
Deleted the power supply voltage ramp rate (VM) parameter from the <i>Absolute Maximum Ratings</i> table	3
Added the output current parameter to the <i>Absolute Maximum Ratings</i> table	3
追加「ドキュメントの更新通知を受け取る方法」セクション	17

2015年8月発行のものから更新	Page
Updated the f_{PWM} max value and added a note	4
Removed the redundant T_A condition and added $f_{PWM} = 24$ kHz	5
Added more information to clarify how the max RMS current varies for different applications	12

5 Pin Configuration and Functions



Pin Functions

PIN		TYPE	DESCRIPTION	
NAME	NO.			
GND	1	PWR	Logic ground	Connect to board ground
ILIM	4	I	Current limit control	Connect a resistor to ground to set the current chopping threshold
IN1	3	I	Logic inputs	Controls the H-bridge output. Has internal pulldowns (see Table 1).
IN2	2			
OUT1	6	O	H-bridge output	Connect directly to the motor or other inductive load.
OUT2	8			
PGND	7	PWR	High-current ground path	Connect to board ground.
VM	5	PWR	6.5-V to 45-V power supply	Connect a 0.1-μF bypass capacitor to ground, as well as sufficient bulk capacitance, rated for the VM voltage.
PAD	—	—	Thermal pad	Connect to board ground. For good thermal dissipation, use large ground planes on multiple layers, and multiple nearby vias connecting those planes.

6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

	MIN	MAX	UNIT
Power supply voltage (VM)	−0.3	50	V
Logic input voltage (IN1, IN2)	−0.3	7	V
Continuous phase node pin voltage (OUT1, OUT2)	−0.7	VM + 0.7	V
Output current (100% duty cycle)	0	3.5	A
Operating junction temperature, T _J	−40	150	°C
Storage temperature, T _{stg}	−65	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

6.2 ESD Ratings

		VALUE	UNIT
V _(ESD) Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	±6000	V
	Charged-device model (CDM), per JEDEC specification JESD22-C101 ⁽²⁾	±750	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
V _M	Power supply voltage	6.5	45	V
V _I	Logic input voltage (IN1, IN2)	0	5.5	V
f _{PWM}	Logic input PWM frequency (IN1, IN2)	0	200 ⁽¹⁾	kHz
I _{peak}	Peak output current ⁽²⁾	0	3.6	A
T _A	Operating ambient temperature ⁽²⁾	–40	125	°C

(1) The voltages applied to the inputs should have at least 800 ns of pulse width to ensure detection. Typical devices require at least 400 ns. If the PWM frequency is 200 kHz, the usable duty cycle range is 16% to 84%.

(2) Power dissipation and thermal limits must be observed

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾		DRV8871	UNIT
		DDA (HSOP)	
		8 PINS	
R _{θJA}	Junction-to-ambient thermal resistance	41.1	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	53.1	°C/W
R _{θJB}	Junction-to-board thermal resistance	23.1	°C/W
ψ _{JT}	Junction-to-top characterization parameter	8.2	°C/W
ψ _{JB}	Junction-to-board characterization parameter	23	°C/W
R _{θJC(bot)}	Junction-to-case (bottom) thermal resistance	2.7	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report (SPRA953).

6.5 Electrical Characteristics

$T_A = 25^\circ\text{C}$, over recommended operating conditions (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
POWER SUPPLY (VM)						
VM	VM operating voltage		6.5		45	V
I_{VM}	VM operating supply current	VM = 12 V		3	10	mA
$I_{VMSLEEP}$	VM sleep current	VM = 12 V			10	μA
$t_{ON}^{(1)}$	Turn-on time	VM > V_{UVLO} with IN1 or IN2 high		40	50	μs
LOGIC-LEVEL INPUTS (IN1, IN2)						
V_{IL}	Input logic low voltage				0.5	V
V_{IH}	Input logic high voltage		1.5			V
V_{HYS}	Input logic hysteresis			0.5		V
I_{IL}	Input logic low current	$V_{IN} = 0\text{ V}$	–1		1	μA
I_{IH}	Input logic high current	$V_{IN} = 3.3\text{ V}$		33	100	μA
R_{PD}	Pulldown resistance	To GND		100		k Ω
t_{PD}	Propagation delay	INx to OUTx change (see Figure 6)		0.7	1	μs
t_{sleep}	Time to sleep	Inputs low to sleep		1	1.5	ms
MOTOR DRIVER OUTPUTS (OUT1, OUT2)						
$R_{DS(ON)}$	High-side FET on resistance	VM = 24 V, $I = 1\text{ A}$, $f_{PWM} = 25\text{ kHz}$		307	360	m Ω
$R_{DS(ON)}$	Low-side FET on resistance	VM = 24 V, $I = 1\text{ A}$, $f_{PWM} = 25\text{ kHz}$		258	320	m Ω
t_{DEAD}	Output dead time			220		ns
V_d	Body diode forward voltage	$I_{OUT} = 1\text{ A}$		0.8	1	V
CURRENT REGULATION						
V_{ILIM}	Constant for calculating current regulation (see Equation 1)	$I_{OUT} = 1\text{ A}$	59	64	69	kV
t_{OFF}	PWM off-time			25		μs
t_{BLANK}	PWM blanking time			2		μs
PROTECTION CIRCUITS						
V_{UVLO}	VM undervoltage lockout	VM falls until UVLO triggers		6.1	6.4	V
		VM rises until operation recovers		6.3	6.5	
$V_{UV,HYS}$	VM undervoltage hysteresis	Rising to falling threshold	100	180		mV
I_{OCP}	Overcurrent protection trip level		3.7	4.5	6.4	A
t_{OCP}	Overcurrent deglitch time			1.5		μs
t_{RETRY}	Overcurrent retry time			3		ms
T_{SD}	Thermal shutdown temperature		150	175		$^\circ\text{C}$
T_{HYS}	Thermal shutdown hysteresis			40		$^\circ\text{C}$

(1) t_{ON} applies when the device initially powers up, and when it exits sleep mode.

6.6 Typical Characteristics

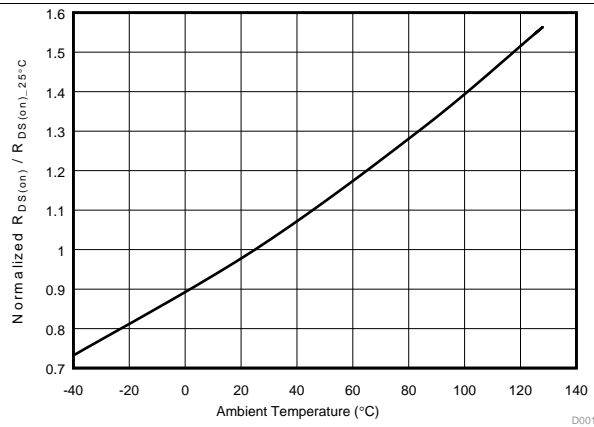


Figure 1. $R_{DS(on)}$ vs Temperature

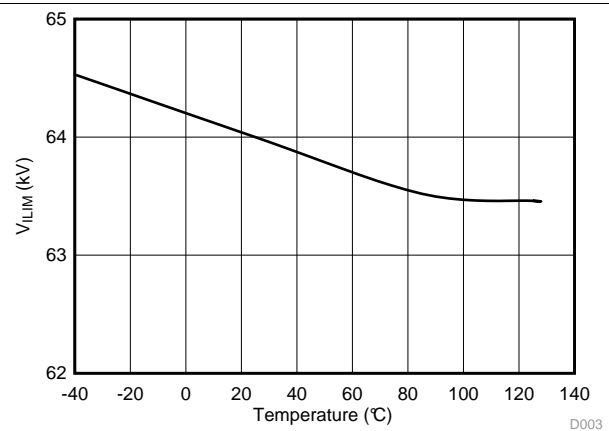


Figure 2. V_{ILIM} vs Temperature

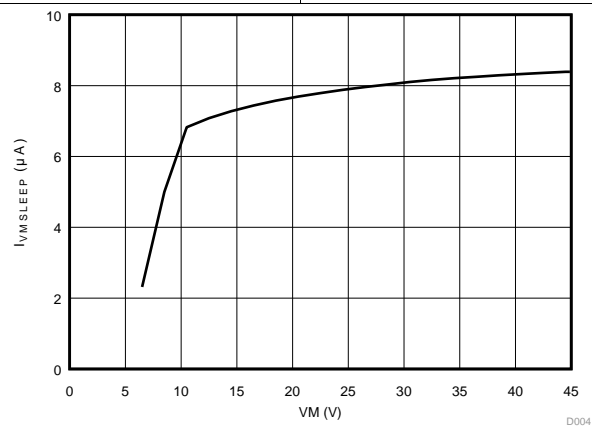


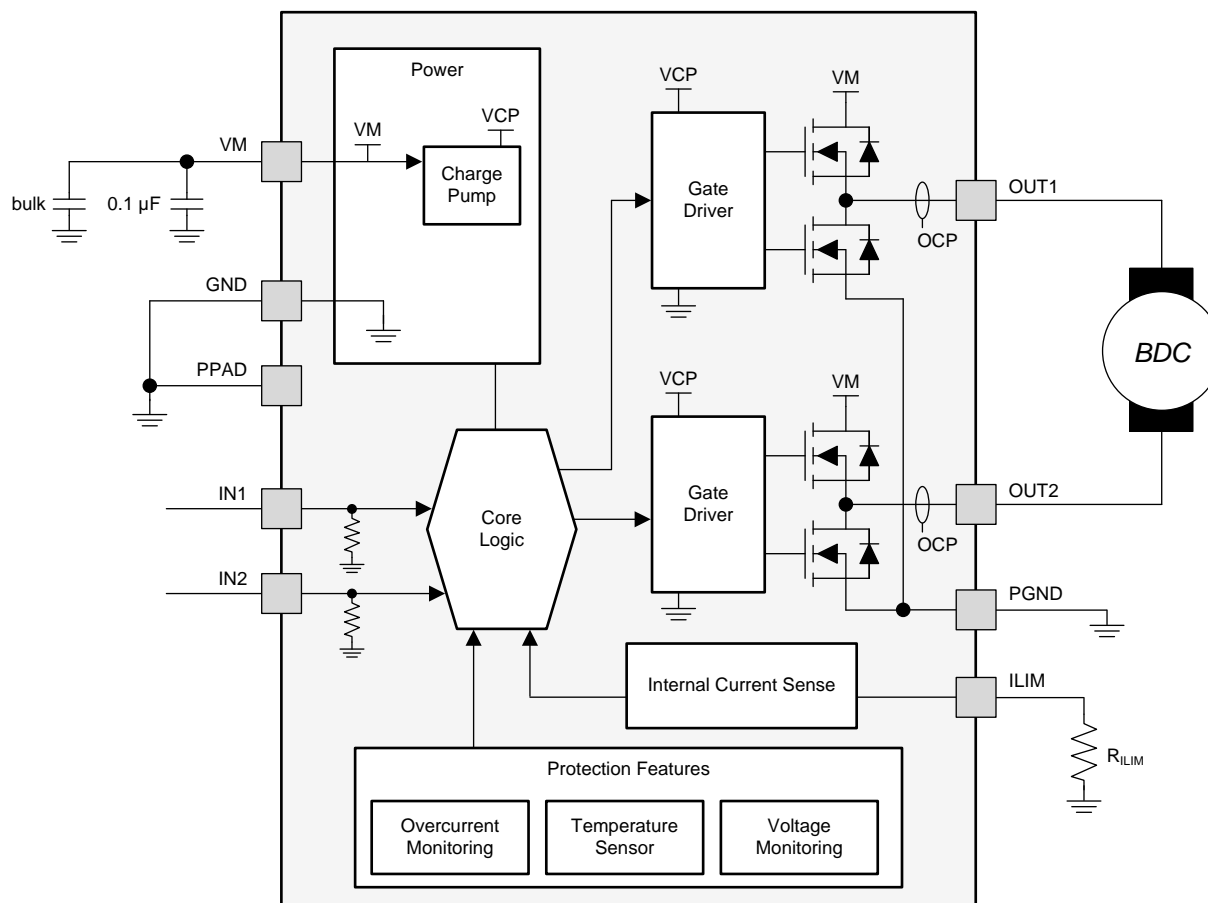
Figure 3. $I_{VMSLEEP}$ vs VM at 25°C

7 Detailed Description

7.1 Overview

The DRV8871 device is an optimized 8-pin device for driving brushed DC motors with 6.5 to 45 V and up to 3.6-A peak current. The integrated current regulation restricts motor current to a predefined maximum. Two logic inputs control the H-bridge driver, which consists of four N-channel MOSFETs that have a typical $R_{ds(on)}$ of 565 m Ω (including one high-side and one low-side FET). A single power input, VM, serves as both device power and the motor winding bias voltage. The integrated charge pump of the device boosts VM internally and fully enhances the high-side FETs. Motor speed can be controlled with pulse-width modulation, at frequencies between 0 to 100 kHz. The device has an integrated sleep mode that is entered by bringing both inputs low. An assortment of protection features prevent the device from being damaged if a system fault occurs.

7.2 Functional Block Diagram



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7.3 Feature Description

7.3.1 Bridge Control

The DRV8871 output consists of four N-channel MOSFETs that are designed to drive high current. They are controlled by the two logic inputs IN1 and IN2, according to Table 1.

Table 1. H-Bridge Control

IN1	IN2	OUT1	OUT2	DESCRIPTION
0	0	High-Z	High-Z	Coast; H-bridge disabled to High-Z (sleep entered after 1 ms)
0	1	L	H	Reverse (Current OUT2 → OUT1)
1	0	H	L	Forward (Current OUT1 → OUT2)
1	1	L	L	Brake; low-side slow decay

The inputs can be set to static voltages for 100% duty cycle drive, or they can be pulse-width modulated (PWM) for variable motor speed. When using PWM, it typically works best to switch between driving and braking. For example, to drive a motor forward with 50% of its max RPM, IN1 = 1 and IN2 = 0 during the driving period, and IN1 = 1 and IN2 = 1 during the other period. Alternatively, the coast mode (IN1 = 0, IN2 = 0) for *fast current decay* is also available. The input pins can be powered before VM is applied.

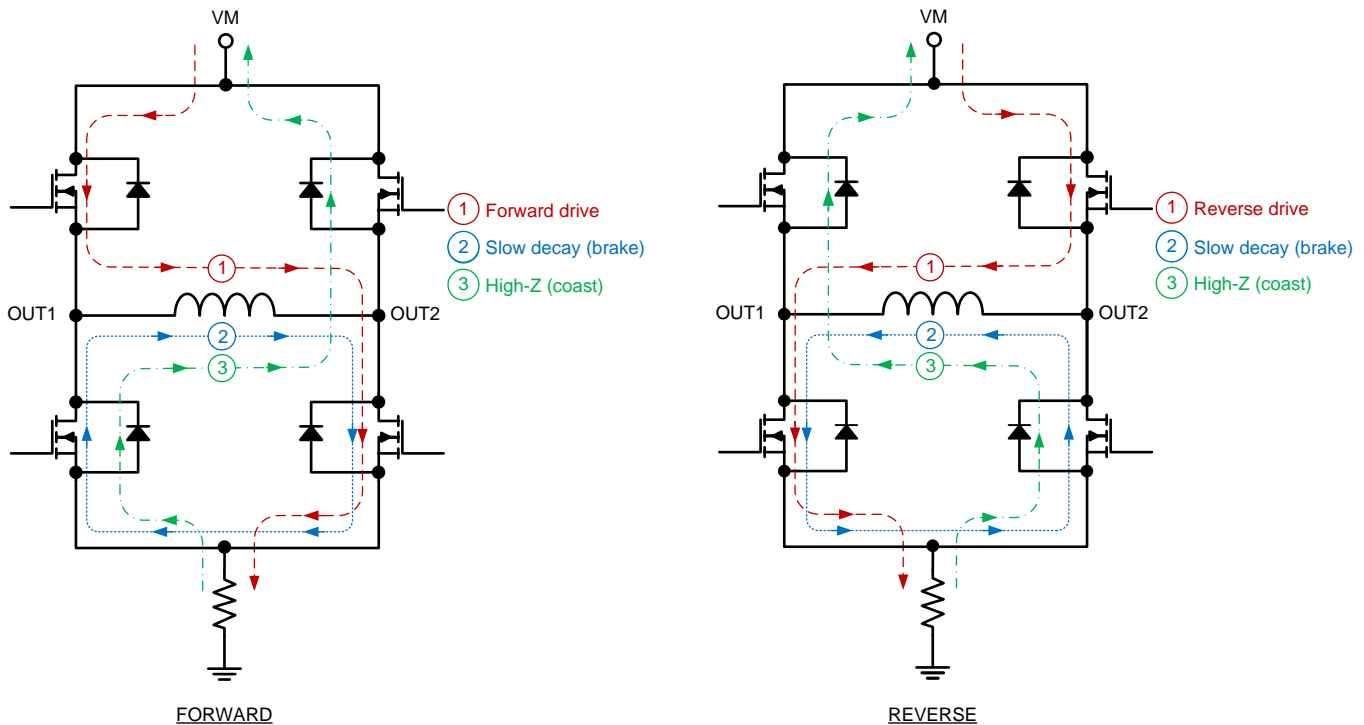


Figure 4. H-Bridge Current Paths

7.3.2 Sleep Mode

When IN1 and IN2 are both low for time t_{SLEEP} (typically 1 ms), the DRV8871 device enters a low-power sleep mode, where the outputs remain High-Z and the device uses $I_{VMSLEEP}$ (microamps) of current. If the device is powered up while both inputs are low, sleep mode is immediately entered. After IN1 or IN2 are high for at least 5 μs , the device will be operational 50 μs (t_{ON}) later.

7.3.3 Current Regulation

The DRV8871 device limits the output current based on a standard resistor attached to pin ILIM, according to this equation:

$$I_{TRIP} (A) = \frac{V_{ILIM} (kV)}{R_{ILIM} (k\Omega)} = \frac{64 (kV)}{R_{ILIM} (k\Omega)} \quad (1)$$

For example, if $R_{ILIM} = 32 \text{ k}\Omega$, the DRV8871 device limits motor current to 2 A no matter how much load torque is applied. The minimum allowed R_{ILIM} is 15 k Ω . System designers should always understand the min and max I_{TRIP} , based on the R_{ILIM} resistor component tolerance and the DRV8871 specified V_{ILIM} range.

When I_{TRIP} has been reached, the device enforces slow current decay by enabling both low-side FETs, and it does this for time t_{OFF} (typically 25 μ s).

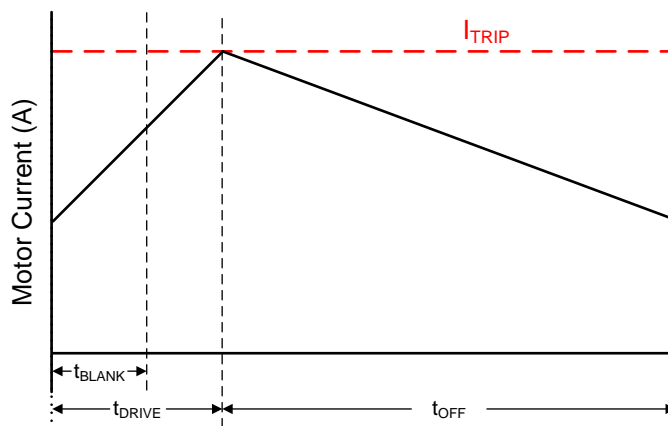


Figure 5. Current Regulation Time Periods

After t_{OFF} has elapsed, the output is re-enabled according to the two inputs INx. The drive time (t_{DRIVE}) until reaching another I_{TRIP} event heavily depends on the VM voltage, the motor's back-EMF, and the motor's inductance.

7.3.4 Dead Time

When an output changes from driving high to driving low, or driving low to driving high, dead time is automatically inserted to prevent shoot-through. t_{DEAD} is the time in the middle when the output is High-Z. If the output pin is measured during t_{DEAD} , the voltage will depend on the direction of current. If current is leaving the pin, the voltage will be a diode drop below ground. If current is entering the pin, the voltage will be a diode drop above VM. This diode is the body diode of the high-side or low-side FET.

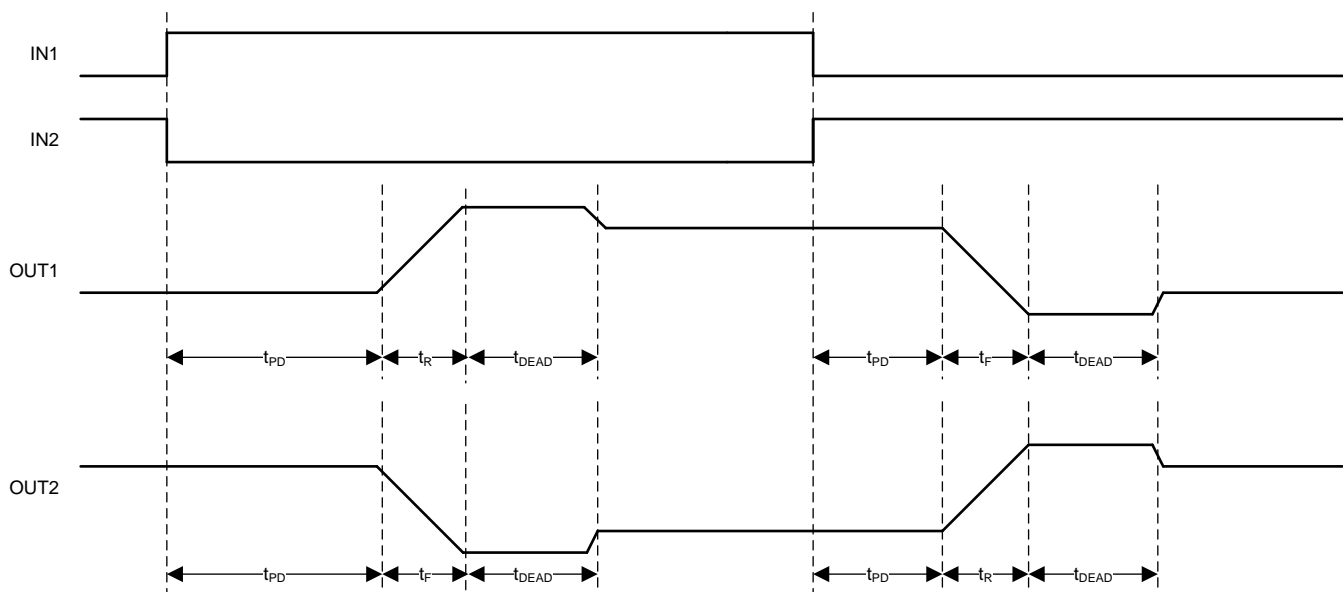


Figure 6. Propagation Delay Time

7.3.5 Protection Circuits

The DRV8871 device is fully protected against VM undervoltage, overcurrent, and overtemperature events.

7.3.5.1 VM Undervoltage Lockout (UVLO)

If at any time the voltage on the VM pin falls below the undervoltage lockout threshold voltage, all FETs in the H-bridge will be disabled. Operation will resume when VM rises above the UVLO threshold.

7.3.5.2 Overcurrent Protection (OCP)

If the output current exceeds the OCP threshold I_{OCP} for longer than t_{OCP} , all FETs in the H-bridge are disabled for a duration of t_{RETRY} . After that, the H-bridge will be re-enabled according to the state of the INx pins. If the overcurrent fault is still present, the cycle repeats; otherwise normal device operation resumes.

7.3.5.3 Thermal Shutdown (TSD)

If the die temperature exceeds safe limits, all FETs in the H-bridge will be disabled. After the die temperature has fallen to a safe level, operation automatically resumes.

Table 2. Protection Functionality

FAULT	CONDITION	H-BRIDGE STATUS	RECOVERY
VM undervoltage lockout (UVLO)	$VM < V_{UVLO}$	Disabled	$VM > V_{UVLO}$
Overcurrent (OCP)	$I_{OUT} > I_{OCP}$	Disabled	t_{RETRY}
Thermal Shutdown (TSD)	$T_J > 150^{\circ}\text{C}$	Disabled	$T_J < T_{SD} - T_{HYS}$

7.4 Device Functional Modes

The DRV8871 device can be used in multiple ways to drive a brushed DC motor.

7.4.1 PWM With Current Regulation

This scheme uses all of the device capabilities. I_{TRIP} is set above the normal operating current, and high enough to achieve an adequate spin-up time, but low enough to constrain current to a desired level. Motor speed is controlled by the duty cycle of one of the inputs, while the other input is static. Brake/slow decay is typically used during the off-time.

7.4.2 PWM Without Current Regulation

If current regulation is not needed, a 15-k Ω to 18-k Ω resistor should be used on pin ILIM. This mode provides the highest possible peak current: up to 3.6 A for a few hundred milliseconds (depending on PCB characteristics and the ambient temperature). If current exceeds 3.6 A, the device might reach overcurrent protection (OCP) or overtemperature shutdown (TSD). If that happens, the device disables and protects itself for about 3 ms (t_{RETRY}) and then resumes normal operation.

7.4.3 Static Inputs With Current Regulation

IN1 and IN2 can be set high and low for 100% duty cycle drive, and I_{TRIP} can be used to control the current, speed, and torque capability of the motor.

7.4.4 VM Control

In some systems it is desirable to vary VM as a means of changing motor speed. See [Motor Voltage](#) for more information.

8 Application and Implementation

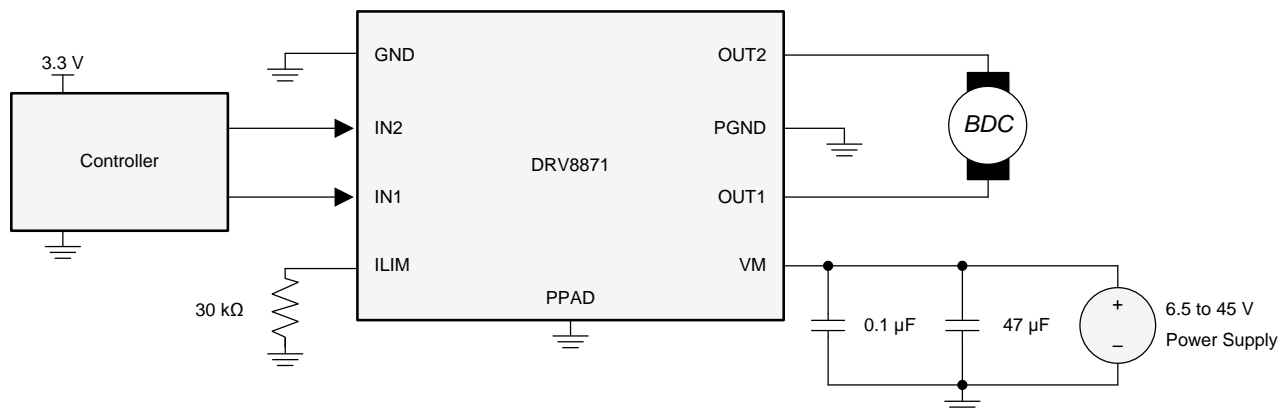
NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The DRV8871 device is typically used to drive one brushed DC motor.

8.2 Typical Application



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Figure 7. Typical Connections

8.2.1 Design Requirements

Table 3 lists the design parameters.

Table 3. Design Parameters

DESIGN PARAMETER	REFERENCE	EXAMPLE VALUE
Motor voltage	V_M	24 V
Motor RMS current	I_{RMS}	0.8 A
Motor startup current	I_{START}	2 A
Motor current trip point	I_{TRIP}	2.1 A
ILIM resistance	R_{ILIM}	30 kΩ
PWM frequency	f_{PWM}	5 kHz

8.2.2 Detailed Design Procedure

8.2.2.1 Motor Voltage

The motor voltage to use will depend on the ratings of the motor selected and the desired RPM. A higher voltage spins a brushed DC motor faster with the same PWM duty cycle applied to the power FETs. A higher voltage also increases the rate of current change through the inductive motor windings.

8.2.2.2 Drive Current

The current path is through the high-side sourcing DMOS power driver, motor winding, and low-side sinking DMOS power driver. Power dissipation losses in one source and sink DMOS power driver are shown in the following equation.

$$P_D = I^2 (R_{DS(on)Source} + R_{DS(on)Sink}) \quad (2)$$

The DRV8871 device has been measured to be capable of 2-A RMS current at 25°C on standard FR-4 PCBs. The max RMS current varies based on the PCB design, ambient temperature, and PWM frequency. Typically, switching the inputs at 200 kHz compared to 20 kHz causes 20% more power loss in heat.

8.2.3 Application Curves

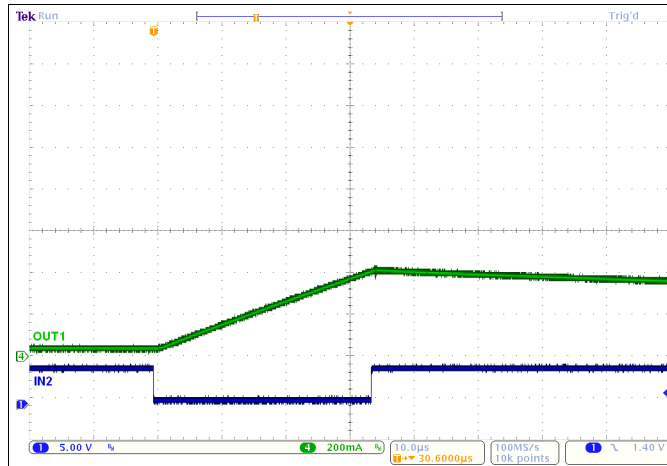


Figure 8. Current Ramp With a 2-Ω, 1 mH, RL Load and VM = 12 V

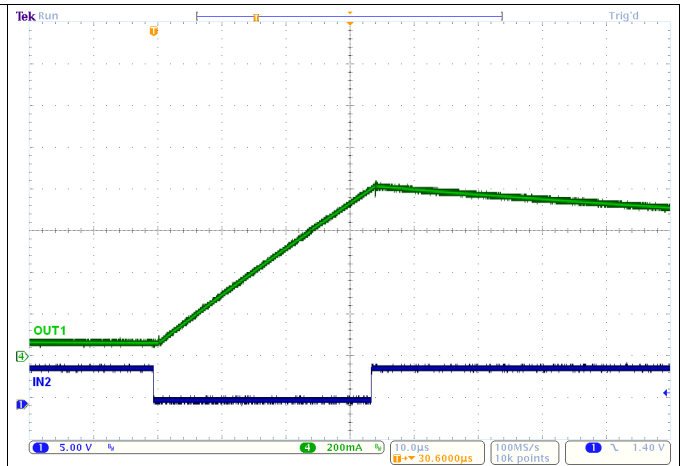


Figure 9. Current Ramp With a 2-Ω, 1 mH, RL Load and VM = 24 V

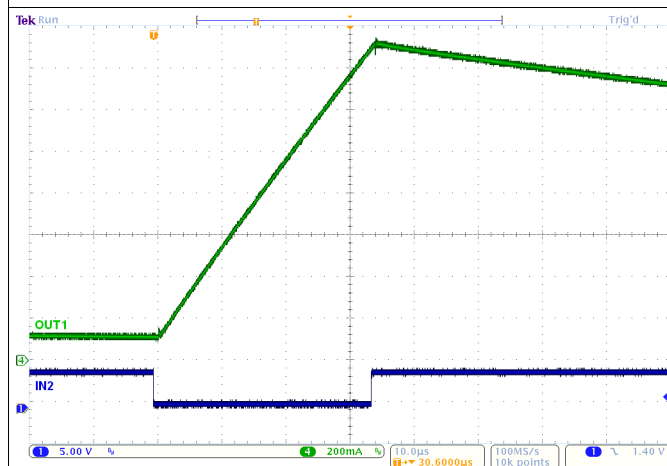


Figure 10. Current Ramp With a 2-Ω, 1 mH, RL Load and VM = 45 V

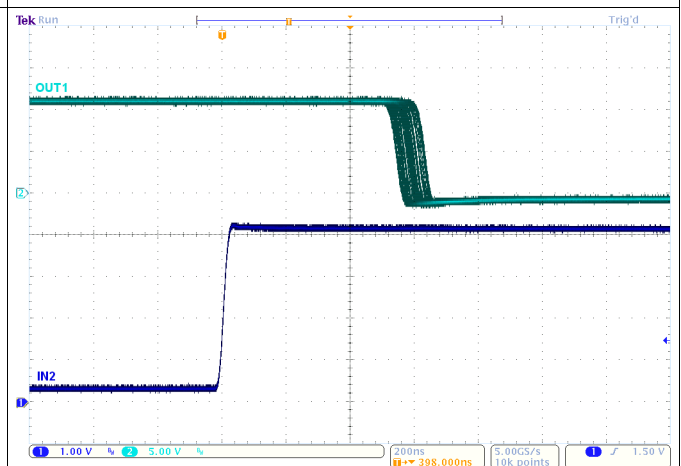


Figure 11. t_{PD}

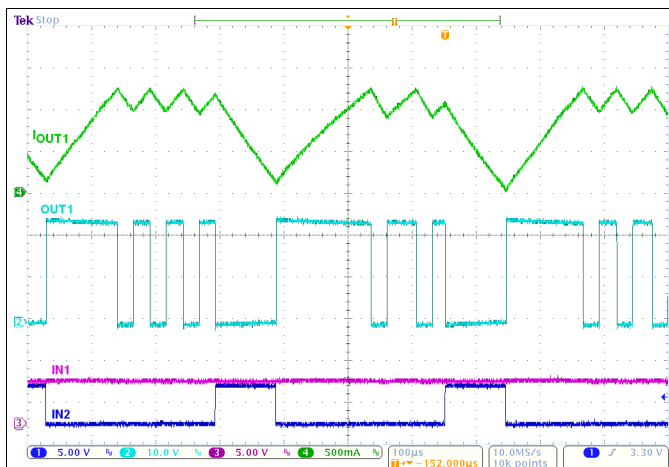


Figure 12. Current Regulation With $R_{ILIM} = 50.5 \text{ k}\Omega$

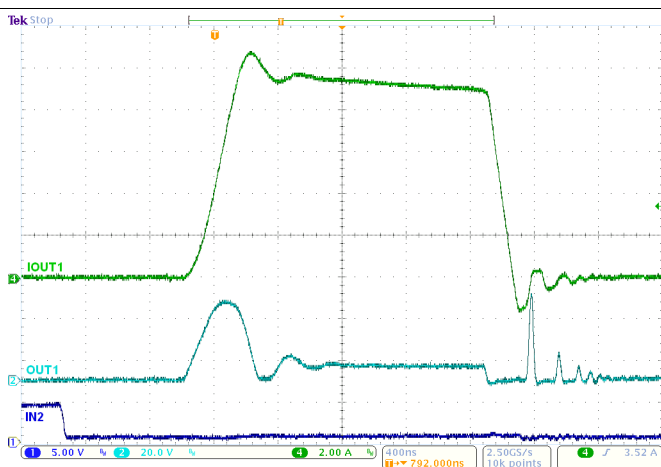


Figure 13. OCP With 45 V and the Outputs Shorted Together

9 Power Supply Recommendations

9.1 Bulk Capacitance

Having appropriate local bulk capacitance is an important factor in motor drive system design. In general, having more bulk capacitance is beneficial, while the disadvantages are increased cost and physical size.

The amount of local capacitance needed depends on a variety of factors, including:

- The highest current required by the motor system
- The power supply's capacitance and ability to source current
- The amount of parasitic inductance between the power supply and motor system
- The acceptable voltage ripple
- The type of motor used (brushed DC, brushless DC, stepper)
- The motor braking method

The inductance between the power supply and motor drive system will limit the rate current can change from the power supply. If the local bulk capacitance is too small, the system responds to excessive current demands or dumps from the motor with a change in voltage. When adequate bulk capacitance is used, the motor voltage remains stable and high current can be quickly supplied.

The data sheet generally provides a recommended value, but system-level testing is required to determine the appropriate sized bulk capacitor.

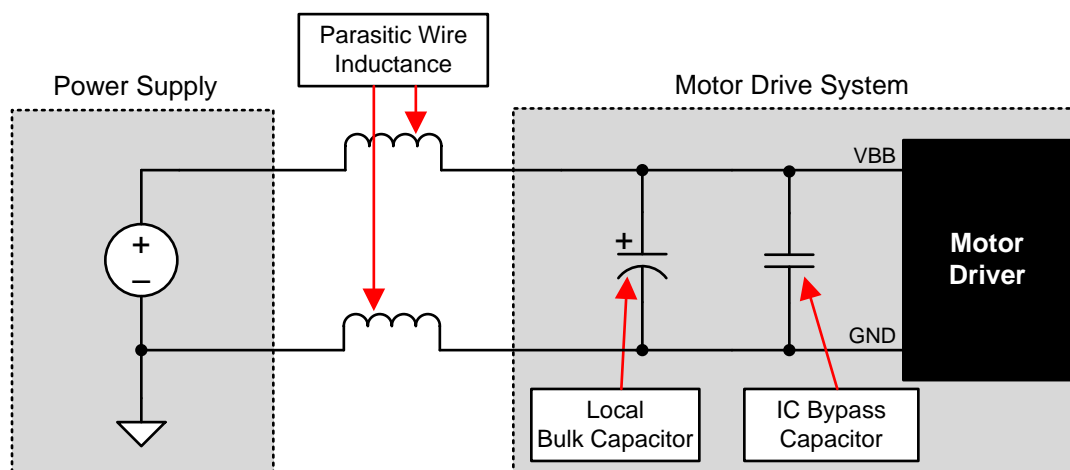


Figure 14. Example Setup of Motor Drive System With External Power Supply

The voltage rating for bulk capacitors should be higher than the operating voltage, to provide margin for cases when the motor transfers energy to the supply.

10 Layout

10.1 Layout Guidelines

The bulk capacitor should be placed to minimize the distance of the high-current path through the motor driver device. The connecting metal trace widths should be as wide as possible, and numerous vias should be used when connecting PCB layers. These practices minimize inductance and allow the bulk capacitor to deliver high current.

Small-value capacitors should be ceramic, and placed closely to device pins.

The high-current device outputs should use wide metal traces.

The device thermal pad should be soldered to the PCB top-layer ground plane. Multiple vias should be used to connect to a large bottom-layer ground plane. The use of large metal planes and multiple vias help dissipate the $I^2 \times R_{DS(on)}$ heat that is generated in the device.

10.2 Layout Example

Recommended layout and component placement is shown in [Figure 15](#)

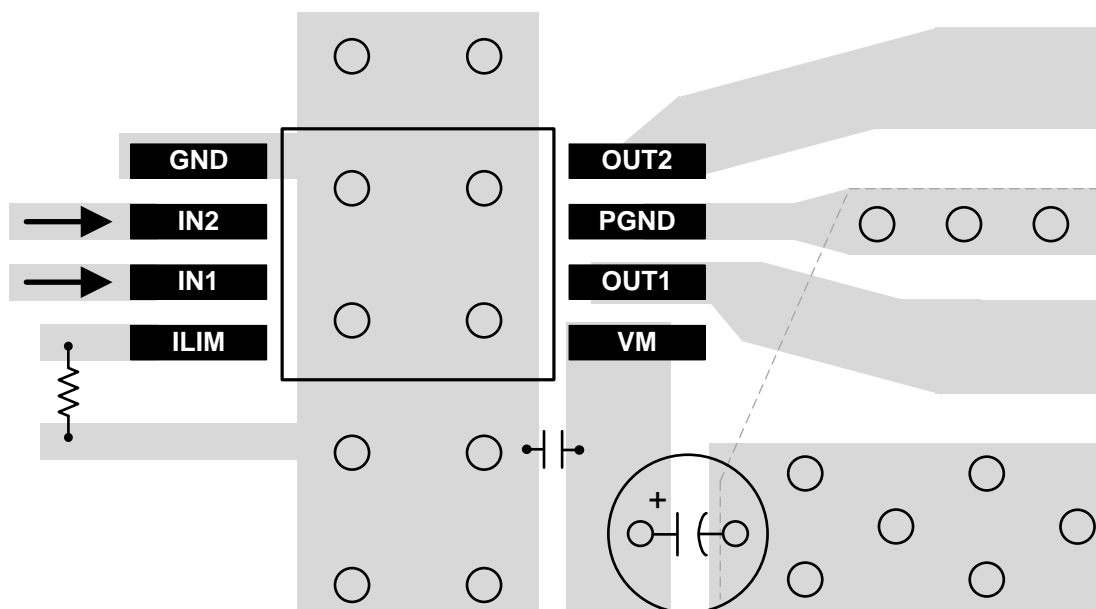


Figure 15. Layout Recommendation

10.3 Thermal Considerations

The DRV8871 device has thermal shutdown (TSD) as described in the [Thermal Shutdown \(TSD\)](#) section. If the die temperature exceeds approximately 175°C, the device is disabled until the temperature drops below the temperature hysteresis level.

Any tendency of the device to enter TSD is an indication of either excessive power dissipation, insufficient heatsinking, or too high of an ambient temperature.

10.4 Power Dissipation

Power dissipation in the DRV8871 device is dominated by the power dissipated in the output FET resistance, $R_{DS(on)}$. Use the equation in the [Drive Current](#) section to calculate the estimated average power dissipation when driving a load.

Note that at startup, the current is much higher than normal running current; this peak current and its duration must be also be considered.

Power Dissipation (continued)

The maximum amount of power that can be dissipated in the device is dependent on ambient temperature and heatsinking.

NOTE

$R_{DS(on)}$ increases with temperature, so as the device heats, the power dissipation increases. This fact must be taken into consideration when sizing the heatsink.

The power dissipation of the DRV8871 device is a function of RMS motor current and the FET resistance ($R_{DS(ON)}$) of each output.

$$\text{Power} \approx I_{RMS}^2 \times (\text{High-side } R_{DS(ON)} + \text{Low-side } R_{DS(ON)}) \quad (3)$$

For this example, the ambient temperature is 58°C, and the junction temperature reaches 80°C. At 58°C, the sum of $R_{DS(ON)}$ is about 0.72 Ω . With an example motor current of 0.8 A, the dissipated power in the form of heat will be $0.8 \text{ A}^2 \times 0.72 \Omega = 0.46 \text{ W}$.

The temperature that the DRV8871 device reaches depends on the thermal resistance to the air and PCB. It is important to solder the device PowerPAD to the PCB ground plane, with vias to the top and bottom board layers, in order dissipate heat into the PCB and reduce the device temperature. In the example used here, the DRV8871 device had an effective thermal resistance $R_{\theta JA}$ of 48°C/W, and:

$$T_J = T_A + (P_D \times R_{\theta JA}) = 58^\circ\text{C} + (0.46 \text{ W} \times 48^\circ\text{C/W}) = 80^\circ\text{C} \quad (4)$$

10.4.1 Heatsinking

The PowerPAD package uses an exposed pad to remove heat from the device. For proper operation, this pad must be thermally connected to copper on the PCB to dissipate heat. On a multi-layer PCB with a ground plane, this connection can be accomplished by adding a number of vias to connect the thermal pad to the ground plane.

On PCBs without internal planes, a copper area can be added on either side of the PCB to dissipate heat. If the copper area is on the opposite side of the PCB from the device, thermal vias are used to transfer the heat between top and bottom layers.

For details about how to design the PCB, refer to [PowerPAD™ Thermally Enhanced Package](#) (SLMA002) and [PowerPAD Made Easy™](#) (SLMA004), available at www.ti.com. In general, the more copper area that can be provided, the more power can be dissipated.

11 デバイスおよびドキュメントのサポート

11.1 ドキュメントのサポート

11.1.1 関連資料

関連資料については、以下を参照してください。

- 『電流再循環および減衰モード』
- 『モータ・ドライバの消費電力の計算』
- 『DRV8871評価モジュール』
- 『放熱特性の優れたPowerPAD™パッケージ』
- 『PowerPAD™の簡単な使用法』
- 『モータ・ドライバの電流定格について』

11.2 ドキュメントの更新通知を受け取る方法

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11.3 コミュニティ・リソース

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

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11.6 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

12 メカニカル、パッケージ、および注文情報

以降のページには、メカニカル、パッケージ、および注文に関する情報が記載されています。この情報は、そのデバイスについて利用可能な最新のデータです。このデータは予告なく変更されることがあり、ドキュメントが改訂される場合もあります。本データシートのブラウザ版を使用されている場合は、画面左側の説明をご覧ください。

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
DRV8871DDA	LIFEBUY	SO PowerPAD	DDA	8	75	RoHS & Green	NIPDAUAG	Level-2-260C-1 YEAR	-40 to 125	8871	
DRV8871DDAR	ACTIVE	SO PowerPAD	DDA	8	2500	RoHS & Green	NIPDAUAG	Level-2-260C-1 YEAR	-40 to 125	8871	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSELETE: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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OTHER QUALIFIED VERSIONS OF DRV8871 :

- Automotive : [DRV8871-Q1](#)

NOTE: Qualified Version Definitions:

- Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

TAPE AND REEL INFORMATION



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
DRV8871DDAR	SO Power PAD	DDA	8	2500	330.0	12.8	6.4	5.2	2.1	8.0	12.0	Q1

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
DRV8871DDAR	SO PowerPAD	DDA	8	2500	366.0	364.0	50.0

TUBE



*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (μm)	B (mm)
DRV8871DDA	DDA	HSOIC	8	75	517	7.87	635	4.25



Images above are just a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.

DDA (R-PDSO-G8)

PowerPAD™ PLASTIC SMALL-OUTLINE



- NOTES:
- All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5-1994.
 - This drawing is subject to change without notice.
 - Body dimensions do not include mold flash or protrusion not to exceed 0,15.
 - This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at www.ti.com <<http://www.ti.com>>.
 - See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.
 - This package complies to JEDEC MS-012 variation BA

PowerPAD is a trademark of Texas Instruments.

DDA (R-PDSO-G8)

PowerPAD™ PLASTIC SMALL OUTLINE

THERMAL INFORMATION

This PowerPAD™ package incorporates an exposed thermal pad that is designed to be attached to a printed circuit board (PCB). The thermal pad must be soldered directly to the PCB. After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For additional information on the PowerPAD package and how to take advantage of its heat dissipating abilities, refer to Technical Brief, PowerPAD Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 and Application Brief, PowerPAD Made Easy, Texas Instruments Literature No. SLMA004. Both documents are available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.



Exposed Thermal Pad Dimensions

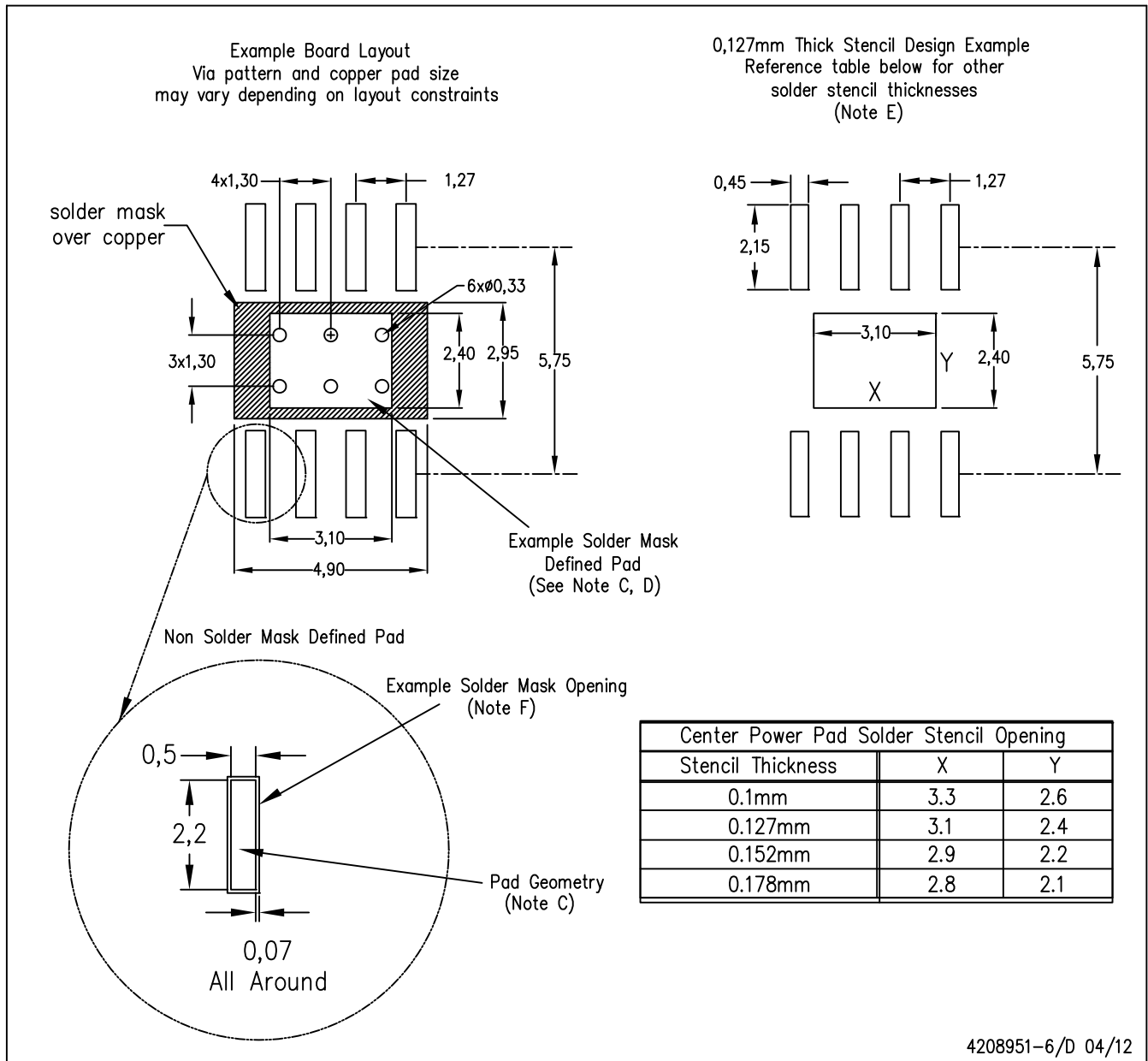
4206322-6/L 05/12

NOTE: A. All linear dimensions are in millimeters

PowerPAD is a trademark of Texas Instruments

DDA (R-PDSO-G8)

PowerPAD™ PLASTIC SMALL OUTLINE



- NOTES:
- All linear dimensions are in millimeters.
 - This drawing is subject to change without notice.
 - Publication IPC-7351 is recommended for alternate designs.
 - This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPAD Thermally Enhanced Package, Texas Instruments Literature No. SLMA002, SLMA004, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <<http://www.ti.com>>. Publication IPC-7351 is recommended for alternate designs.
 - Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.
 - Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.

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