

# TMAG5328 抵抗および電圧で調整可能、低消費電力、ホール・エフェクト・スイッチ

## 1 特長

- 電源電圧範囲: 1.65V~5.5V
- $B_{OP}$  を 2mT~15mT で調整可能
  - 2k $\Omega$ ~15k $\Omega$  の抵抗
  - または 160mV~1200mV の電圧源を使用
- オムニポーラのホール・スイッチ
- プッシュプル出力
- 低い消費電力
  - 20Hz のサンプリング・レート: 3.3V で 1.4 $\mu$ A
- 業界標準のパッケージとピン配置
  - SOT-23 パッケージ
- 40°C~125°Cの動作温度範囲

## 2 アプリケーション

- バッテリー駆動時間が重要な位置センシング
- 電気メーターの改ざん検出
- 携帯電話、ラップトップ、またはタブレットのケース・センシング
- 電子ロック、煙感知器、家電機器
- 医療機器、IoT システム
- バルブまたはソレノイドの位置検出
- 非接触式の診断または起動

## 3 概要

TMAG5328 デバイスは、高精度、低消費電力、抵抗で調整可能、低電圧で動作するホール・エフェクト・スイッチ・センサです。

外付け抵抗により、デバイスが動作する  $B_{OP}$  の値を設定します。簡単な式によって、適切な  $B_{OP}$  の値を設定するために必要な抵抗値を容易に計算できます。ヒステリシスの値は固定であるため、 $B_{RP}$  の値は  $B_{OP}$ -ヒステリシスとして定義されます。

この調整可能なスレッシュホールド機能により、TMAG5328 は、簡単で迅速なプロトタイピング、設計から市場投入までの期間短縮、異なるプラットフォーム間での再利用、予想外の変更に備えた直前の修正を可能にします。

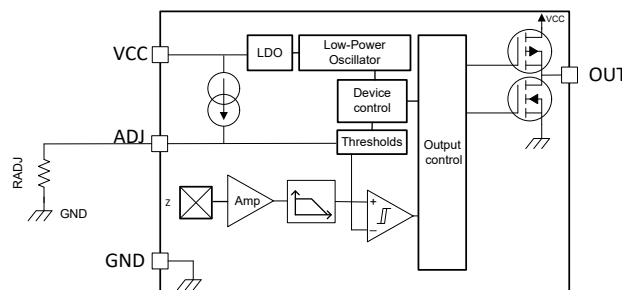
印加されている磁束密度が  $B_{OP}$  スレッシュホールドを超えると、デバイスは LOW 電圧を出力します。出力は、磁束密度が  $B_{RP}$  を下回るまで LOW のまま維持され、下回ると HIGH 電圧に駆動されます。このデバイスには発振器が内蔵されており、費電流を最小限に抑えるため、20Hz で磁界をサンプリングして出力を更新します。TMAG5328 は、オムニポーラ磁気応答を採用しています。

このデバイスは、1.65V~5.5V の  $V_{CC}$  範囲で動作し、標準の SOT-23-6 パッケージで供給されます。

### 製品情報

部品番号	パッケージ <sup>(1)</sup>	本体サイズ (公称)
TMAG5328	SOT-23 (6)	2.92mm × 1.30mm

(1) 利用可能なパッケージについては、このデータシートの末尾にある注文情報を参照してください。



代表的な回路図



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## 4 Revision History

Changes from Revision * (December 2021) to Revision A (June 2022)	Page
• データシートステータスを「事前情報」から「量産データ」に変更.....	<b>1</b>
• デバイスの FA および FD バージョンを追加.....	<b>1</b>

## 5 Pin Configuration and Functions

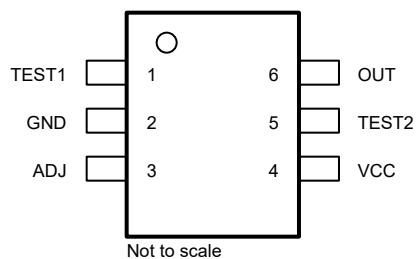


図 5-1. DBV Package 6-Pin SOT-23 Top View

表 5-1. Pin Functions

PIN		I/O	DESCRIPTION
NAME	SOT-23		
GND	2	—	Ground reference
OUT	6	O	Omnipolar output that responds to north and south magnetic poles
VCC	4	—	1.65-V to 5.5-V power supply. TI recommends connecting this pin to a ceramic capacitor to ground with a value of at least 0.1 $\mu$ F
ADJ	3	I	This pin is used to set the thresholds up. Can either be connected to a resistor or voltage source.
TEST1	1	—	TI recommends to leave this pin floating
TEST2	5	—	TI recommends connecting this pin to GND

## 6 Specifications

### 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
Power Supply Voltage	$V_{CC}$	-0.3	5.5	V
Pin Voltage	OUT, TEST1	-0.3	$V_{CC} + 0.3$	V
	TEST2	-0.3	0.3	
	ADJ	-0.3	5.5	
Pin current	OUT, TEST1	-5	5	mA
Magnetic Flux Density, BMAX		Unlimited		T
Junction temperature, $T_J$	Junction temperature, $T_J$		150	°C
Storage temperature, $T_{stg}$		-65	150	°C

- (1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

### 6.2 ESD Ratings

			VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins <sup>(1)</sup>	±2000	V
		Charged device model (CDM), per ANSI/ESDA/JEDEC JS-002, all pins <sup>(2)</sup>	± 500	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.  
 (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
$V_{CC}$	Power supply voltage	1.65	5.5	V
$V_{IO}$	Pin Voltage. OUT, TEST1	0	$V_{CC}$	V
	Pin Voltage. TEST2	0	0	
	Pin Voltage. ADJ	0	5	
$I_O$	Pin current. OUT, TEST1	-5	5	mA
$T_A$	Ambient temperature	-40	125	°C

## 6.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		TMAG5328	UNIT
		SOT-23 (DBV)	
		6 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	167.6	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	84.1	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	52.2	°C/W
$\Psi_{JT}$	Junction-to-top characterization parameter	32	°C/W
$\Psi_{JB}$	Junction-to-board characterization parameter	51.9	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	–	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

## 6.5 Electrical Characteristics

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
ADJ pin						
ADJ_ICC	Current output source			80		μA
ADJ_C	Maximum external capacitance				50	pF
PUSH-PULL OUTPUT DRIVER						
V <sub>OH</sub>	High-level output voltage	I <sub>OUT</sub> = −0.5 mA	V <sub>CC</sub> − 0.35		V <sub>CC</sub> − 0.1	V
V <sub>OL</sub>	Low-level output voltage	I <sub>OUT</sub> = 0.5 mA		0.1	0.3	V
TMAG5328A1D						
f <sub>s</sub>	Frequency of magnetic sampling			20		Hz
t <sub>s</sub>	Period of magnetic sampling			50		ms
I <sub>CC(AVG)</sub>	Average current consumption	V <sub>CC</sub> = 3.3 V T <sub>A</sub> = 25°C		1.4	1.6	μA
		V <sub>CC</sub> = 1.65 V to 5.5 V			2.3	
ALL VERSIONS						
I <sub>CC(PK)</sub>	Peak current consumption			1.8	3	mA
I <sub>CC(SLP)</sub>	Sleep current consumption			300	600	nA
t <sub>ON</sub>	Power-on time			125		μs
P <sub>OS</sub>	Power-on state without external magnetic field	V <sub>CC</sub> > V <sub>CCMIN</sub>		High		
t <sub>ACTIVE</sub>	Active time period			65		μs

## 6.6 Magnetic Characteristics

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>TMAG5328A1D</b>						
$B_{OP(Range\ A)}$	Adjustable Operate Point		$\pm 2$		$\pm 15$	mT
$B_{RP(Range\ A)}$	Adjustable Release Point		$\pm 1$		$\pm 14$	mT
$V_{ADJ\ (Range\ A)}$	Voltage range		160		1200	mV
$R_{ADJ\ (Range\ A)}$	Resistor range		2		15	kOhm
$B_{OP}(R_{ADJ})$	$B_{OP}/R$			$\pm 1$		mT/ kOhm
$B_{OP\_ACC}(R_{ADJ})$	$B_{OP}$ Accuracy $B_{OPSET} \pm B_{OP(MAX/MIN)}/B_{OPSET}$	$2\text{ mT} \leq B_{OPSET} < 6\text{ mT}$	-0.85		0.85	mT
		$6\text{ mT} \leq B_{OPSET} \leq 15\text{ mT}$	-1.75		1.75	
$B_{RP\_ACC}(R_{ADJ})$	$B_{RP}$ Accuracy $B_{RPSET} \pm B_{RP(MAX/MIN)}$	$2\text{ mT} \leq B_{OPSET} < 6\text{ mT}$	-1		1	
		$6\text{ mT} \leq B_{OPSET} \leq 15\text{ mT}$	-2.1		2.1	
$B_{HYSA}(R_{ADJ})$	Magnetic hysteresis	$ B_{OP} - B_{RP} $	0.25	1	1.6	

## 6.7 Typical Characteristics

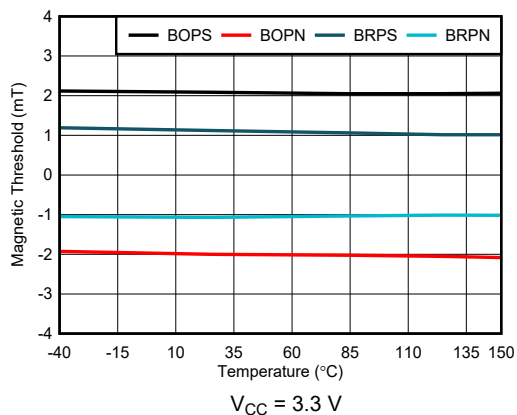


Figure 6-1. 2-mT Magnetic Threshold vs Temperature

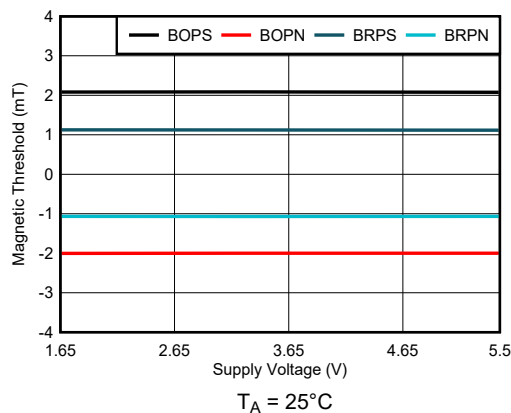


Figure 6-2. 2-mT Magnetic Threshold vs Supply

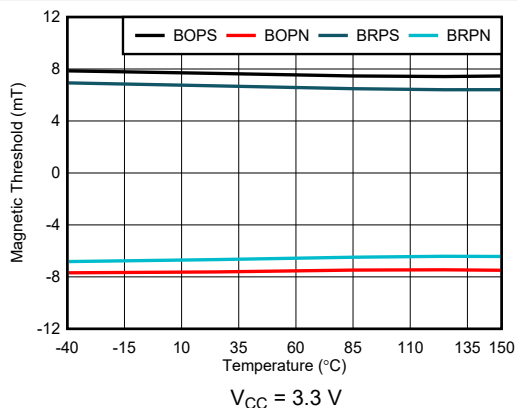


Figure 6-3. 7.5-mT Magnetic Threshold vs Temperature

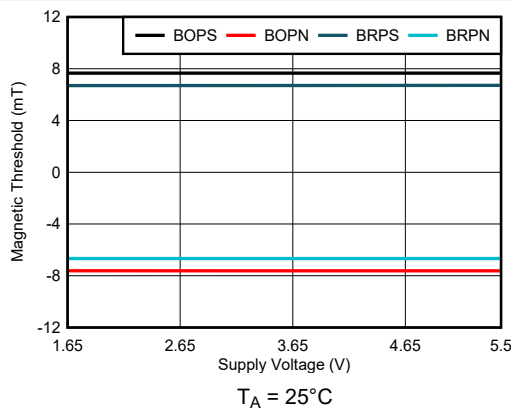


Figure 6-4. 7.5-mT Magnetic Threshold vs Supply

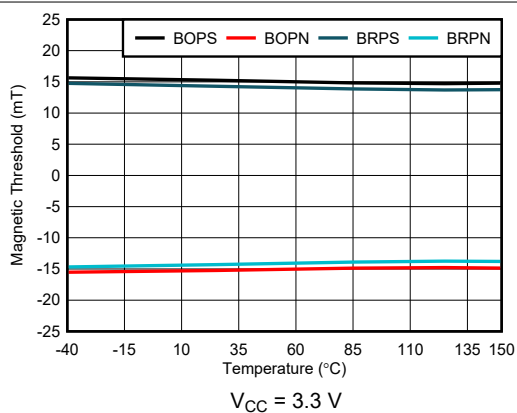


Figure 6-5. 15-mT Magnetic Threshold vs Temperature

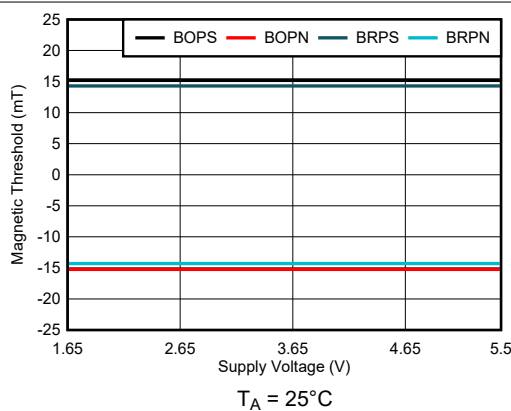
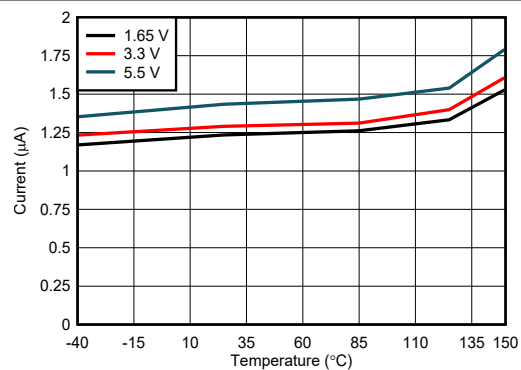


Figure 6-6. 15-mT Magnetic Threshold vs Supply



Sampling Rate = 20 Hz

图 6-7. Average  $I_{CC}$  vs Temperature



## 7 Detailed Description

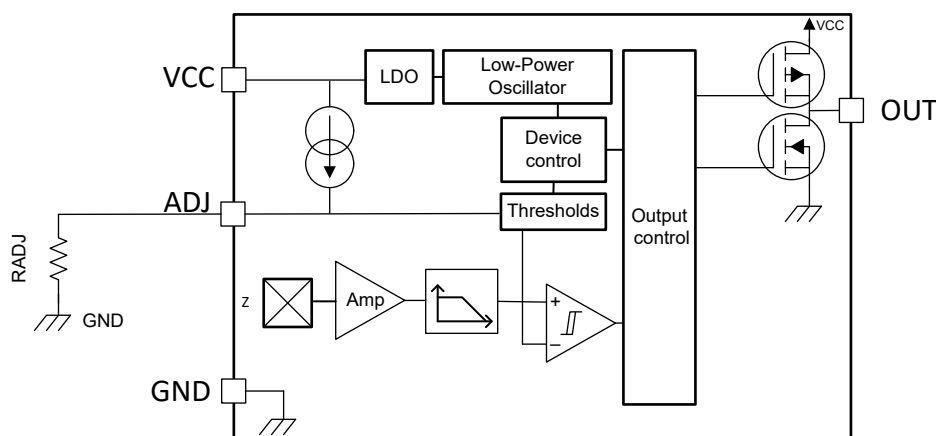
### 7.1 Overview

The TMAG5328 device is a magnetic sensor with a digital output that indicates when the magnetic flux density threshold has been crossed. The device integrates a Hall effect element, analog signal conditioning, and a low-frequency oscillator that enables ultra-low average power consumption.

While most of the Hall effect sensor have fixed threshold, the TMAG5328 offers an extra pin that allows the user to set up a specific threshold of operation. This pin can either be connected to a resistor or a voltage source. While the value can be set at production, it is also possible to allow dynamic change of either the resistor value or the voltage value to dynamically change the threshold value.

Operating from a 1.65-V to 5.5-V supply, the device periodically measures magnetic flux density, updates the output, and enters into a low-power sleep state.

### 7.2 Functional Block Diagram



## 7.3 Feature Description

### 7.3.1 Magnetic Flux Direction

Magnetic flux that travels from the bottom to the top of the package is considered positive in this data sheet. This condition exists when a south magnetic pole is near the top of the package. Magnetic flux that travels from the top to the bottom of the package results in negative millitesla values.

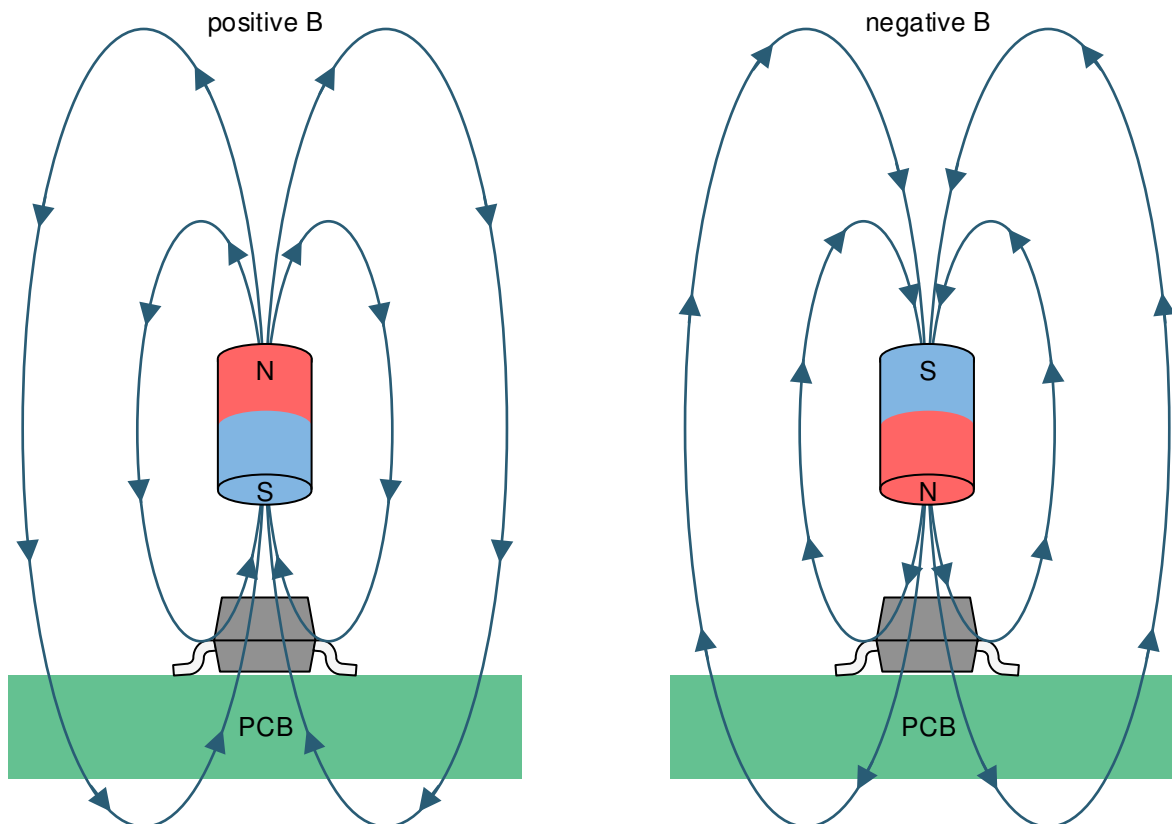


図 7-1. Flux Direction Polarity

### 7.3.2 Magnetic Response

The TMAG5328A1D has omnipolar functionality, so the device responds to both positive and negative magnetic flux densities, as shown in 図 7-2.

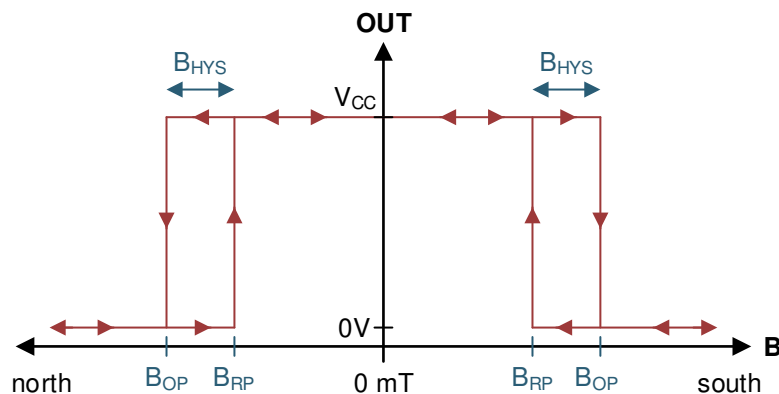


図 7-2. Omnipolar Functionality

### 7.3.3 Output Type

The TMAG5328A1D also has a push-pull CMOS output.

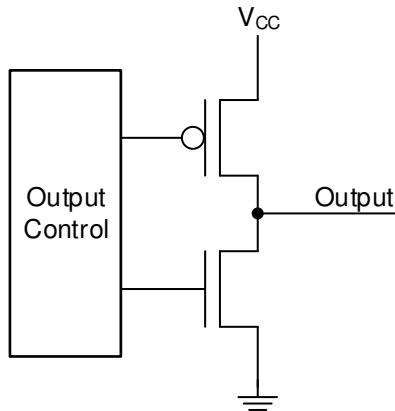


図 7-3. Push-Pull Output (Simplified)

### 7.3.4 Sampling Rate

When the TMAG5328 device powers up, the device measures the first magnetic sample and sets the output within the  $t_{ON}$  time. The output is latched, and the device enters an ultra-low-power sleep state. After each  $t_{Active}$  time has passed, the device measures a new sample and updates the output if necessary. If the magnetic field does not change between periods, the output also does not change.

While in active mode, the part will go through different steps. The content of the OTP (One-Time-Programmable Memory) is loaded first, and this steps takes about 35  $\mu$ s and consumes around 350  $\mu$ A. For the next 5  $\mu$ s, the current source will be started and settled. The part now consumes around 650  $\mu$ A in this step. Finally, the part conducts the Hall sensor conversion for about 25  $\mu$ s and consumes the peak current of around 2 mA.

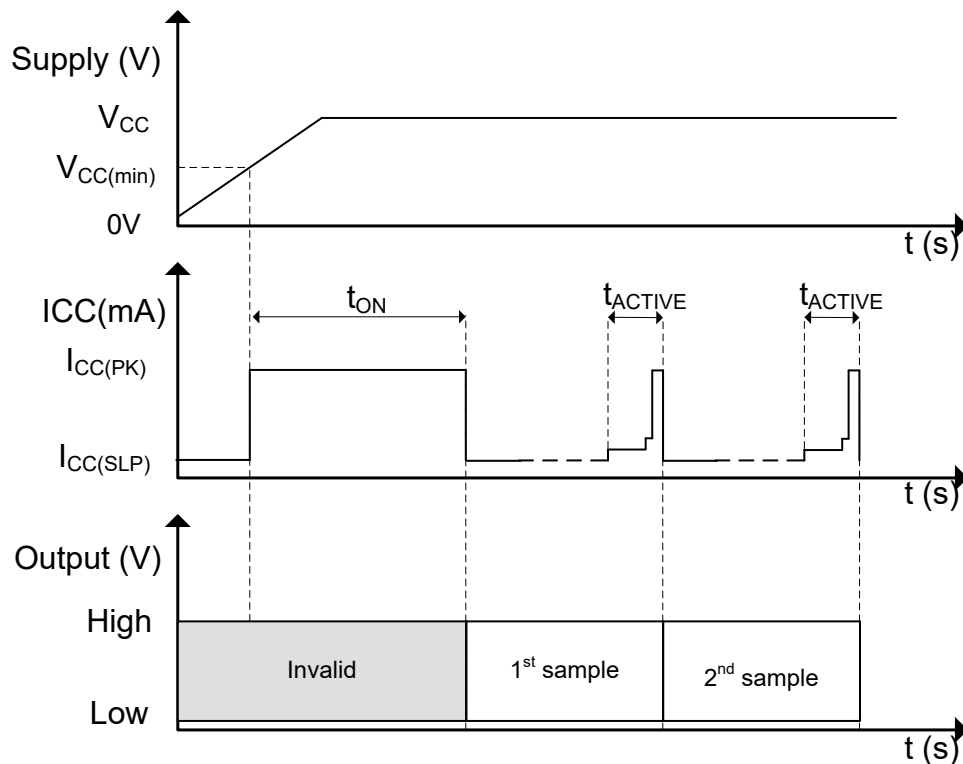


図 7-4. Timing Diagram

### 7.3.5 Adjustable Threshold

While most Hall Effect switch sensors have fixed magnetic characteristics, the TMAG5328 offers a wide range of adjustable thresholds. The user can use the "ADJ" pin to set the value of  $B_{OP}$  threshold. This pin can be used in two different ways. A resistor or a voltage source can be applied on "ADJ". In both scenarios, the resistor or voltage value will define the position of the  $B_{OP}$ . While the  $B_{OP}$  can be adjusted, the hysteresis has a fixed value.  $B_{RP}$  is therefore defined as  $B_{OP}$ -Hysteresis.

An 80- $\mu$ A current is generated on pin "ADJ" when the part goes into active mode. The device then reads the "ADJ" pin and defines the value of  $B_{OP}$ . The TMAG5328 supports adjusting the  $B_{OP}$  dynamically. If the "ADJ" pin value is adjusted while the sensor is in sleep mode, the  $B_{OP}$  will update at the next active period of the device. Consequently, the maximum time it could take for the  $B_{OP}$  to update is equal to the period of magnetic sampling,  $t_s$ .

#### 7.3.5.1 Adjustable Resistor

One way to setup the  $B_{OP}$  is to connect a resistor to the "ADJ" pin. The device generates a fixed current that is injected in the external resistor. This will generate a voltage that represents the  $B_{OP}$  value. The relationship between  $B_{OP}$  and resistance is defined as  $B_{OP}(mT) = R_{ADJ}(k\Omega)$ . Please note that the generated current on the "ADJ" pin is only present when the device is in active mode and it is turned OFF when in sleep mode. As a result, the voltage on the "ADJ" pin is only present when the device is in active mode, which is a small duration compared to the time the device is in sleep mode.

The device  $B_{OP}$  must be set to any value between 2 mT and 15 mT. This means  $R_{ADJ}$  must be set between 2 k $\Omega$  and 15 k $\Omega$ . Operating above and beyond those limits is not recommended and could result in either getting the wrong threshold set or locking up the device into a specific state without the possibility of exiting.

Figure 7-5 shows the relationship between  $B_{OP}$  and  $R_{ADJ}$ .

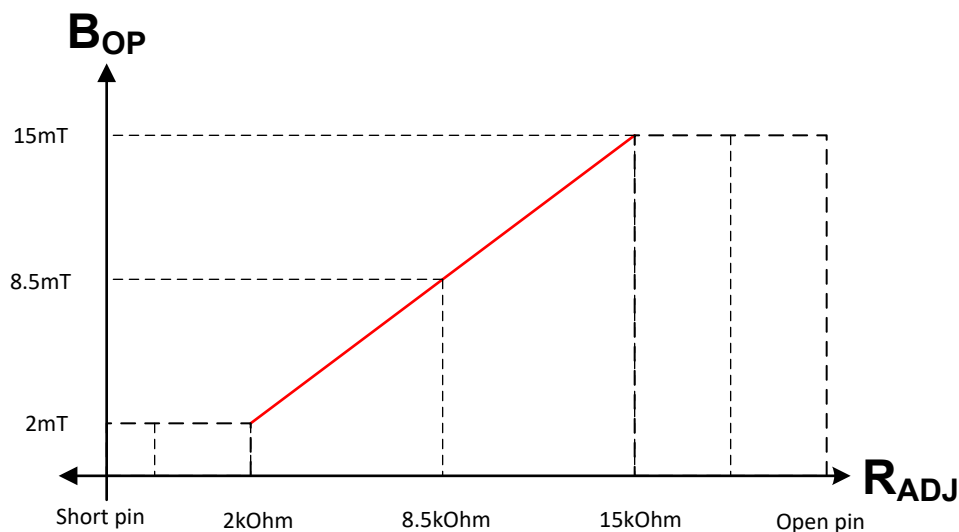


Figure 7-5.  $B_{OP}$  vs  $R_{ADJ}$

### 7.3.5.2 Adjustable Voltage

One other way to setup the  $B_{OP}$  is to apply a voltage to the "ADJ" pin. This voltage is directly proportional to the  $B_{OP}$  value. The relationship between  $B_{OP}$  and voltage is defined as  $B_{OP}(mT) = V_{ADJ}(mV) \times 0.0125$ . To apply a voltage on the "ADJ" pin, the voltage source must be able to settle within 4  $\mu s$  after being exposed to a 80  $\mu A$  current on the ADJ pin.

The device  $B_{OP}$  must be set to any value between 2 mT and 15 mT. This means  $V_{ADJ}$  must be set between 160 mV and 1200 mV. Operating above and beyond those limits is not recommended and could result in either getting the wrong threshold set or locking up the device into a specific state without the possibility of exiting.

Figure 7-6 shows the relationship between  $B_{OP}$  and  $V_{ADJ}$ .

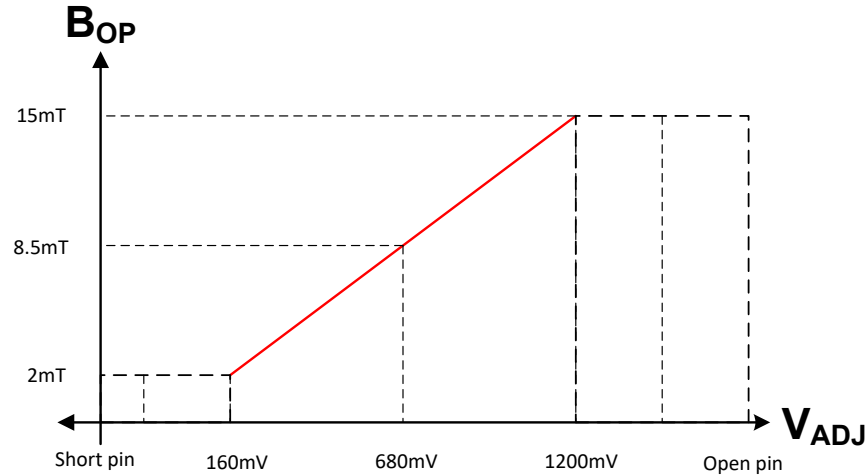


Figure 7-6.  $B_{OP}$  vs  $R_{ADJ}$

### 7.3.6 Hall Element Location

Figure 7-7 shows the sensing element location inside the device.

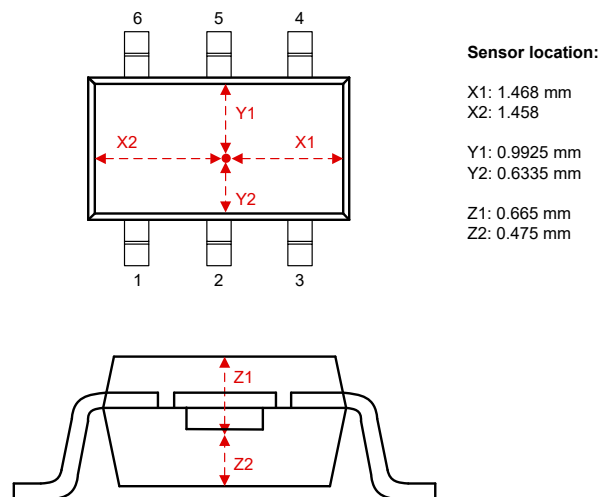


Figure 7-7. Hall Element Location

## 7.4 Device Functional Modes

The TMAG5328 device has one mode of operation that applies when the [Recommended Operating Conditions](#) are met.

## 8 Application and Implementation

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### 注

以下のアプリケーション情報は、TI の製品仕様に含まれるものではなく、TI ではその正確性または完全性を保証いたしません。個々の目的に対する製品の適合性については、お客様の責任で判断していただくことになります。お客様は自身の設計実装を検証しテストすることで、システムの機能を確認する必要があります。

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### 8.1 Application Information

The TMAG5328 device is typically used to detect the proximity of a magnet. The magnet is often attached to a movable component in the system.

#### 8.1.1 Output Type Tradeoffs

The push-pull output allows for the lowest system power consumption, because there is no current leakage path when the output drives high or low. The open-drain output involves a leakage path when the output drives low, through the external pullup resistor.

The open-drain outputs of multiple devices can be tied together to form a logical AND. In this setup, if any sensor drives low, the voltage on the shared node becomes low. This can allow a single GPIO to measure an array of sensors.

### 8.1.2 Valid TMAG5328 Configurations

The TMAG5328  $B_{OP}$  is set by connecting a resistor or a voltage source to the “ADJ” pin. 図 8-1 shows how to use resistor R1 to set the  $B_{OP}$ . 図 8-2 shows how to use a DAC as a voltage source for setting the  $B_{OP}$ . Using the DAC allows the user to dynamically change the  $B_{OP}$  with software. To use a DAC, the output of the DAC must settle within 4  $\mu$ s after the 80- $\mu$ A current source of the “ADJ” pin is turned ON.

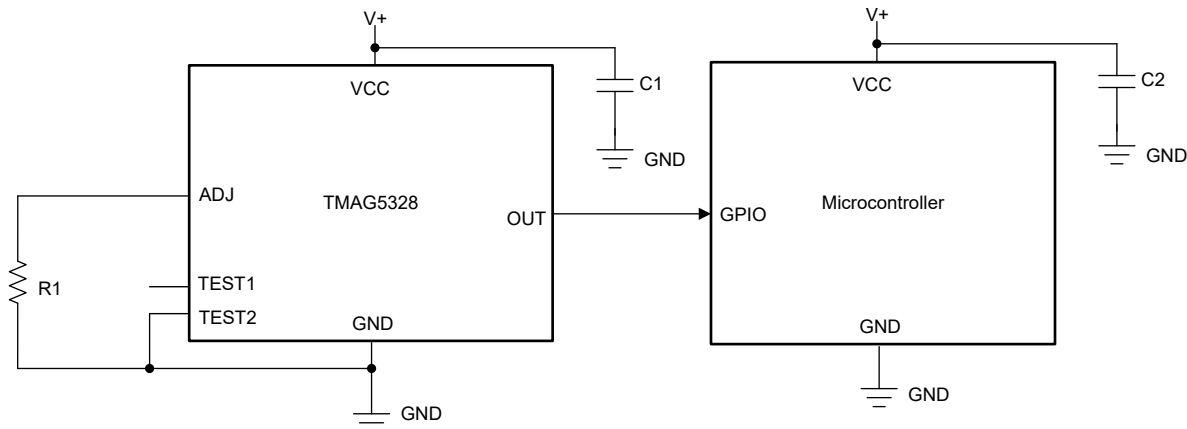


図 8-1. Setting  $B_{OP}$  of One TMAG5328 Device Using a Resistor

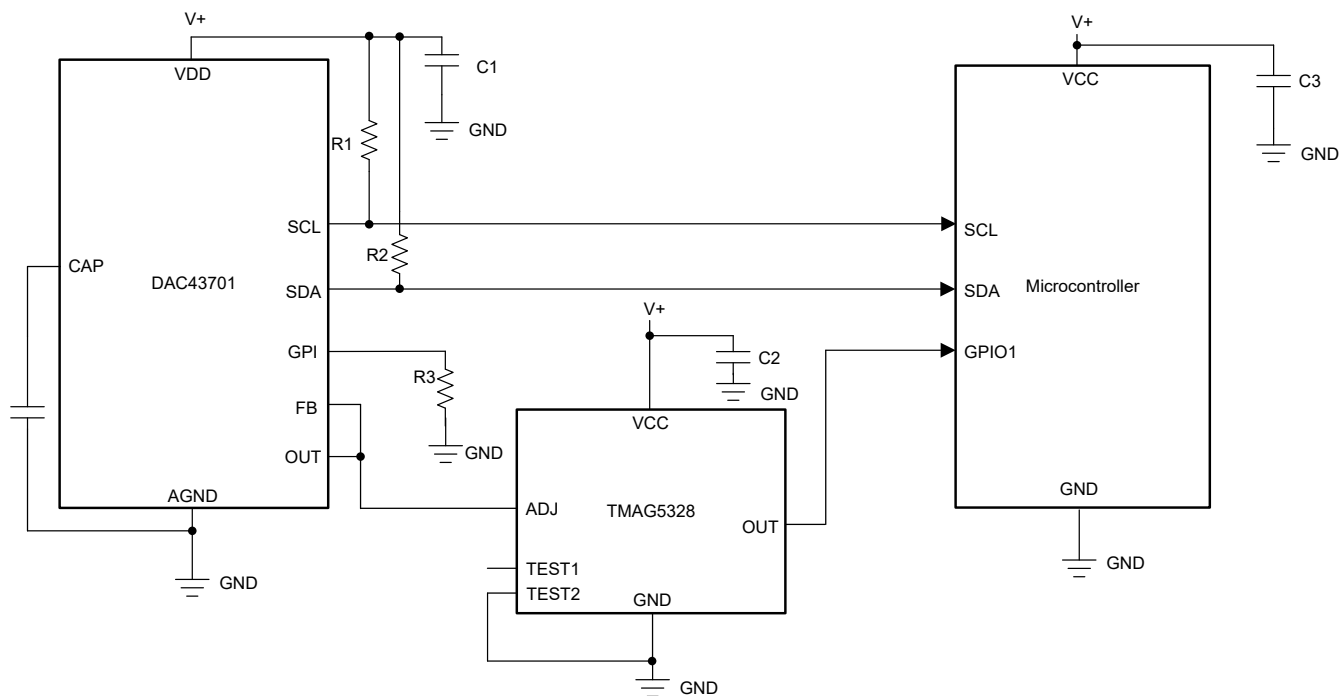
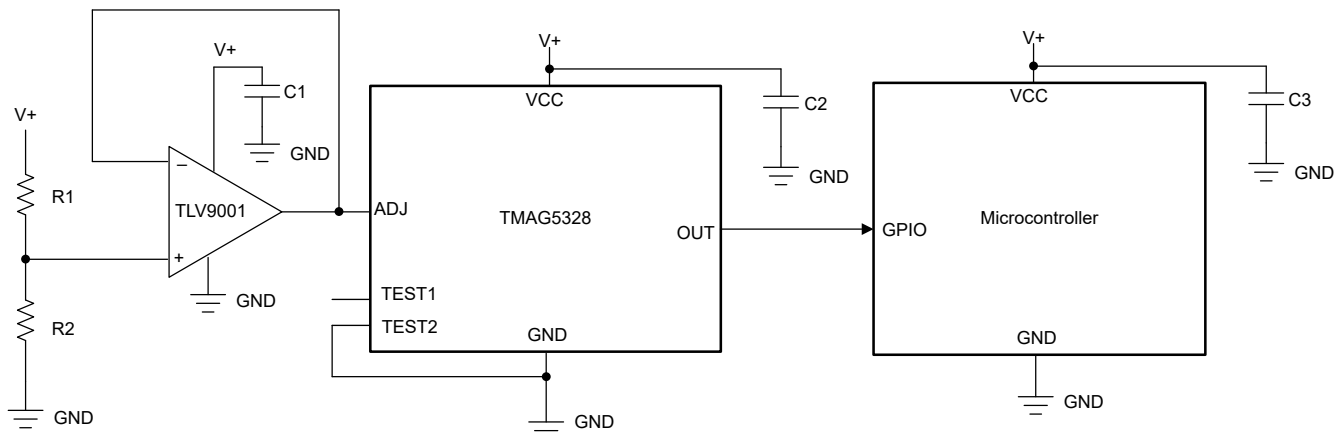


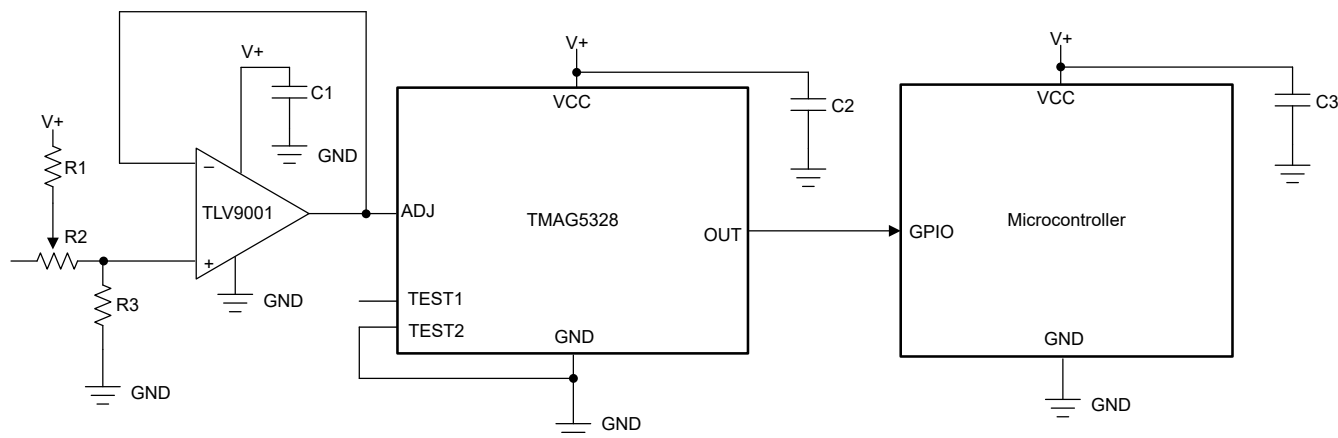
図 8-2. Setting  $B_{OP}$  of One TMAG5328 Device Using a DAC

As a DAC alternative, [Figure 8-3](#) shows how a voltage divider may be used as a voltage source. In [Figure 8-3](#), an operational amplifier is placed between the voltage divider and the “ADJ” pin so that the voltage fed to the “ADJ” pin is not impacted by the internal current source of the TMAG5328 when the current source is turned ON. To use an op amp, the output of the op amp must settle within 4  $\mu$ s after the 80- $\mu$ A current source of the “ADJ” pin is turned ON.



**Figure 8-3. Setting  $B_{OP}$  of One TMAG5328 Device Using a Voltage Divider**

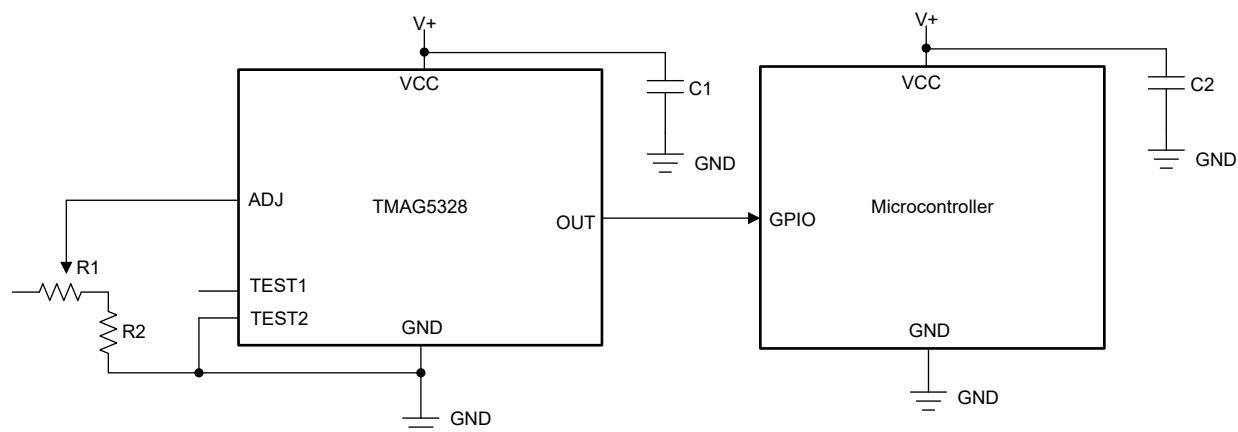
A potentiometer or rheostat may be integrated into a voltage divider, and the user can adjust this potentiometer to dynamically update the  $B_{OP}$ . [Figure 8-4](#) shows how to use a potentiometer in a voltage divider to set the  $B_{OP}$  of the TMAG5328. The maximum output voltage, which determines the maximum  $B_{OP}$ , is set based on the values of resistors R1 and R3. The minimum output voltage, which determines the minimum  $B_{OP}$ , is set based on the values of the maximum potentiometer resistance, R1's resistance, and R3's resistance. The user should select a minimum output voltage greater than 0.16 V and a maximum output voltage less than 1.2 V.



**Figure 8-4. Setting  $B_{OP}$  of One TMAG5328 Device Using a Voltage Divider and Potentiometer**

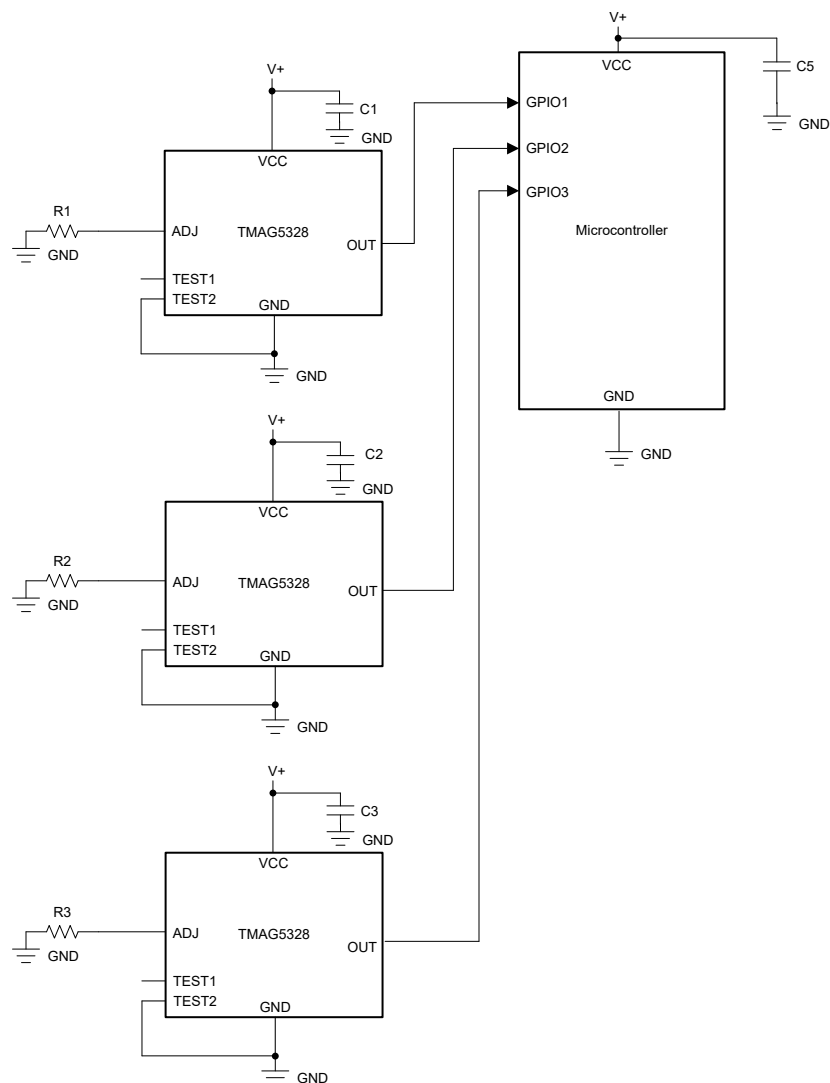


8-5 shows how the TMAG5328's internal current source can drive a potentiometer or rheostat instead of a voltage divider. In this implementation, resistor R2 should be at least 2 k $\Omega$  to ensure that the "ADJ" resistance is always above its minimum 2 k $\Omega$ . The sum of the maximum potentiometer resistance and the resistance of R1 must also be less than 15 k $\Omega$ .



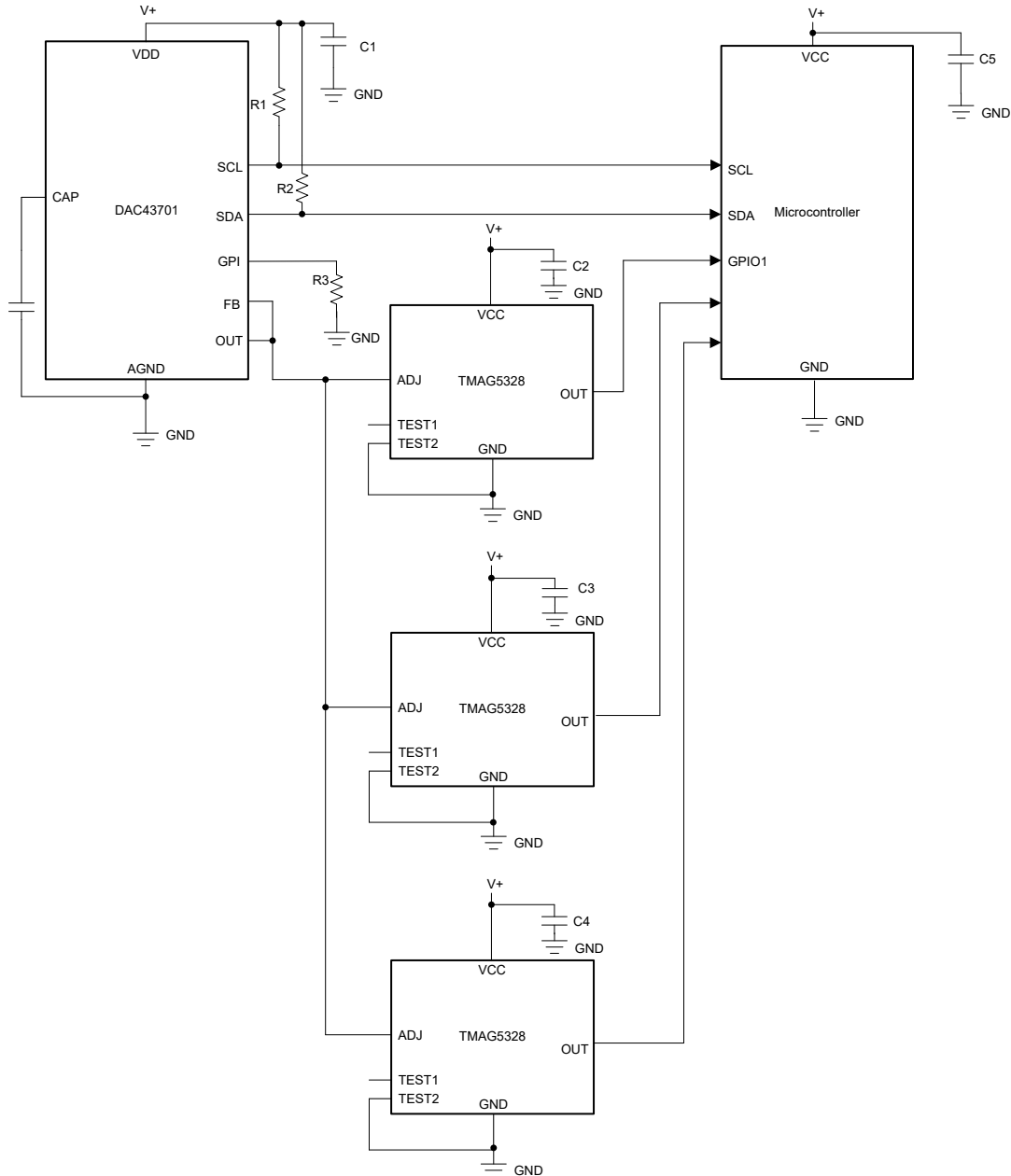
**8-5. Setting  $B_{OP}$  of One TMAG5328 Device Using a Potentiometer and the TMAG5328's Internal Current Source**

Multiple TMAG5328 devices may be used in the same system. When setting the  $B_{OP}$  using a resistor, TI recommends that each TMAG5328 has its own “ADJ” resistor, even if multiple TMAG5328 devices have the same “ADJ” resistor value. [図 8-6](#) shows an example implementation that has three TMAG5328 devices. If each device is set to the same  $B_{OP}$ , then the resistances of R1, R2, and R3 are equal.



**図 8-6. Setting  $B_{OP}$  of Three TMAG5328 Devices Using Three Resistors**

When setting the  $B_{OP}$  using a DAC, one DAC can be used to set the “ADJ” pin voltage of multiple devices only if the DAC’s output could sink the current from all of the TMAG5328 devices. [Figure 8-7](#) shows an example of a DAC driving the “ADJ” pin of three TMAG5328 devices. A DAC can only work reliably in this specific scenario if the DAC’s output can settle within 4  $\mu s$  after being exposed to the three “ADJ” current sources. Each current source is 80  $\mu A$ , therefore the DAC can only reliably work if the DAC’s output can settle within 4  $\mu s$  after being exposed to  $80 \times 3 = 240 \mu A$  of current.



**Figure 8-7. Setting  $B_{OP}$  of Three TMAG5328 Devices Using a DAC**

## 8.2 Typical Applications

The TMAG5328 can be used in a large variety of industrial applications. For almost all these applications, the sensor is fixed and the magnet is attached to a movable component in the system.

### 8.2.1 Refrigerator Door Open/Close Detection

This application section describes how to use the same device for two identical applications with different mechanical characteristic.

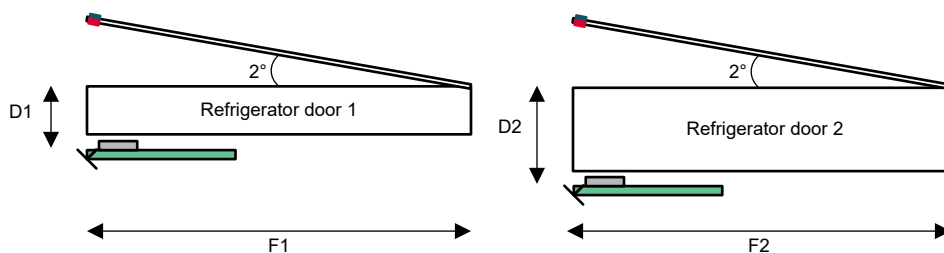


図 8-8. Refrigerator 1 and Refrigerator 2 Principal Diagram

#### 8.2.1.1 Design Requirements

For this design example, use the parameters listed in 表 8-1.

表 8-1. Design Parameters for Fridge 1

DESIGN PARAMETER	EXAMPLE VALUE
Hall effect device	TMAG5328A1D
$V_{CC}$	5 V
Magnet	10 mm cubic N35
D1	7.025 mm
F1	500 mm
Door opening angle	2°
Calculated threshold needed ( $B_{OP}$ )	7.87 mT
$R_{ADJ}$	7.87 kΩ

表 8-2. Design Parameters for Fridge 2

DESIGN PARAMETER	EXAMPLE VALUE
Hall effect device	TMAG5328A1D
$V_{CC}$	5 V
Magnet	10 mm cubic N35
D2	16.08 mm
F2	500 mm
Door opening angle	2°
Calculated threshold needed ( $B_{OP}$ )	3.49 mT
$R_{ADJ}$	3.48 kΩ

#### 8.2.1.2 Detailed Design Procedure

For both applications, the Hall sensor is used to detect if the refrigerator door is open or closed. Both refrigerator doors are different from each other and therefore have different mechanical design. This means the Hall sensor and the magnet are positioned differently from each other. In other terms, if the user wants to detect a specific distance for both refrigerator doors, they must use either a different magnet or a different sensor. For the purpose of this application, there is no flexibility in the choice of magnet. The electronic board will also be reused across platforms and therefore will use the same sensor.

The TMAG5328 is a resistor adjustable Hall effect switch that allows the user to set up whatever threshold is needed between 2 mT and 15 mT.

For this application, the refrigerator door manufacturer can use the same printed circuit board (PCB) with the same semiconductor content and only has to change the resistor value depending on which refrigerator version is manufactured.

For both refrigerator doors, the opening angle is the same. Now refrigerator door 1 is a thinner model than refrigerator door 2. This means the PCB is located further away for refrigerator door 2 and therefore the sensitivity required to detect the position of the door will be impacted.

Knowing the door dimensions, the door opening angle required, and the distance from the magnet to the PCB, it is possible to use a simulation tool that will calculate the magnet strength at the desired position. For refrigerator door 1, the sensitivity calculated is 7.87 mT at a distance of 7.025 mm. For Refrigerator 2, the sensitivity is 3.49 mT at a distance of 16.08 mm. Based on those values, a resistor value can be selected from the E48 series. A resistor of 7.87 kΩ can be used for refrigerator door 1 and resistor of 3.48 kΩ can be used for refrigerator door 2.

## 9 Power Supply Recommendations

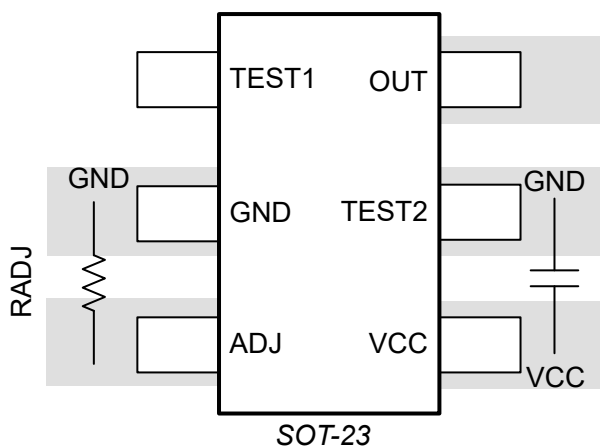
The TMAG5328 device is powered from 1.65-V to 5.5-V DC power supplies. A decoupling capacitor close to the device must be used to provide local energy with minimal inductance. TI recommends using a ceramic capacitor with a value of at least 0.1 μF.

## 10 Layout

### 10.1 Layout Guidelines

Magnetic fields pass through most non-ferromagnetic materials with no significant disturbance. Embedding Hall effect sensors within plastic or aluminum enclosures and sensing magnets on the outside is common practice. Magnetic fields also easily pass through most printed circuit boards, which makes placing the magnet on the opposite side possible.

### 10.2 Layout Examples



10-1. Layout Examples

## 11 Device and Documentation Support

### 11.1 ドキュメントの更新通知を受け取る方法

ドキュメントの更新についての通知を受け取るには、[ti.com](https://ti.com) のデバイス製品フォルダを開いてください。「更新の通知を受け取る」をクリックして登録すると、変更されたすべての製品情報に関するダイジェストを毎週受け取れます。変更の詳細については、修正されたドキュメントに含まれている改訂履歴をご覧ください。

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### 11.5 用語集

[テキサス・インスツルメンツ用語集](#)

この用語集には、用語や略語の一覧および定義が記載されています。

## 12 メカニカル、パッケージ、および注文情報

以下のページには、メカニカル、パッケージ、および注文に関する情報が記載されています。この情報は、指定のデバイスに対して提供されている最新のデータです。このデータは予告なく変更されることがあり、ドキュメントが改訂される場合もあります。本データシートのブラウザ版については、左側のナビゲーションをご覧ください。

## PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
TMAG5328A1DQDBVR	ACTIVE	SOT-23	DBV	6	3000	RoHS & Green	SN	Level-1-260C-UNLIM	-40 to 125	A1D	<a href="#">Samples</a>

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSELETE:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

## TAPE AND REEL INFORMATION



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TMAG5328A1DQDBVR	SOT-23	DBV	6	3000	178.0	9.0	3.3	3.2	1.4	4.0	8.0	Q3



## TAPE AND REEL BOX DIMENSIONS

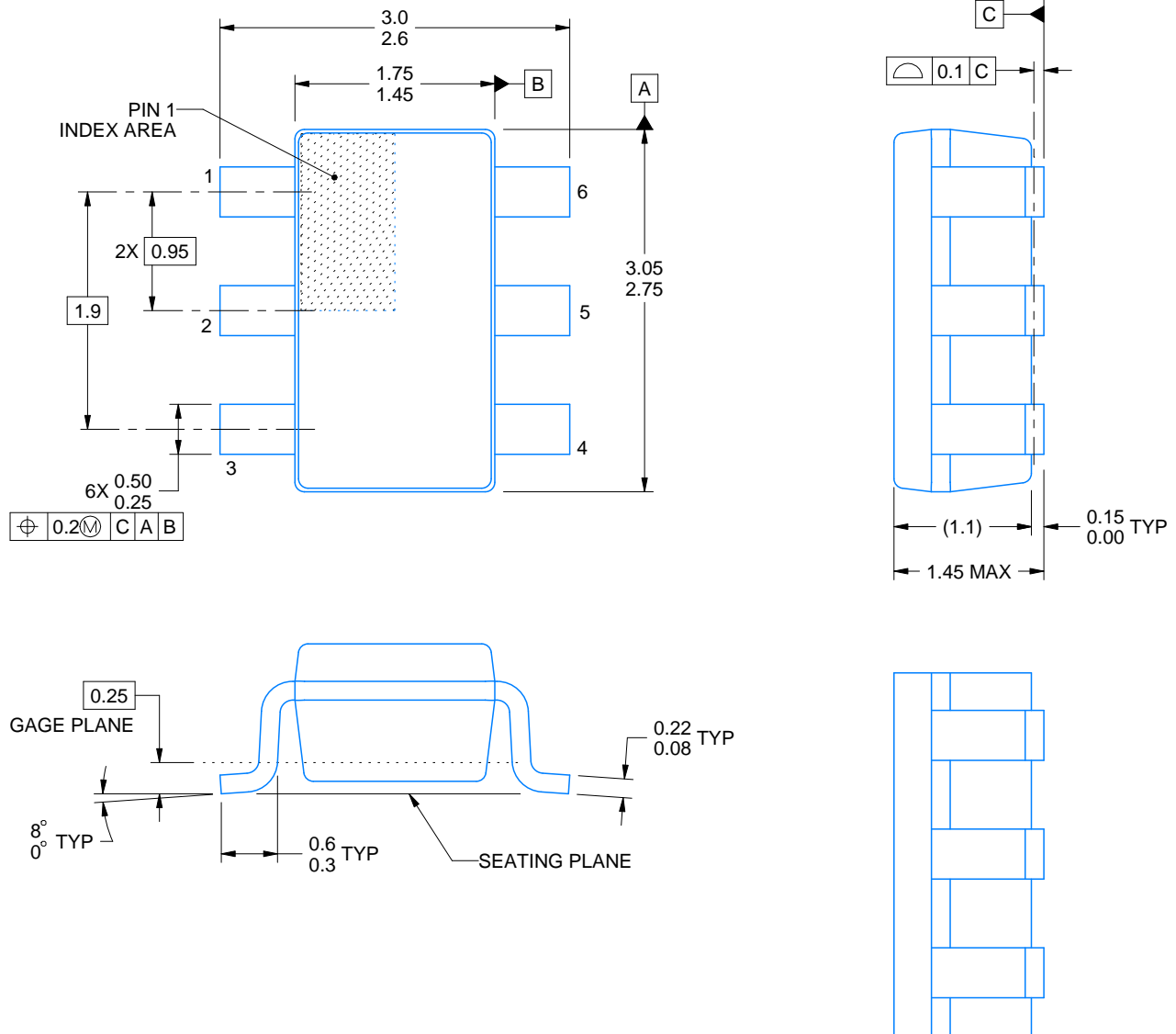


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TMAG5328A1DQDBVR	SOT-23	DBV	6	3000	190.0	190.0	30.0

**DBV0006A****PACKAGE OUTLINE****SOT-23 - 1.45 mm max height**

SMALL OUTLINE TRANSISTOR



ALTERNATIVE PACKAGE SINGULATION VIEW

4214840/E 02/2024

**NOTES:**

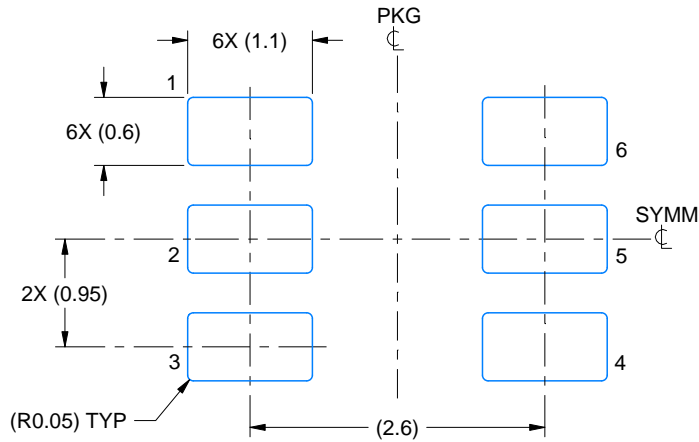
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. Body dimensions do not include mold flash or protrusion. Mold flash and protrusion shall not exceed 0.25 per side.
4. Leads 1,2,3 may be wider than leads 4,5,6 for package orientation.
5. Reference JEDEC MO-178.

# EXAMPLE BOARD LAYOUT

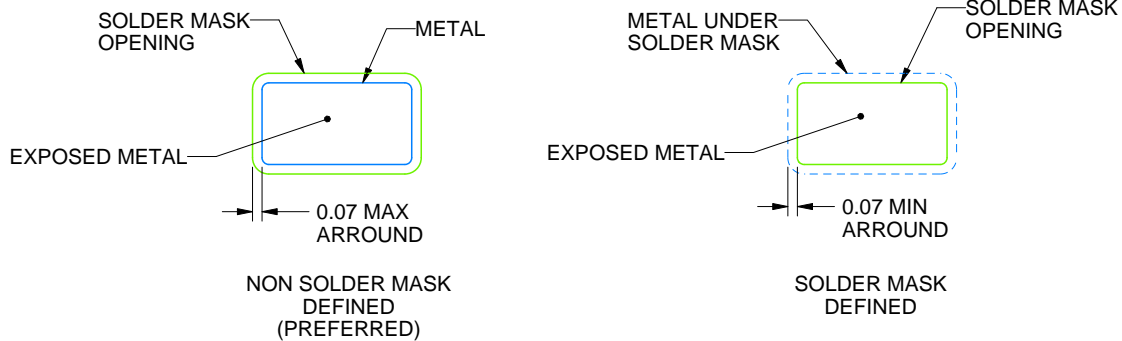
DBV0006A

SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:15X



SOLDER MASK DETAILS

4214840/E 02/2024

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

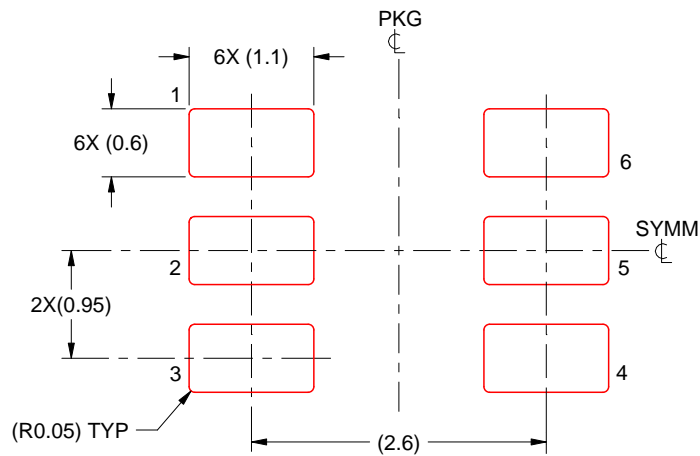
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

## EXAMPLE STENCIL DESIGN

DBV0006A

SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



SOLDER PASTE EXAMPLE  
BASED ON 0.125 mm THICK STENCIL  
SCALE:15X

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NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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