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A previous [blog addresses the highway addressable remote transducer \(HART\) protocol](#) and its place in sensor transmitter designs. To recap, simple transmitter designs traditionally communicate an analog value, typically referred to as the process variable (PV), through a current loop. This PV is generally tied to a sensor value (humidity, temperature, pH, pressure) that is represented by a 4-to-20mA analog signal. The analog value can traverse kilometers of wire in reaching the analog front-end circuitry, which records the potential drop across a shunt resistor in interpreting the transmitted sensor value.

Now, this is great if you want to communicate one value over lengthy cabling. But what do you do if you want to send or receive additional data over the same two wires? By putting HART into your transmitter design.

By including a HART modem, your transmitter design can now communicate extensive calibration routines, send diagnostic data or communicate PVs from other included sensor platforms. This communication is possible through the HART frequency shift-keying (FSK) waveform, which couples onto the analog current signal.

Before diving into the nitty-gritty of two-wire HART transmitter design, take this crash course (or refresher) on a [simple two-wire transmitter design](#). Did you finish the review? Awesome! You're halfway there.

Let's start off with the circuit shown in [Figure 1](#).

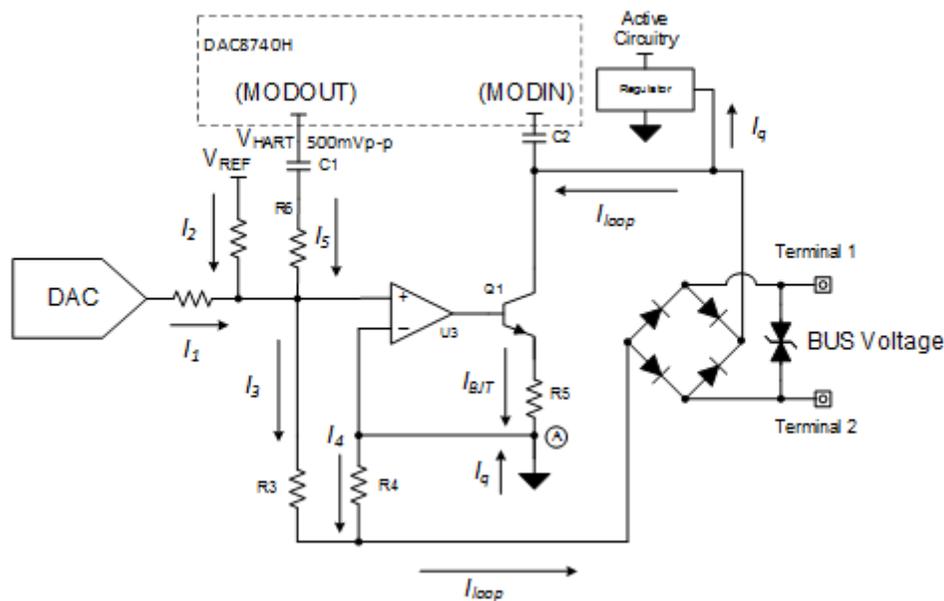


Figure 1. Two-wire Transmitter with HART Modem

I know that the circuit may look a little daunting, but the only difference between this circuit and the one shown in the simple two-wire transmitter design blog post is the inclusion of the DAC8740H HART modem. The low quiescent current of the DAC8740H HART modem, 180µA, makes the modem an excellent candidate for low-power sensor transmitter solutions. Using the methods shown in the crash course will determine a gain of $(1 + R3/R4)$ for the loop current.

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