MSP430FR263x、MSP430FR253x 静電容量式タッチ・センシング・ミクスト・シグナル・マイクロコントローラ

1 デバイスの概要

1.1 特長

- CapTIvate™ テクノロジ – 静電容量式タッチ
  - 性能
    - 4 つの同時スキャンによる高速な電極スキャン
    - 最大 1024 ポイントの高分解能スライダをサポート
    - 近接センシング
  - 信頼性
    - 電源ライン、RF、その他環境ノイズへの耐性の強化
    - スペクトラム拡散、自動チューニング、ノイズ・フィルタリング、デバウンシング・アルゴリズムを内蔵
    - 10V RMS の同相ノイズ、4kV の電気的高速過渡、15kV の静電放電により、IEC-61000-4-6、IEC-61000-4-4、IEC-61000-4-2 に準拠した信頼性の高いタッチ・ソリューションを実現
    - RF 放射の低減により電気的設計が簡素化
    - 金属タッチおよび耐水性設計をサポート
  - 柔軟性
    - 最大 16 の自己容量および 64 の相互容量電極
    - 同じ設計内に自己容量と相互容量の電極を混在可能
    - マルチタッチ機能をサポート
    - 広い範囲の容量検出、広い電極範囲：0～300pF
  - 低消費電力
    - 4 つのセンサにより、消費電流 5µA 未満のウェイク・オン・タッチ
    - ウェイク・オン・タッチのステート・マシンにより、CPU がスリープ状態でも電極スキャンが可能
    - 環境補償、フィルタリング、スレッショルド検出のハードウェア・アクセラレーション
  - 使いやすさ
    - CapTIvate Design Center の PC GUI により、エンジニアはコードを作成せず、リアルタイムで容量性ボタンを設計し、チューニング可能
    - ROM の CapTIvate ソフトウェア・ライブラリにより、顧客アプリケーションに豊富な FRAM を使用可能
- 組み込みマイクロコントローラ
  - 16 ビットの RISC アーキテクチャ
  - 最高 16MHz のクロック周波数をサポート
  - 3.6V～1.8V の広い電源電圧範囲 (最小電源電圧は SVS レベルにより制限されます。「SVS 仕様」を参照)
- 最適化された超低消費電力モード
  - アクティブ・モード：126µA/MHz (標準値)
  - スタンバイ：4 つのセンサのウェイク・オン・タッチで 5µA 未満
  - LPM3.5 リアルタイム・クロック (RTC) カウンタ、32,768Hz の水晶発振器を使用：730nA (標準値)
  - シャットダウン (LPM4.5)：16nA (標準値)
- 高性能アナログ
  - 8 チャネル、10 ビットの A/D コンバータ (ADC)
    - 内蔵の 1.5V 基準電圧
    - サンプル・アンド・ホールド 200ksps
- 拡張シリアル通信
  - 2 つの拡張ユニバーサル・シリアル通信インターフェイス (eUSCI_A) により UART、IrDA、SPI をサポート
  - 1 つの eUSCI (eUSCI_B) が SPI および I^2C をサポート
- インテリジェントなデジタル・ペリフェラル
  - 4 つの 16 ビット・タイマ
    - 3 つのキャプチャ/比較レジスタを搭載したタイマ (Timer_A3) × 2
    - 2 つのキャプチャ/比較レジスタを搭載したタイマ (Timer_A2) × 2
  - CapTIvate テクノロジに関連付けられた 16 ビット・タイマ × 1
  - 16 ビット・カウンタ専用 RTC × 1
  - 16 ビットの巡回冗長性検査 (CRC)
- 低消費電力の強誘電体 RAM (FRAM)
  - 最大 15.5KB の不揮発性メモリ
  - エラー訂正コード (ECC) 搭載
  - 書き込み保護を設定可能
  - プログラム、定数、ストレージの統合メモリ
  - 書き込みサイクルの耐久性：10^{15} 回
  - 放射線耐性、非磁性
  - 高いFRAM:SRAM比、最大4:1

英語版のTI製品についての情報を翻訳したこの資料は、製品の概要を確認する目的で便宜的に提供しているものです。該当する正式な英語版の最新情報は、www.ti.comで閲覧でき、その内容が常に優先されます。TIでは翻訳の正確性および妥当性につきましては一切保証いたしません。実際の設計などの前には、必ず最新版の英語版をご参照くださいますようお願いいたします。

- クロック・システム (CS)
  - オンチップの 32kHz RC 発振器 (REFO)
  - オンチップの 16MHz デジタル制御発振器 (DCO)、周波数ロック・ループ (FLL) 付き
    - オンチップの基準電圧は室温で ±1% 精度
  - オンチップの超低周波数 10kHz 発振器 (VLO)
  - オンチップの高周波数変調発振器 (MODOSC)
  - 外付けの 32kHz 水晶発振器 (LFXT)
  - 1～128 の MCLK プリスケーラをプログラム可能
  - 1、2、4、8 のプログラマブル・プリスケーラを使って MCLK から SMCLK を生成
- 汎用入出力およびピン機能
  - TSSOP-32 パッケージに合計 19 の I/O を搭載
  - 16 本の割り込みピン (P1 および P2) により、低消費電力モードから MCU をウェイクアップ可能
- 開発ツールとソフトウェア
  - 開発ツール
    - MSP CapTIvate™ MCU 開発キットの評価：CAPTIVATE-PGMR プログラマ、容量性タッチ MSP430FR2633 MCU ボード CAPTIVATE-FR2633 とともに使用
    - ターゲット開発ボード (MSP-TS430RGE24A)
  - 使いやすいエコシステム
    - CapTIvate Design Center - コード生成、カスタマイズ可能な GUI、リアルタイム・チューニング
- ファミリ・メンバー (「 デバイスの比較」も参照)
  - MSP430FR2633：15KB のプログラム FRAM、512 バイトの情報 FRAM、4KB の RAM、最大 16 の自己容量式または 64 の相互容量式センサ
  - MSP430FR2533：15KB のプログラム FRAM、512 バイトの情報 FRAM、2KB の RAM、最大 16 の自己容量式または 24 の相互容量式センサ
  - MSP430FR2632：8KB のプログラム FRAM、512 バイトの情報 FRAM、2KB の RAM、最大 8 つの自己容量式または 16 の相互容量式センサ
  - MSP430FR2532：8KB のプログラム FRAM、512 バイトの情報 FRAM、1KB の RAM、最大 8 つの自己容量式または 8 つの相互容量式センサ
- パッケージ・オプション
  - 32 ピン：VQFN (RHB)
  - 32ピン：TSSOP (DA)
  - 24ピン：VQFN (RGE)
  - 24ピン：DSBGA (YQW)

1.2 アプリケーション

- 電子スマート・ロック、ドア・キーパッド、リーダー
- ガレージのドア・システム
- 侵入防止 HMI キーパッドおよび制御パネル
- 電動ブラインド
- リモート・コントロール
- パーソナル・エレクトロニクス
- ワイヤレス・スピーカおよびヘッドセット
- ハンドヘルド・ビデオ・ゲーム・コントローラ
- A/V レシーバ
- 白物家電
- 小型家電
- 園芸用具および電動工具

1.3 概要

MSP430FR263x/MSP430FR253xは、ボタン、スライダ、ホイール、近接センサ向けにCapTIvate™タッチ・テクノロジを搭載した、超低消費電力の静電容量式タッチ・センシング用MSP430™マイクロコントローラです。CapTIvateテクノロジを搭載したMSP430 MCUは、信頼性とノイズ耐性に優れ、消費電力が極めて低い、市場最高クラスの包括的かつ自律的な静電容量式タッチ・ソリューションを提供します。TIの静電容量式タッチ・テクノロジは、1つの設計で自己容量式と相互容量式の両方に対応し、最大限の柔軟性を実現します。CapTIvateテクノロジを搭載したMSP430 MCUは、厚いガラスやプラスチック筐体、金属、木材を透過し、湿気、油、汚れの多い過酷な環境でも動作します。

TIの静電容量式タッチ・センシング用MSP430 MCUは、ハードウェアおよびソフトウェアの大規模なエコシステムによってサポートされており、リファレンス・デザインやサンプル・コードを利用して設計をすぐに開始できます。開発キットには、MSP-CAPT-FR2633 CapTIvateテクノロジ開発キットがあります。また TI は、CapTIvate Design Center (使いやすい GUI でアプリケーションを迅速に開発可能) や MSP430Ware™ ソフトウェアなどの無償ソフトウェアと、CapTIvate テクノロジ・ガイドを含む広範囲の資料も提供しています。

MSP430超低消費電力(ULP) FRAMマイクロコントローラ・プラットフォームは、独自の組み込みFRAMと包括的な超低消費電力のシステム・アーキテクチャを組み合わせたもので、システム設計者は性能向上とエネルギー消費量削減を同時に実現できます。FRAMテクノロジは、RAMの低エネルギーでの高速書き込み、柔軟性、耐久性と、フラッシュの不揮発性を併せ持つものです。

モジュールの詳細な説明については、*『MSP430FR4xx and MSP430FR2xx Family User's Guide』* (英語) を参照してください。

Copyright © 2015–2019, Texas Instruments Incorporated

製品情報(1)

型番	パッケージ	本体サイズ (2)
MSP430FR2633IRHB	VQFN (32)	5mm×5mm
MSP430FR2533IRHB	VQFN (32)	5mm×5mm
MSP430FR2633IDA	TSSOP (32)	11mm×6.2mm
MSP430FR2533IDA	TSSOP (32)	11mm×6.2mm
MSP430FR2632IRGE	VQFN (24)	4mm×4mm
MSP430FR2532IRGE	VQFN (24)	4mm×4mm
MSP430FR2633IYQW	DSBGA (24)	2.29mm×2.34mm
MSP430FR2632IYQW	DSBGA (24)	2.29mm×2.34mm

(1) 最新の製品、パッケージ、および注文情報については、9の「*付録：パッケージ・オプション*」、または www.ti.comのTI Webサイトを参照してください。
(2) ここに記載されているサイズは概略です。許容公差を含めたパッケージの寸法については、9の「*メカニカル・データ*」を参照してください。

注意

電気的な過剰ストレスや、データやコード・メモリの不安定化を防止するため、デバイス・レベルのESD仕様に従って、システム・レベルのESD保護を適用する必要があります。詳細については、*『MSP430のシステム・レベルのESD考慮事項』*を参照してください。

Copyright © 2015–2019, Texas Instruments Incorporated

1.4 機能ブロック図

機能ブロック図を、図 1-1に示します。

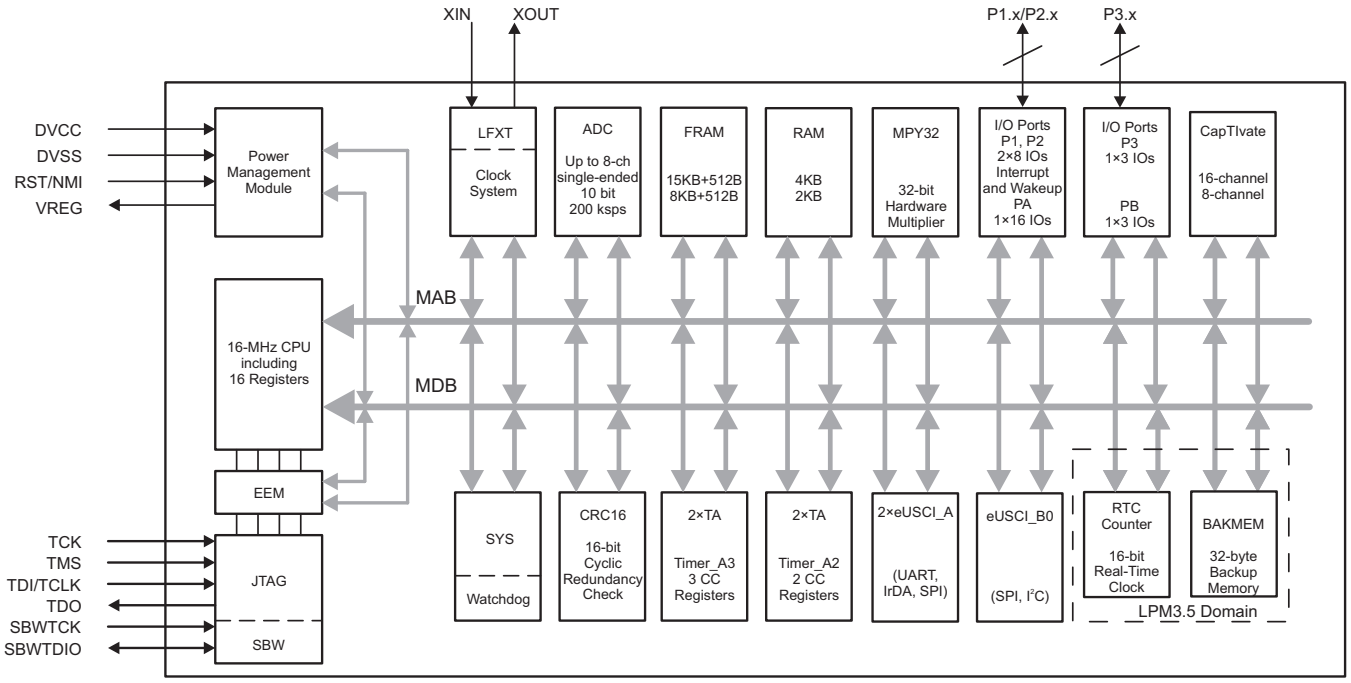


図 1-1. 機能ブロック図

- このMCUには、DVCCおよびDVSSの1つのメイン電源ペアがあり、デジタルとアナログの両方のモジュールへ電力を供給します。バイパスおよびデカップリング・コンデンサとしては、それぞれ4.7µF～10µFおよび0.1µFで、精度±5%が推奨されます。
- VREGは、CapTIvateレギュレータのデカップリング・コンデンサです。必要なデカップリング・コンデンサの推奨値は1µFで、最大ESRは200mΩ以下です。
- P1およびP2にはピン割り込み機能があり、LPM3.5およびLPM4を含むすべてのLPMからMCUをウェイクアップできます。
- 各Timer_A3には3つのキャプチャ/比較レジスタがあります。外部的に接続されているのはCCR1およびCCR2のみです。CCR0レジスタは、内部的な期間のタイミングと割り込みの生成にのみ使用できます。
- 各Timer_A2には2つのキャプチャ/比較レジスタがあります。この2つのレジスタは、内部的な期間のタイミングと割り込みの生成にのみ使用できます。
- LPM3モードでは、他のペリフェラルがオフの間もCapTIvateモジュールは機能できます。

Copyright © 2015–2019, Texas Instruments Incorporated

Table of Contents

1 デバイスの概要 1
1.1 特長 1
1.2 アプリケーション 2
1.3 概要 2
1.4 機能ブロック図 4
2 改訂履歴 6
3 Device Comparison 8
3.1 Related Products 8
4 Terminal Configuration and Functions 9
4.1 Pin Diagrams 9
4.2 Pin Attributes 13
4.3 Signal Descriptions 16
4.4 Pin Multiplexing 19
4.5 Buffer Types 19
4.6 Connection of Unused Pins 19
5 Specifications 20
5.1 Absolute Maximum Ratings 20
5.2 ESD Ratings 20
5.3 Recommended Operating Conditions 20
5.4 Active Mode Supply Current Into V_{CC} Excluding External Current 21
5.5 Active Mode Supply Current Per MHz 21
5.6 Low-Power Mode LPM0 Supply Currents Into V_{CC} Excluding External Current 21
5.7 Low-Power Mode (LPM3 and LPM4) Supply Currents (Into V_{CC}) Excluding External Current 22
5.8 Low-Power Mode LPMx.5 Supply Currents (Into V_{CC}) Excluding External Current 23
5.9 Typical Characteristics - Low-Power Mode Supply Currents 24
5.10 Thermal Resistance Characteristics 25
5.11 Timing and Switching Characteristics 26
6 Detailed Description 45
6.1 Overview 45
6.2 CPU 45
6.3 Operating Modes 45
6.4 Interrupt Vector Addresses 47
6.5 Bootloader (BSL) 48
6.6 JTAG Standard Interface 49
6.7 Spy-Bi-Wire Interface (SBW) 49
6.8 FRAM 49
6.9 Memory Protection 49
6.10 Peripherals 50
6.11 Input/Output Diagrams 60
6.12 Device Descriptors 67
6.13 Memory 68
6.14 Identification 76
7 Applications, Implementation, and Layout 77
7.1 Device Connection and Layout Fundamentals 77
7.2 Peripheral- and Interface-Specific Design Information 80
7.3 CapTIvate Technology Evaluation 83
8 デバイスおよびドキュメントのサポート 84
8.1 使い始めと次の手順 84
8.2 デバイスの項目表記 84
8.3 ツールとソフトウェア 85
8.4 ドキュメントのサポート 87
8.5 関連リンク 88
8.6 Community Resources 88
8.7 商標 88
8.8 静電気放電に関する注意事項 89
8.9 Export Control Notice 89
8.10 Glossary 89
9 メカニカル、パッケージ、および注文情報 90

Copyright © 2015–2019, Texas Instruments Incorporated

2 改訂履歴

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

リビジョン D からリビジョン E への変更点

2019年8月20日発行分から2019年12月9日発行分への変更 **Page**

- Changed the note that begins "Supply voltage changes faster than 0.2 V/µs can trigger a BOR reset..." in Section 5.3, *Recommended Operating Conditions* 20
- Added the note that begins "TI recommends that power to the DVCC pin must not exceed the limits..." in Section 5.3, *Recommended Operating Conditions* 20
- Changed the note that begins "A capacitor tolerance of ±20% or better is required..." in Section 5.3, *Recommended Operating Conditions* 20
- Changed the note that begins "Requires external capacitors at both terminals..." in Table 5-4, *XT1 Crystal Oscillator (Low Frequency)* 28
- Added the $t_{(int)}$ parameter in Table 5-10, *Digital Inputs* 32
- Added the $t_{TA,cap}$ parameter in Table 5-13, *Timer_A* 34
- Corrected the test conditions for the $R_{I,MUX}$ parameter in Table 5-20, *ADC, Power Supply and Input Range Conditions* 40
- Added the note that begins "$t_{Sample} = \ln(2^{n+1}) \times \tau$ ..." in Table 5-21, *ADC, 10-Bit Timing Parameters* 40
- Moved C_{REG} and $C_{ELECTRODE}$ from Section 5.3, *Recommended Operating Conditions* to Table 5-23, *CapTIvate Electrical Characteristics* 42
- Changed the CRC covered end address to 0x1AF5 in note (1) in Table 6-22, *Device Descriptors* 67

リビジョン C からリビジョン D への変更点

2018年8月29日発行分から2019年08月19日発行分への変更 **Page**

- 1.1「特長」を更新 1
- 1.1「特長」に「ターゲット開発ボード」を追加 2
- Changed "f_{CONVER} = 2 MHz" to "f_{CONVER} = 4 MHz" in the note that begins "CapTIvate technology works in LPM3 with 64 mutual-capacitance buttons" on Section 5.7, *Low-Power Mode (LPM3 and LPM4) Supply Currents (Into V_{CC}) Excluding External Current* 22
- Added the $t_{TA,cap}$ parameter in Table 5-13, *Timer_A* 34
- Changed the parameter symbol from R_I to $R_{I,MUX}$ in Table 5-20 , *ADC, Power Supply and Input Range Conditions* . 40
- Added $R_{I,Misc}$ TYP value of 34 kΩ in Table 5-20 , *ADC, Power Supply and Input Range Conditions* 40
- Added formula for R_I calculation in Table 5-21 , *ADC, 10-Bit Timing Parameters* 40
- Removed the description of "±3°C" in table note that starts "The device descriptor structure ..." of Table 5-22, *ADC, 10-Bit Linearity Parameters* 41
- Moved C_{REG} and $C_{ELECTRODE}$ from Section 5.3, *Recommended Operating Conditions* to Table 5-23, *CapTIvate Electrical Characteristics* 42
- Added test condition for $C_{ELECTRODE}$ in Table 5-23 , *CapTIvate Electrical Characteristics* 42
- Changed the symbol and description of the DC_{CAPCLK} parameter in Table 5-23, *CapTIvate Electrical Characteristics* 42
- Moved the SNR parameter to Table 5-24, *CapTIvate Signal-to-Noise Ratio Characteristics* 42
- Corrected bitfield from IRDSEL to IRDSSEL in Section 6.10.8, *Timers (Timer0_A3, Timer1_A3, Timer2_A2 and Timer3_A2)*, in the description that starts "The interconnection of Timer0_A3 and ..." 56
- Corrected the ADCINCHx column heading in Table 6-15, *ADC Channel Connections* 58
- Corrected the ADCSHSx column heading in Table 6-16, *ADC Trigger Signal Connections* 58
- Added P1SELC information in Table 6-32, *Port P1, P2 Registers (Base Address: 0200h)* 71
- Added P2SELC information in Table 6-32, *Port P1, P2 Registers (Base Address: 0200h)* 71
- Added P3SELC information in Table 6-33, *Port P3 Registers (Base Address: 0220h)* 71
- Updated Section 7.2.2, *CapTIvate Peripheral* 81

Copyright © 2015–2019, Texas Instruments Incorporated

リビジョン B からリビジョン C への変更点

2017年6月9日発行分から2018年08月28日発行分への変更	Page
• 1.1「*特長*」の「近接センシング」箇条書き項目から「30cm」を削除	1
• Updated Section 3.1, *Related Products*	8
• Corrected package type in VQFN row (changed from QFN to VQFN) in Table 4-2, *Signal Descriptions*	18
• Changed HBM limit to ±1000 V and CDM limit to ±250 V in Section 5.2, *ESD Ratings*	20
• Added note to V_{SVSH-} and V_{SVSH+} parameters in Table 5-2, *PMM, SVS and BOR*	26
• Added the $t_{TA,cap}$ parameter in Table 5-13, *Timer_A*	34
• Moved C_{REG} and $C_{ELECTRODE}$ from Section 5.3, *Recommended Operating Conditions* to Table 5-23, *CapTIvate Electrical Characteristics*	42
• Added the SNR parameter in Table 5-23, *CapTIvate Electrical Characteristics*	42
• Moved "FRAM access time error" to "System Reset" row and added ACCTEIFG to interrupt flag column in Table 6-2, *Interrupt Sources, Flags, and Vectors*	47
• Corrected the offset for P2SEL1 in Table 6-32, *Port P1, P2 Registers (Base Address: 0200h)*	71
• 8.2「*デバイスの項目表記*」のテキストおよび図を更新	84

リビジョン A からリビジョン B への変更点

2015年12月10日発行分から2017年06月8日発行分への変更	Page
• 「特長」一覧を再編成	1
• 1.1「*特長*」の「パッケージ・オプション」一覧に DSBGA (YQW) パッケージを追加	2
• 1.2「*アプリケーション*」の一覧を更新	2
• 1.3「*概要*」を更新	2
• 1.3「*概要*」の*製品情報*の表にDSBGA (YQW)パッケージ・オプションを追加	3
• Added MSP430FR2633IYQW and MSP430FR2632IYQW to Table 3-1, *Device Comparison*	8
• Added Section 3.1, *Related Products*	8
• Added DSBGA (YQW) pinout	12
• Added DSBGA (YQW) package to Table 4-1, *Pin Attributes*	13
• Added DSBGA (YQW) package to Table 4-2, *Signal Descriptions*	16
• Added row for VQFN thermal pad in Table 4-2, *Signal Descriptions*	18
• Removed FRAM reflow note	20
• Updated the notes on $I_{LPM3,\ CapTIvate,\ 16\ buttons}$ and $I_{LPM3,\ CapTIvate,\ 64\ buttons}$ in Section 5.7, *Low-Power Mode (LPM3 and LPM4) Supply Currents (Into V_{CC}) Excluding External Current*	22
• Added DSBGA (YQW) package and changed notes for Section 5.10, *Thermal Resistance Characteristics*	25
• Added the $t_{TA,cap}$ parameter in Table 5-13, *Timer_A*	34
• Removed ADCDIV from the formula for the TYP value in the second row of the $t_{CONVERT}$ parameter in Table 5-21, *ADC, 10-Bit Timing Parameters* (removed because ADCCLK is after division)	40
• Moved C_{REG} and $C_{ELECTRODE}$ from Section 5.3, *Recommended Operating Conditions* to Table 5-23, *CapTIvate Electrical Characteristics*	42
• Add description of blank device detection	48
• Changed the paragraph that starts "Quickly switching digital signals and ..." in Section 7.2.1.2, *Design Requirements*	80
• 図 8-1「*デバイスの項目表記*」を更新	84
• 従来の「*開発ツールのサポート*」セクションを 8.3、「*ツールとソフトウェア*」に置き換え	85
• 8.4「*ドキュメントのサポート*」の形式および内容を更新	87

初版からリビジョン A への変更点

2015年11月6日発行分から2015年12月9日発行分への変更	Page
• ドキュメントのステータスを「製品プレビュー」から「量産データ」に変更	1
• 一覧の「信頼性の高いタッチ・ソリューションを実現」を含む項目を変更	1
• 一覧の「広い電源電圧範囲」を含む項目に注を追加	1
• In the note that starts "Low-power mode 3, VLO, excludes SVS test conditions...", changed "f_{XT1} = 0 Hz" to "f_{XT1} = 32768 Hz"	22

Copyright © 2015–2019, Texas Instruments Incorporated

- Added note that starts "The VLO clock frequency is reduced by 15%..." 31
- Added the $t_{TA,cap}$ parameter in Table 5-13, *Timer_A* 34
- Moved C_{REG} and $C_{ELECTRODE}$ from Section 5.3, *Recommended Operating Conditions* to Table 5-23, *CapTIvate Electrical Characteristics* 42
- Added note to "Clock" in Table 6-1, *Operating Modes* 46
- Added note that starts "XT1CLK and VLOCLK can be active during LPM4..." 46
- Corrected description in Section 6.10.10, *Backup Memory (BKMEM)* 57

Copyright © 2015–2019, Texas Instruments Incorporated

3 Device Comparison

Table 3-1 summarizes the features of the available family members.

Table 3-1. Device Comparison(1)(2)

DEVICE	PROGRAM FRAM + INFORMATION FRAM (BYTES)	SRAM (BYTES)	TA0 TO TA3	eUSCI_A		eUSCI_B	10-BIT ADC CHANNELS	CapTIvate™ CHANNELS	GPIOs	PACKAGE TYPE
				UART	SPI					
MSP430FR2633IRHB	15360 + 512	4096	2, 3 × CCR(3) 2, 2 × CCR	up to 2	up to 2	1	8	16(4)	19	32 RHB (VQFN)
MSP430FR2533IRHB	15360 + 512	2048	2, 3 × CCR(3) 2, 2 × CCR	up to 2	up to 2	1	8	16(4)	19	32 RHB (VQFN)
MSP430FR2633IDA	15360 + 512	4096	2, 3 × CCR(3) 2, 2 × CCR	up to 2	up to 2	1	8	16(4)	19	32 DA (TSSOP)
MSP430FR2533IDA	15360 + 512	2048	2, 3 × CCR(3) 2, 2 × CCR	up to 2	up to 2	1	8	16(4)	19	32 DA (TSSOP)
MSP430FR2632IRGE	8192 + 512	2048	2, 3 × CCR(3) 2, 2 × CCR	up to 2	1	1	8	8(5)	15	24 RGE (VQFN)
MSP430FR2532IRGE	8192 + 512	1024	2, 3 × CCR(3) 2, 2 × CCR	up to 2	1	1	8	8(5)	15	24 RGE (VQFN)
MSP430FR2633IYQW	15360 + 512	4096	2, 3 × CCR(3) 2, 2 × CCR	up to 2	1	1	8	8(6)	17	24 YQW (DSBGA)
MSP430FR2632IYQW	8192 + 512	2048	2, 3 × CCR(3) 2, 2 × CCR	up to 2	1	1	8	8(6)	17	24 YQW (DSBGA)

(1) For the most current package and ordering information, see the *Package Option Addendum* in 9, or see the TI website at www.ti.com
(2) Package drawings, standard packing quantities, thermal data, symbolization, and PCB design guidelines are available at www.ti.com/packaging
(3) A CCR register is a configurable register that provides internal and external capture or compare inputs, or internal and external PWM outputs.
(4) Eight dedicated CapTIvate channels are included.
(5) Four dedicated CapTIvate channels are included.
(6) Two dedicated CapTIvate channels are included.

3.1 Related Products

For information about other devices in this family of products or related products, see the following links.

TI 16-bit and 32-bit microcontrollers

High-performance, low-power solutions to enable the autonomous future

Products for MSP430 ultra-low-power sensing & measurement MCUs

One platform. One ecosystem. Endless possibilities.

Companion products for MSP430FR2633

Review products that are frequently purchased or used with this product.

Reference designs for MSP430FR2633

Find reference designs leveraging the best in TI technology – from analog and power management to embedded processors

Copyright © 2015–2019, Texas Instruments Incorporated

4 Terminal Configuration and Functions

4.1 Pin Diagrams

Figure 4-1 shows the pinout for the 32-pin RHB package.

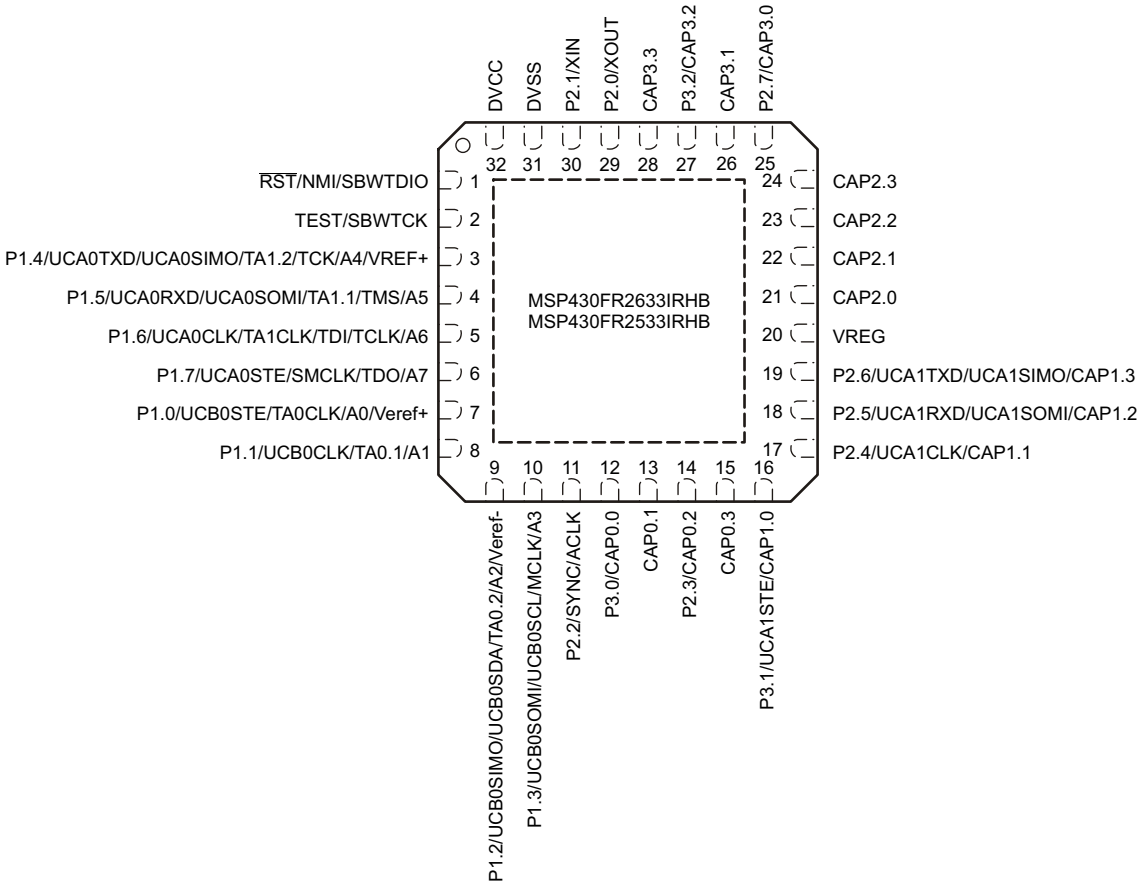


Figure 4-1. 32-Pin RHB Package (Top View)

Copyright © 2015–2019, Texas Instruments Incorporated

Figure 4-2 shows the pinout for the 32-pin DA package.

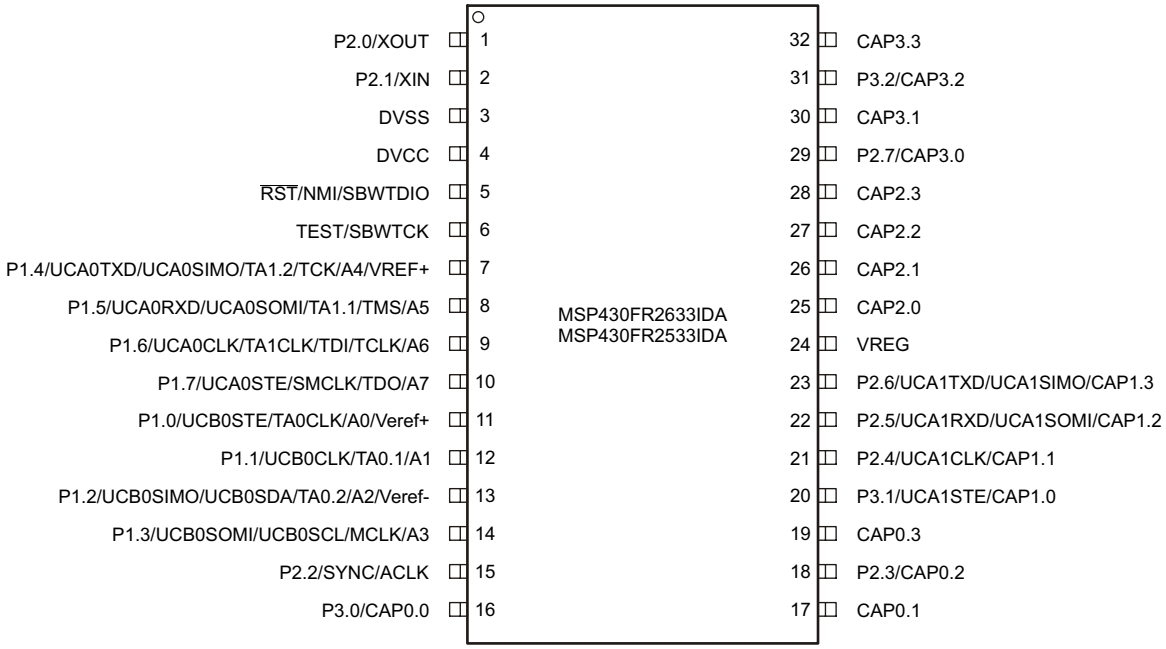


Figure 4-2. 32-Pin DA Package (Top View)

Figure 4-3 shows the pinout for the 24-pin RGE package.

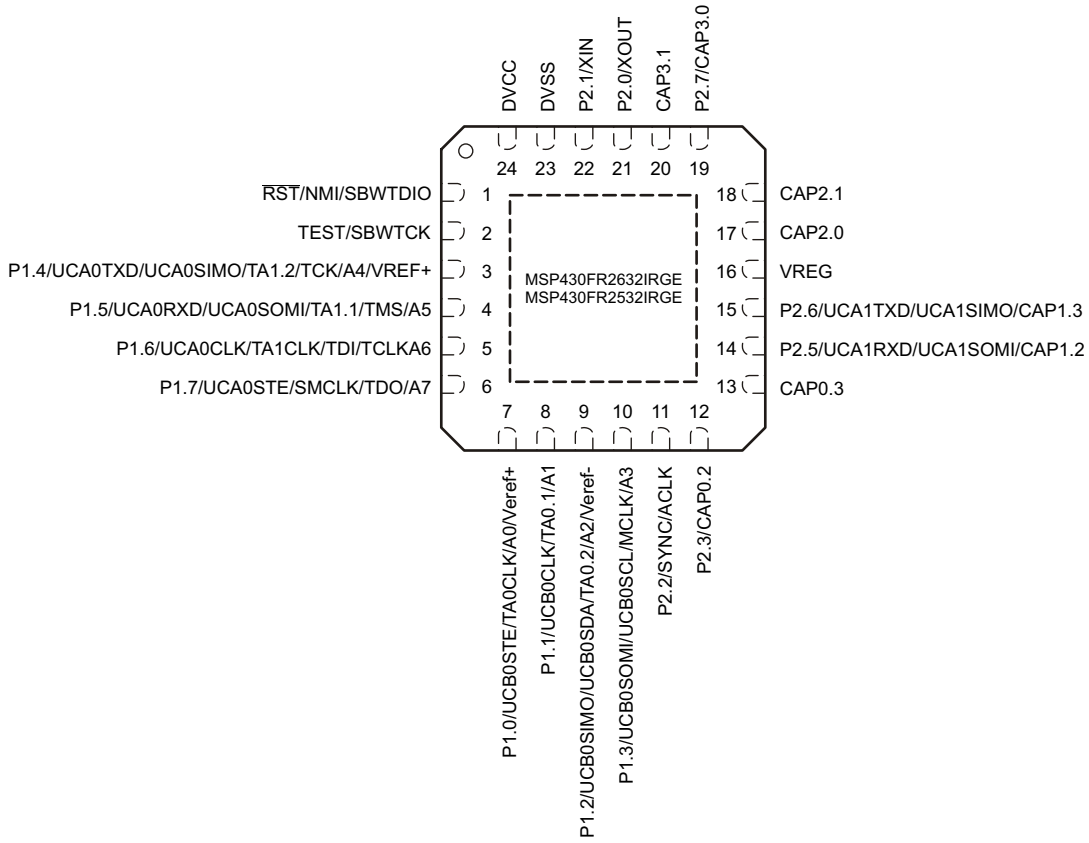
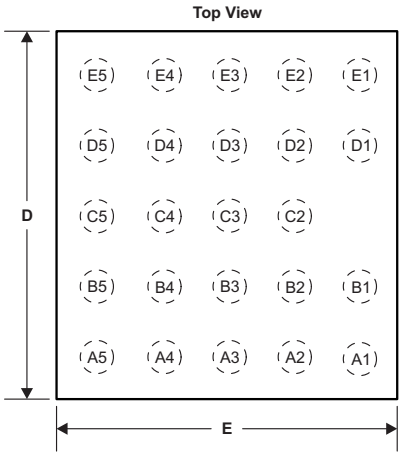


Figure 4-3. 24-Pin RGE Package (Top View)

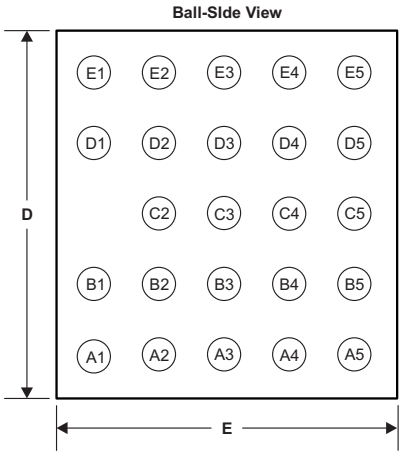
Copyright © 2015–2019, Texas Instruments Incorporated

Figure 4-4 shows the top view of the YQW package, and Figure 4-5 shows the bottom (ball-side) view.



PIN NO.	SIGNAL NAME	PIN NO.	SIGNAL NAME
A1	P1.1/UCB0CLK/TA0.1/A1	C4	CAP2.0
A2	P1.3/UCB0SOMI/UCB0SCL/MCLK/A3	C5	VREG
A3	P2.2/SYNC/ACLK	D1	P1.4/UCA0TXD/UCA0SIMO/TA1.2/TCK/A4/VREF+
A4	P3.0/CAP0.0	D2	TEST/SBWTCK
A5	P2.3/CAP0.2	D3	DVSS
B1	P1.0/UCB0STE/TA0CLK/A0/Veref+	D4	P3.2/CAP3.2
B2	P1.2/UCB0SIMO/UCB0SDA/TA0.2/A2/Veref-	D5	CAP2.2
B3	P1.7/UCA0STE/SMCLK/TDO/A7	E1	$\overline{\text{RST}}$/NMI/SBWTDIO
B4	P2.5/UCA1RXD/CAP1.2	E2	DVCC
B5	P2.6/UCA1TXD/CAP1.3	E3	P2.1/XIN
C2	P1.5/UCA0RXD/UCA0SOMI/TA1.1/TMS/A5	E4	P2.0/XOUT
C3	P1.6/UCA0CLK/TA1CLK/TDI/TCLK/A6	E5	P2.7/CAP3.0

Figure 4-4. 24-Pin YQW Package (Top View)



PIN NO.	SIGNAL NAME	PIN NO.	SIGNAL NAME
A1	P1.1/UCB0CLK/TA0.1/A1	C4	CAP2.0
A2	P1.3/UCB0SOMI/UCB0SCL/MCLK/A3	C5	VREG
A3	P2.2/SYNC/ACLK	D1	P1.4/UCA0TXD/UCA0SIMO/TA1.2/TCK/A4/VREF+
A4	P3.0/CAP0.0	D2	TEST/SBWTCK
A5	P2.3/CAP0.2	D3	DVSS
B1	P1.0/UCB0STE/TA0CLK/A0/Veref+	D4	P3.2/CAP3.2
B2	P1.2/UCB0SIMO/UCB0SDA/TA0.2/A2/Veref-	D5	CAP2.2
B3	P1.7/UCA0STE/SMCLK/TDO/A7	E1	$\overline{\text{RST}}$/NMI/SBWTDIO
B4	P2.5/UCA1RXD/CAP1.2	E2	DVCC
B5	P2.6/UCA1TXD/CAP1.3	E3	P2.1/XIN
C2	P1.5/UCA0RXD/UCA0SOMI/TA1.1/TMS/A5	E4	P2.0/XOUT
C3	P1.6/UCA0CLK/TA1CLK/TDI/TCLK/A6	E5	P2.7/CAP3.0

Figure 4-5. 24-Pin YQW Package (Bottom View)

Copyright © 2015–2019, Texas Instruments Incorporated

4.2 Pin Attributes

Table 4-1 lists the attributes of all pins.

Table 4-1. Pin Attributes

PIN NUMBER				SIGNAL NAME(1) (2)	SIGNAL TYPE(3)	BUFFER TYPE(4)	POWER SOURCE(5)	RESET STATE AFTER BOR(6)
RHB	DA	RGE	YQW					
1	5	1	E1	$\overline{\text{RST}}$ (RD)	I	LVCMOS	DVCC	OFF
				NMI	I	LVCMOS	DVCC	–
				SBWTDIO	I/O	LVCMOS	DVCC	–
2	6	2	D2	TEST (RD)	I	LVCMOS	DVCC	OFF
				SBWTCK	I	LVCMOS	DVCC	–
3	7	3	D1	P1.4 (RD)	I/O	LVCMOS	DVCC	OFF
				UCA0TXD	O	LVCMOS	DVCC	–
				UCA0SIMO	I/O	LVCMOS	DVCC	–
				TA1.2	I/O	LVCMOS	DVCC	–
				TCK	I	LVCMOS	DVCC	–
				A4	I	Analog	DVCC	–
				VREF+	O	Power	DVCC	–
4	8	4	C2	P1.5 (RD)	I/O	LVCMOS	DVCC	OFF
				UCA0RXD	I	LVCMOS	DVCC	–
				UCA0SOMI	I/O	LVCMOS	DVCC	–
				TA1.1	I/O	LVCMOS	DVCC	–
				TMS	I	LVCMOS	DVCC	–
				A5	I	Analog	DVCC	–
5	9	5	C3	P1.6 (RD)	I/O	LVCMOS	DVCC	OFF
				UCA0CLK	I/O	LVCMOS	DVCC	–
				TA1CLK	I	LVCMOS	DVCC	–
				TDI	I	LVCMOS	DVCC	–
				TCLK	I	LVCMOS	DVCC	–
				A6	I	Analog	DVCC	–
6	10	6	B3	P1.7 (RD)	I/O	LVCMOS	DVCC	OFF
				UCA0STE	I/O	LVCMOS	DVCC	–
				SMCLK	O	LVCMOS	DVCC	–
				TDO	O	LVCMOS	DVCC	–
				A7	I	Analog	DVCC	–
7	11	7	B1	P1.0 (RD)	I/O	LVCMOS	DVCC	OFF
				UCB0STE	I/O	LVCMOS	DVCC	–
				TA0CLK	I	LVCMOS	DVCC	–
				A0	I	Analog	DVCC	–
				Veref+	I	Power	DVCC	–

(1) Signals names with (RD) denote the reset default pin name.
(2) To determine the pin mux encodings for each pin, see Section 6.11, *Input/Output Diagrams*.
(3) Signal Types: I = Input, O = Output, I/O = Input or Output
(4) Buffer Types: LVCMOS, Analog, or Power (see Table 4-3)
(5) The power source shown in this table is the I/O power source, which may differ from the module power source.
(6) Reset States:
OFF = High-impedance with Schmitt trigger and pullup or pulldown (if available) disabled
N/A = Not applicable

Copyright © 2015–2019, Texas Instruments Incorporated

Table 4-1. Pin Attributes (continued)

PIN NUMBER				SIGNAL NAME[1] [2]	SIGNAL TYPE[3]	BUFFER TYPE[4]	POWER SOURCE[5]	RESET STATE AFTER BOR[6]
RHB	DA	RGE	YQW					
8	12	8	A1	P1.1 (RD)	I/O	LVCMOS	DVCC	OFF
				UCB0CLK	I/O	LVCMOS	DVCC	–
				TA0.1	I/O	LVCMOS	DVCC	–
				A1	I	Analog	DVCC	–
9	13	9	B2	P1.2 (RD)	I/O	LVCMOS	DVCC	OFF
				UCB0SIMO	I/O	LVCMOS	DVCC	–
				UCB0SDA	I/O	LVCMOS	DVCC	–
				TA0.2	I/O	LVCMOS	DVCC	–
				A2	I	Analog	DVCC	–
				Veref-	I	Power	DVCC	–
10	14	10	A2	P1.3 (RD)	I/O	LVCMOS	DVCC	OFF
				UCB0SOMI	I/O	LVCMOS	DVCC	–
				UCB0SCL	I/O	LVCMOS	DVCC	–
				MCLK	O	LVCMOS	DVCC	–
				A3	I	Analog	DVCC	–
11	15	11	A3	P2.2 (RD)	I/O	LVCMOS	DVCC	OFF
				SYNC	I	LVCMOS	DVCC	–
				ACLK	O	LVCMOS	DVCC	–
12	16	–	A4	P3.0 (RD)	I/O	LVCMOS	DVCC	OFF
				CAP0.0	I/O	Analog	V_{REG}	–
13	17	–	–	CAP0.1	I/O	Analog	V_{REG}	OFF
14	18	12	A5	P2.3 (RD)	I/O	LVCMOS	DVCC	OFF
				CAP0.2	I/O	Analog	V_{REG}	–
15	19	13	–	CAP0.3	I/O	Analog	V_{REG}	OFF
16	20	–	–	P3.1 (RD)	I/O	LVCMOS	DVCC	OFF
				UCA1STE	I/O	LVCMOS	DVCC	–
				CAP1.0	I/O	Analog	V_{REG}	–
17	21	–	–	P2.4 (RD)	I/O	LVCMOS	DVCC	OFF
				UCA1CLK	I/O	LVCMOS	DVCC	–
				CAP1.1	I/O	Analog	V_{REG}	–
18	22	14	B4	P2.5 (RD)	I/O	LVCMOS	DVCC	OFF
				UCA1RXD	I	LVCMOS	DVCC	–
				UCA1SOMI	I/O	LVCMOS	DVCC	–
				CAP1.2	I/O	Analog	V_{REG}	–
19	23	15	B5	P2.6 (RD)	I/O	LVCMOS	DVCC	OFF
				UCA1TXD	O	LVCMOS	DVCC	–
				UCA1SIMO	I/O	LVCMOS	DVCC	–
				CAP1.3	I/O	Analog	V_{REG}	–
20	24	16	C5	VREG	P	Power	V_{REG}	N/A
21	25	17	C4	CAP2.0	I/O	Analog	V_{REG}	OFF
22	26	18	–	CAP2.1	I/O	Analog	V_{REG}	OFF
23	27	–	D5	CAP2.2	I/O	Analog	V_{REG}	OFF
24	28	–	–	CAP2.3	I/O	Analog	V_{REG}	OFF
25	29	19	E5	P2.7 (RD)	I/O	LVCMOS	DVCC	OFF
				CAP3.0	I/O	Analog	V_{REG}	–
26	30	20	–	CAP3.1	I/O	Analog	V_{REG}	OFF

Copyright © 2015–2019, Texas Instruments Incorporated

Table 4-1. Pin Attributes (continued)

PIN NUMBER				SIGNAL NAME[1] [2]	SIGNAL TYPE[3]	BUFFER TYPE[4]	POWER SOURCE[5]	RESET STATE AFTER BOR[6]
RHB	DA	RGE	YQW					
27	31	–	D4	P3.2 (RD)	I/O	LVCMOS	DVCC	OFF
				CAP3.2	I/O	Analog	V_{REG}	–
28	32	–	–	CAP3.3	I/O	Analog	V_{REG}	OFF
29	1	21	E4	P2.0 (RD)	I/O	LVCMOS	DVCC	OFF
				XOUT	O	LVCMOS	DVCC	–
30	2	22	E3	P2.1 (RD)	I/O	LVCMOS	DVCC	OFF
				XIN	I	LVCMOS	DVCC	–
31	3	23	D3	DVSS	P	Power	DVCC	N/A
32	4	24	E2	DVCC	P	Power	DVCC	N/A

Copyright © 2015–2019, Texas Instruments Incorporated

4.3 Signal Descriptions

Table 4-2 describes the signals for all device variants and package options.

Table 4-2. Signal Descriptions

FUNCTION	SIGNAL NAME	PIN NUMBER				PIN TYPE(1)	DESCRIPTION
		RHB	DA	RGE	YQW		
ADC	A0	7	11	7	B1	I	Analog input A0
	A1	8	12	8	A1	I	Analog input A1
	A2	9	13	9	B2	I	Analog input A2
	A3	10	14	10	A2	I	Analog input A3
	A4	3	7	3	D1	I	Analog input A4
	A5	4	8	4	C2	I	Analog input A5
	A6	5	9	5	C3	I	Analog input A6
	A7	6	10	6	B3	I	Analog input A7
	Veref+	7	11	7	B1	I	ADC positive reference
	Veref-	9	13	9	B2	I	ADC negative reference
CapTIvate	CAP0.0	12	16	–	A4	I/O	CapTIvate channel
	CAP0.1	13	17	–	–	I/O	CapTIvate channel
	CAP0.2	14	18	12	A5	I/O	CapTIvate channel
	CAP0.3	15	19	13	–	I/O	CapTIvate channel
	CAP1.0	16	20	–	–	I/O	CapTIvate channel
	CAP1.1	17	21	–	–	I/O	CapTIvate channel
	CAP1.2	18	22	14	B4	I/O	CapTIvate channel
	CAP1.3	19	23	15	B5	I/O	CapTIvate channel
	CAP2.0	21	25	17	C4	I/O	CapTIvate channel
	CAP2.1	22	26	18	–	I/O	CapTIvate channel
	CAP2.2	23	27	–	D5	I/O	CapTIvate channel
	CAP2.3	24	28	–	–	I/O	CapTIvate channel
	CAP3.0	25	29	19	E5	I/O	CapTIvate channel
	CAP3.1	26	30	20	–	I/O	CapTIvate channel
	CAP3.2	27	31	–	D4	I/O	CapTIvate channel
	CAP3.3	28	32	–	–	I/O	CapTIvate channel
	SYNC	11	15	11	A3	I	CapTIvate synchronous trigger input for processing and conversion
Clock	ACLK	11	15	11	A3	O	ACLK output
	MCLK	10	14	10	A2	O	MCLK output
	SMCLK	6	10	6	B3	O	SMCLK output
	XIN	30	2	22	E3	I	Input terminal for crystal oscillator
	XOUT	29	1	21	E4	O	Output terminal for crystal oscillator
Debug	SBWTCK	2	6	2	D2	I	Spy-Bi-Wire input clock
	SBWTDIO	1	5	1	E1	I/O	Spy-Bi-Wire data input/output
	TCK	3	7	3	D1	I	Test clock
	TCLK	5	9	5	C3	I	Test clock input
	TDI	5	9	5	C3	I	Test data input
	TDO	6	10	6	B3	O	Test data output
	TEST	2	6	2	D2	I	Test Mode pin – selected digital I/O on JTAG pins
	TMS	4	8	4	C2	I	Test mode select

(1) Pin Types: I = Input, O = Output, I/O = Input or Output, P = Power

Copyright © 2015–2019, Texas Instruments Incorporated

Table 4-2. Signal Descriptions (continued)

FUNCTION	SIGNAL NAME	PIN NUMBER				PIN TYPE(1)	DESCRIPTION
		RHB	DA	RGE	YQW		
GPIO	P1.0	7	11	7	B1	I/O	General-purpose I/O
	P1.1	8	12	8	A1	I/O	General-purpose I/O
	P1.2	9	13	9	B2	I/O	General-purpose I/O
	P1.3	10	14	10	A2	I/O	General-purpose I/O
	P1.4	3	7	3	D1	I/O	General-purpose I/O(2)
	P1.5	4	8	4	C2	I/O	General-purpose I/O(2)
	P1.6	5	9	5	C3	I/O	General-purpose I/O(2)
	P1.7	6	10	6	B3	I/O	General-purpose I/O(2)
	P2.0	29	1	21	E4	I/O	General-purpose I/O
	P2.1	30	2	22	E3	I/O	General-purpose I/O
	P2.2	11	15	11	A3	I/O	General-purpose I/O
	P2.3	14	18	12	A5	I/O	General-purpose I/O
	P2.4	17	21	–	–	I/O	General-purpose I/O
	P2.5	18	22	14	B4	I/O	General-purpose I/O
	P2.6	19	23	15	B5	I/O	General-purpose I/O
	P2.7	25	29	19	E5	I/O	General-purpose I/O
	P3.0	12	16	–	A4	I/O	General-purpose I/O
	P3.1	16	20	–	–	I/O	General-purpose I/O
	P3.2	27	31	–	D4	I/O	General-purpose I/O
I^2C	UCB0SCL	10	14	10	A2	I/O	eUSCI_B0 I^2C clock
	UCB0SDA	9	13	9	B2	I/O	eUSCI_B0 I^2C data
Power	DVCC	32	4	24	E2	P	Power supply
	DVSS	31	3	23	D3	P	Power ground
	VREF+	3	7	3	D1	P	Output of positive reference voltage with ground as reference
	VREG	20	24	16	C5	O	CapTIvate regulator external decoupling capacitor
SPI	UCA0CLK	5	9	5	C3	I/O	eUSCI_A0 SPI clock input/output
	UCA0SIMO	3	7	3	D1	I/O	eUSCI_A0 SPI slave in/master out
	UCA0SOMI	4	8	4	C2	I/O	eUSCI_A0 SPI slave out/master in
	UCA0STE	6	10	6	B3	I/O	eUSCI_A0 SPI slave transmit enable
	UCA1CLK	17	21	–	–	I/O	eUSCI_A1 SPI clock input/output
	UCA1SIMO	19	23	15	B5	I/O	eUSCI_A1 SPI slave in/master out
	UCA1SOMI	18	22	14	B4	I/O	eUSCI_A1 SPI slave out/master in
	UCA1STE	16	20	–	–	I/O	eUSCI_A1 SPI slave transmit enable
	UCB0CLK	8	12	8	A1	I/O	eUSCI_B0 clock input/output
	UCB0SIMO	9	13	9	B2	I/O	eUSCI_B0 SPI slave in/master out
	UCB0SOMI	10	14	10	A2	I/O	eUSCI_B0 SPI slave out/master in
	UCB0STE	7	11	7	B1	I/O	eUSCI_B0 slave transmit enable
System	NMI	1	5	1	E1	I	Nonmaskable interrupt input
	$\overline{RST}$	1	5	1	E1	I	Active-low reset input

(2) Because this pin is multiplexed with the JTAG function, TI recommends disabling the pin interrupt function while in JTAG debug to prevent collisions.

Copyright © 2015–2019, Texas Instruments Incorporated

Table 4-2. Signal Descriptions (continued)

FUNCTION	SIGNAL NAME	PIN NUMBER				PIN TYPE(1)	DESCRIPTION
		RHB	DA	RGE	YQW		
Timer_A	TA0.1	8	12	8	A1	I/O	Timer TA0 CCR1 capture: CCI1A input, compare: Out1 outputs
	TA0.2	9	13	9	B2	I/O	Timer TA0 CCR2 capture: CCI2A input, compare: Out2 outputs
	TA0CLK	7	11	7	B1	I	Timer clock input TACLK for TA0
	TA1.1	4	8	4	C2	I/O	Timer TA1 CCR1 capture: CCI1A input, compare: Out1 outputs
	TA1.2	3	7	3	D1	I/O	Timer TA1 CCR2 capture: CCI2A input, compare: Out2 outputs
	TA1CLK	5	9	5	C3	I	Timer clock input TACLK for TA1
UART	UCA0RXD	4	8	4	C2	I	eUSCI_A0 UART receive data
	UCA0TXD	3	7	3	D1	O	eUSCI_A0 UART transmit data
	UCA1RXD	18	22	14	B4	I	eUSCI_A1 UART receive data
	UCA1TXD	19	23	15	B5	O	eUSCI_A1 UART transmit data
VQFN Pad	VQFN thermal pad	Pad	N/A	Pad	N/A		VQFN package exposed thermal pad. TI recommends connecting to V_{SS}.

Copyright © 2015–2019, Texas Instruments Incorporated

4.4 Pin Multiplexing

Pin multiplexing for these MCUs is controlled by both register settings and operating modes (for example, if the MCU is in test mode). For details of the settings for each pin and schematics of the multiplexed ports, see Section 6.11.

4.5 Buffer Types

Table 4-3 defines the pin buffer types that are listed in Table 4-1.

Table 4-3. Buffer Types

BUFFER TYPE (STANDARD)	NOMINAL VOLTAGE	HYSTERESIS	PU OR PD	NOMINAL PU OR PD STRENGTH (µA)	OUTPUT DRIVE STRENGTH (mA)	OTHER CHARACTERISTICS
LVCMOS	3.0 V	Y(1)	Programmable	See Section 5.11.4	See Section 5.11.4	
Analog	3.0 V	N	N/A	N/A	N/A	See analog modules in Section 5 for details.
Power (DVCC)	3.0 V	N	N/A	N/A	N/A	SVS enables hysteresis on DVCC.
Power (AVCC)	3.0 V	N	N/A	N/A	N/A	

(1) Only for input pins.

4.6 Connection of Unused Pins

Table 4-4 lists the correct termination of unused pins.

Table 4-4. Connection of Unused Pins(1)

PIN	POTENTIAL	COMMENT
Px.0 to Px.7	Open	Switched to port function, output direction (PxDIR.n = 1)
$\overline{\text{RST}}$/NMI	DV_{CC}	47-kΩ pullup or internal pullup selected with 10-nF (or 1.1-nF) pulldown(2)
TEST	Open	This pin always has an internal pulldown enabled.
CAP2.x, CAPx.1, CAPx.3	Open	These pins have internal pullup and pulldown resistors, and high impedance is their default setting.

(1) Any unused pin with a secondary function that is shared with general-purpose I/O should follow the Px.0 to Px.7 unused pin connection guidelines.
(2) The pulldown capacitor should not exceed 1.1 nF when using MCUs with Spy-Bi-Wire interface in Spy-Bi-Wire mode with TI tools like FET interfaces or GANG programmers.

Copyright © 2015–2019, Texas Instruments Incorporated

5 Specifications

5.1 Absolute Maximum Ratings(1)

over operating free-air temperature range (unless otherwise noted)

	MIN	MAX	UNIT
Voltage applied at DVCC pin to V_{SS}	–0.3	4.1	V
Voltage applied to any dedicated CapTIvate pin or pin in CapTIvate mode (2)	–0.3	V_{REG}	V
Voltage applied to any other pin(3)	–0.3	V_{CC} + 0.3 (4.1 V Max)	V
Diode current at any device pin		±2	mA
Maximum junction temperature, T_J		85	°C
Storage temperature, T_{stg}(4)	–40	125	°C

(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
(2) This applies to dedicated CapTIvate I/Os only or I/Os worked in CapTIvate mode.
(3) All voltages referenced to V_{SS}.
(4) Higher temperature may be applied during board soldering according to the current JEDEC J-STD-020 specification with peak reflow temperatures not higher than classified on the device label on the shipping boxes or reels.

5.2 ESD Ratings

			VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001(1)	±1000	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101(2)	±250	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process. Pins listed as ±1000 V may actually have higher performance.
(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process. Pins listed as ±250 V may actually have higher performance.

5.3 Recommended Operating Conditions

			MIN	NOM	MAX	UNIT
V_{CC}	Supply voltage applied at DVCC pin(1)(2)(3)(4)		1.8		3.6	V
V_{SS}	Supply voltage applied at DVSS pin			0		V
T_A	Operating free-air temperature		–40		85	°C
T_J	Operating junction temperature		–40		85	°C
C_{DVCC}	Recommended capacitor at DVCC(5)		4.7	10		µF
f_{SYSTEM}	Processor frequency (maximum MCLK frequency)(6)	No FRAM wait states (NWAITSx = 0)	0		8	MHz
		With FRAM wait states (NWAITSx = 1)(7)	0		16(8)	
f_{ACLK}	Maximum ACLK frequency				40	kHz
f_{SMCLK}	Maximum SMCLK frequency				16(8)	MHz

(1) Supply voltage changes faster than 0.2 V/µs can trigger a BOR reset even within the recommended supply voltage range. Following the data sheet recommendation for capacitor C_{DVCC} limits the slopes accordingly.
(2) Modules may have a different supply voltage range specification. See the specification of the respective module in this data sheet.
(3) TI recommends that power to the DVCC pin must not exceed the limits specified in *Recommended Operating Conditions*. Exceeding the specified limits can cause malfunction of the device including erroneous writes to RAM and FRAM.
(4) The minimum supply voltage is defined by the SVS levels. See the SVS threshold parameters in Table 5-2.
(5) A capacitor tolerance of ±20% or better is required. A low-ESR ceramic capacitor of 100 nF (minimum) should be placed as close as possible (within a few millimeters) to the respective pin pair.
(6) Modules may have a different maximum input clock specification. See the specification of the respective module in this data sheet.
(7) Wait states only occur on actual FRAM accesses (that is, on FRAM cache misses). RAM and peripheral accesses are always executed without wait states.
(8) If clock sources such as HF crystals or the DCO with frequencies >16 MHz are used, the clock must be divided in the clock system to comply with this operating condition.

Copyright © 2015–2019, Texas Instruments Incorporated

5.4 Active Mode Supply Current Into V_{CC} Excluding External Current(1)

V_{CC} = 3 V, T_A = 25°C (unless otherwise noted)

PARAMETER	EXECUTION MEMORY	TEST CONDITION	FREQUENCY (f_{MCLK} = f_{SMCLK})						UNIT
			1 MHz 0 WAIT STATES (NWAITSx = 0)		8 MHz 0 WAIT STATES (NWAITSx = 0)		16 MHz 1 WAIT STATE (NWAITSx = 1)		
			TYP	MAX	TYP	MAX	TYP	MAX	
$I_{AM,\ FRAM}$(0%)	FRAM 0% cache hit ratio	3 V, 25°C	504		2772		3047	3480	µA
		3 V, 85°C	516		2491		2871		
$I_{AM,\ FRAM}$(100%)	FRAM 100% cache hit ratio	3 V, 25°C	203		625		1000	1215	µA
		3 V, 85°C	212		639		1016		
$I_{AM,\ RAM}$(2)	RAM	3 V, 25°C	229		818		1377		µA

(1) All inputs are tied to 0 V or to V_{CC}. Outputs do not source or sink any current. Characterized with program executing typical data processing.
f_{ACLK} = 32768 Hz, f_{MCLK} = f_{SMCLK} = f_{DCO} at specified frequency
Program and data entirely reside in FRAM. All execution is from FRAM.
(2) Program and data reside entirely in RAM. All execution is from RAM. No access to FRAM.

5.5 Active Mode Supply Current Per MHz

V_{CC} = 3 V, T_A = 25°C (unless otherwise noted)

PARAMETER		TEST CONDITIONS	TYP	UNIT
$dI_{AM,FRAM}/df$	Active mode current consumption per MHz, execution from FRAM, no wait states	[I_{AM} (75% cache hit rate) at 8 MHz – I_{AM} (75% cache hit rate) at 1 MHz)] / 7 MHz	126	µA/MHz

5.6 Low-Power Mode LPM0 Supply Currents Into V_{CC} Excluding External Current

V_{CC} = 3 V, T_A = 25°C (unless otherwise noted)(1)(2)

PARAMETER	V_{CC}	FREQUENCY (f_{SMCLK})						UNIT
		1 MHz		8 MHz		16 MHz		
		TYP	MAX	TYP	MAX	TYP	MAX	
I_{LPM0}	2 V	156		328		420		µA
	3 V	166		342		433		

(1) All inputs are tied to 0 V or to V_{CC}. Outputs do not source or sink any current.
(2) Current for watchdog timer clocked by SMCLK included.
f_{ACLK} = 32768 Hz, f_{MCLK} = 0 MHz, f_{SMCLK} at specified frequency.

Copyright © 2015–2019, Texas Instruments Incorporated

5.7 Low-Power Mode (LPM3 and LPM4) Supply Currents (Into V_{CC}) Excluding External Current

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (1)

PARAMETER		V_{CC}	–40°C		25°C		85°C		UNIT
			TYP	MAX	TYP	MAX	TYP	MAX	
$I_{LPM3,XT1}$	Low-power mode 3, 12.5-pF crystal, includes SVS (2)(3)(4)	3 V	0.98		1.18	1.65	3.24		µA
		2 V	0.96		1.16		3.21		
$I_{LPM3,VLO}$	Low-power mode 3, VLO, excludes SVS (5)	3 V	0.78		0.98	1.40	3.04		µA
		2 V	0.76		0.96		3.01		
$I_{LPM3,\ RTC}$	Low-power mode 3, RTC, excludes SVS (6) (see Figure 5-1)	3 V	0.93		1.13		3.19		µA
$I_{LPM3,\ CapTIvate,}$ 1 proximity, wake on touch	Low-power mode 3, CapTIvate, excludes SVS (7)	3.3 V			5				µA
$I_{LPM3,\ CapTIvate,}$ 1 button, wake on touch	Low-power mode 3, CapTIvate, excludes SVS (8)	3.3 V			3.4				µA
$I_{LPM3,\ CapTIvate,}$ 4 buttons, wake on touch	Low-power mode 3, CapTIvate, excludes SVS (9)	3.3 V			3.6				µA
$I_{LPM3,\ CapTIvate,}$ 16 buttons	Low-power mode 3, CapTIvate, excludes SVS (10)	3.3 V			27.2				µA
$I_{LPM3,\ CapTIvate,}$ 64 buttons	Low-power mode 3, CapTIvate, excludes SVS (11)	3.3 V			109.2				µA
$I_{LPM4,\ SVS}$	Low-power mode 4, includes SVS	3 V	0.51		0.65		2.65		µA
		2 V	0.49		0.64		2.63		
I_{LPM4}	Low-power mode 4, excludes SVS	3 V	0.35		0.49		2.49		µA
		2 V	0.34		0.48		2.46		
$I_{LPM4,\ CapTIvate,}$ 1 proximity, wake on touch	Low-power mode 4, CapTIvate, excludes SVS (12)	3 V			4.4				µA

(1) All inputs are tied to 0 V or to V_{CC}. Outputs do not source or sink any current.
(2) Not applicable for MCUs with HF crystal oscillator only.
(3) Characterized with a Micro Crystal MS1V-T1K crystal with a load capacitance of 12.5 pF. The internal and external load capacitance are chosen to closely match the required 12.5-pF load.
(4) Low-power mode 3, 12.5-pF crystal, includes SVS test conditions:
Current for watchdog timer clocked by ACLK and RTC clocked by XT1 included. Current for brownout and SVS included (SVSHE = 1).
CPUOFF = 1, SCG0 = 1 SCG1 = 1, OSCOFF = 0 (LPM3),
f_{XT1} = 32768 Hz, $f_{ACLK} = f_{XT1}$, $f_{MCLK} = f_{SMCLK}$ = 0 MHz
(5) Low-power mode 3, VLO, excludes SVS test conditions:
Current for watchdog timer clocked by VLO included. RTC disabled. Current for brownout included. SVS disabled (SVSHE = 0).
CPUOFF = 1, SCG0 = 1 SCG1 = 1, OSCOFF = 0 (LPM3)
f_{XT1} = 32768 Hz, $f_{ACLK} = f_{MCLK} = f_{SMCLK}$ = 0 MHz
(6) RTC periodically wakes up every second with external 32768-Hz input as source.
(7) CapTIvate technology works in LPM3 with one proximity sensor for wake on touch. CapTIvate BSWP demonstration board with 1.5-mm overlay. Current for brownout included. SVS disabled (SVSHE = 0).
f_{SCAN} = 8 Hz, f_{CONVER} = 2 MHz, COUNTS = 800
(8) CapTIvate technology works in LPM3 with one button, wake on touch. CapTIvate BSWP demonstration board with 1.5-mm overlay, Current for brownout included. SVS disabled (SVSHE = 0).
f_{SCAN} = 8 Hz, f_{CONVER} = 2 MHz, COUNTS = 250
(9) CapTIvate technology works in LPM3 with four self-capacitance buttons, wake on touch. CapTIvate BSWP demonstration board with 1.5-mm overlay. Current for brownout included. SVS disabled (SVSHE = 0).
f_{SCAN} = 8 Hz, f_{CONVER} = 2 MHz, COUNTS = 250
(10) CapTIvate technology works in LPM3 with 16 self-capacitance buttons. The CPU enters active mode between time cycles to configure the conversions and read the results. CapTIvate BSWP demonstration board with 1.5-mm overlay. Current for brownout included. SVS disabled (SVSHE = 0).
f_{SCAN} = 8 Hz, f_{CONVER} = 2 MHz, COUNTS = 250
(11) CapTIvate technology works in LPM3 with 64 mutual-capacitance buttons. The CPU enters active mode between time cycles to configure the conversions and read the results. TIDM-CAPTIVATE-64-BUTTON 64-Button Capacitive Touch Panel. Current for brownout included. SVS disabled (SVSHE = 0).
f_{SCAN} = 8 Hz, f_{CONVER} = 4 MHz, COUNTS = 250
(12) CapTIvate technology works in LPM4 with one proximity sensor for wake on touch. CapTIvate BSWP demonstration board with 1.5-mm overlay. Current for brownout included. SVS disabled (SVSHE = 0). VLO (10 kHz) sources to CapTIvate timer, no external crystal.
f_{SCAN} = 8 Hz, f_{CONVER} = 2 MHz, COUNTS = 800

Copyright © 2015–2019, Texas Instruments Incorporated

Low-Power Mode (LPM3 and LPM4) Supply Currents (Into V_{CC}) Excluding External Current *(continued)*

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (1)

PARAMETER		V_{CC}	–40°C		25°C		85°C		UNIT
			TYP	MAX	TYP	MAX	TYP	MAX	
$I_{LPM4, CapTIvate, 1 button, wake on touch}$	Low-power mode 4, CapTIvate, excludes SVS(13)	3 V			2.7				µA
$I_{LPM4, CapTIvate, 4 buttons, wake on touch}$	Low-power mode 4, CapTIvate, excludes SVS(14)	3 V			3.0				µA

(13) CapTIvate technology works in LPM4 with one button, wake on touch. CapTIvate BSWP demonstration board with 1.5-mm overlay, Current for brownout included. SVS disabled (SVSHE = 0). VLO (10 kHz) sources to CapTIvate timer, no external crystal.
f_{SCAN} = 8 Hz, f_{CONVER} = 2 MHz, COUNTS = 250

(14) CapTIvate technology works in LPM4 with four self-capacitance buttons, wake on touch. CapTIvate BSWP demonstration board with 1.5-mm overlay. Current for brownout included. SVS disabled (SVSHE = 0). VLO (10 kHz) sources to CapTIvate timer, no external crystal.
f_{SCAN} = 8 Hz, f_{CONVER} = 2 MHz, COUNTS = 250

5.8 Low-Power Mode LPMx.5 Supply Currents (Into V_{CC}) Excluding External Current

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		V_{CC}	–40°C		25°C		85°C		UNIT
			TYP	MAX	TYP	MAX	TYP	MAX	
$I_{LPM3.5, XT1}$	Low-power mode 3.5, 12.5-pF crystal, includes SVS(1)(2)(3) (see Figure 5-2)	3 V	0.65		0.73	0.95	0.99	1.42	µA
		2 V	0.63		0.71		0.87		
$I_{LPM4.5, SVS}$	Low-power mode 4.5, includes SVS(4) (see Figure 5-3)	3 V	0.22		0.24	0.31	0.30	0.38	µA
		2 V	0.21		0.23		0.28		
$I_{LPM4.5}$	Low-power mode 4.5, excludes SVS(5)	3 V	0.012		0.016	0.055	0.061	0.120	µA
		2 V	0.002		0.007		0.044		

(1) Not applicable for MCUs with HF crystal oscillator only.
(2) Characterized with a Micro Crystal MS1V-T1K crystal with a load capacitance of 12.5 pF. The internal and external load capacitance are chosen to closely match the required 12.5-pF load.
(3) Low-power mode 3.5, 12.5-pF crystal, includes SVS test conditions:
Current for RTC clocked by XT1 included. Current for brownout and SVS included (SVSHE = 1). Core regulator disabled.
PMMREGOFF = 1, CPUOFF = 1, SCG0 = 1 SCG1 = 1, OSCOFF = 1 (LPMx.5),
f_{XT1} = 32768 Hz, f_{ACLK} = 0, f_{MCLK} = f_{SMCLK} = 0 MHz
(4) Low-power mode 4.5, includes SVS test conditions:
Current for brownout and SVS included (SVSHE = 1). Core regulator disabled.
PMMREGOFF = 1, CPUOFF = 1, SCG0 = 1 SCG1 = 1, OSCOFF = 1 (LPMx.5),
f_{XT1} = 0 Hz, f_{ACLK} = f_{MCLK} = f_{SMCLK} = 0 MHz
(5) Low-power mode 4.5, excludes SVS test conditions:
Current for brownout included. SVS disabled (SVSHE = 0). Core regulator disabled.
PMMREGOFF = 1, CPUOFF = 1, SCG0 = 1 SCG1 = 1, OSCOFF = 1 (LPMx.5),
f_{XT1} = 0 Hz, f_{ACLK} = f_{MCLK} = f_{SMCLK} = 0 MHz

Copyright © 2015–2019, Texas Instruments Incorporated

5.9 Typical Characteristics - Low-Power Mode Supply Currents

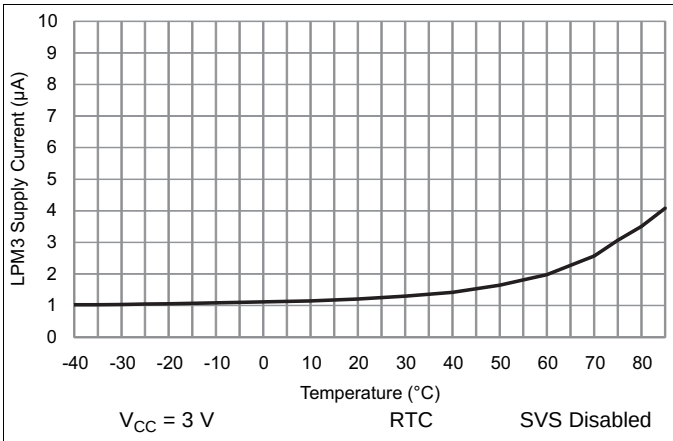


Figure 5-1. LPM3 Supply Current vs Temperature

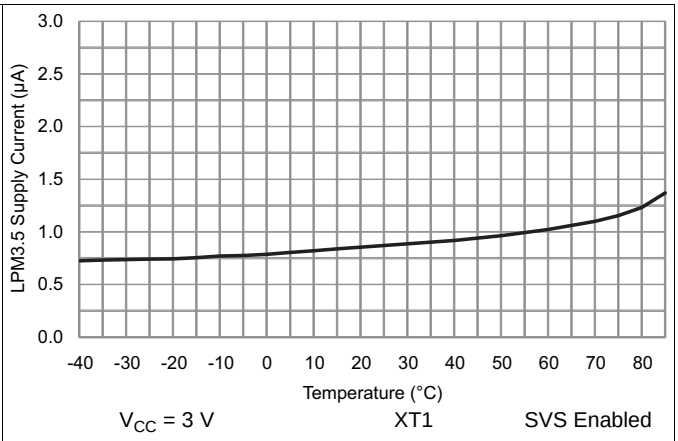


Figure 5-2. LPM3.5 Supply Current vs Temperature

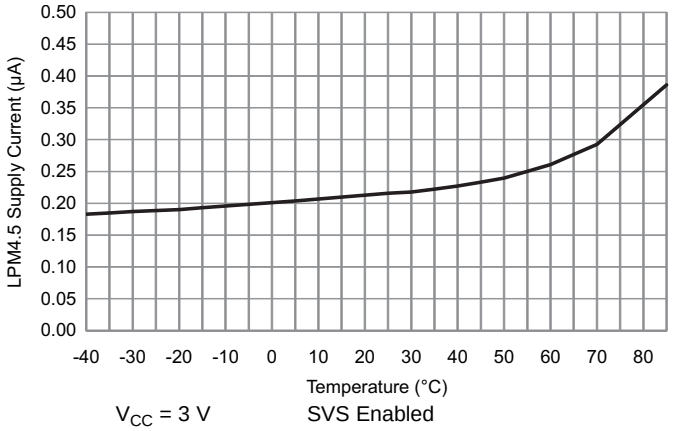


Figure 5-3. LPM4.5 Supply Current vs Temperature

Table 5-1. Typical Characteristics – Current Consumption Per Module

MODULE	TEST CONDITIONS	REFERENCE CLOCK	MIN	TYP	MAX	UNIT
Timer_A		Module input clock		5		µA/MHz
eUSCI_A	UART mode	Module input clock		7		µA/MHz
eUSCI_A	SPI mode	Module input clock		5		µA/MHz
eUSCI_B	SPI mode	Module input clock		5		µA/MHz
eUSCI_B	I^2C mode, 100 kbaud	Module input clock		5		µA/MHz
RTC		32 kHz		85		nA
CRC	From start to end of operation	MCLK		8.5		µA/MHz

Copyright © 2015–2019, Texas Instruments Incorporated

5.10 Thermal Resistance Characteristics

THERMAL METRIC[1]			VALUE[2]	UNIT
$R\theta_{JA}$	Junction-to-ambient thermal resistance, still air	VQFN 32 pin (RHB)	33.5	°C/W
		TSSOP 32 pin (DA)	69.4	
		VQFN 24 pin (RGE)	32.6	
		DSBGA 24 pin (YQW)	63.7	
$R\theta_{JC(top)}$	Junction-to-case (top) thermal resistance	VQFN 32 pin (RHB)	25.7	°C/W
		TSSOP 32 pin (DA)	18.1	
		VQFN 24 pin (RGE)	32.4	
		DSBGA 24 pin (YQW)	0.3	
$R\theta_{JB}$	Junction-to-board thermal resistance	VQFN 32 pin (RHB)	7.6	°C/W
		TSSOP 32 pin (DA)	33.1	
		VQFN 24 pin (RGE)	10.1	
		DSBGA 24 pin (YQW)	9.2	

(1) For more information about traditional and new thermal metrics, see *Semiconductor and IC Package Thermal Metrics*.
(2) These values are based on a JEDEC-defined 2S2P system (with the exception of the Theta JC ($R\theta_{JC}$) value, which is based on a JEDEC-defined 1S0P system) and will change based on environment and application. For more information, see these EIA/JEDEC standards:
- JESD51-2, *Integrated Circuits Thermal Test Method Environmental Conditions - Natural Convection (Still Air)*
- JESD51-3, *Low Effective Thermal Conductivity Test Board for Leaded Surface Mount Packages*
- JESD51-7, *High Effective Thermal Conductivity Test Board for Leaded Surface Mount Packages*
- JESD51-9, *Test Boards for Area Array Surface Mount Package Thermal Measurements*

Copyright © 2015–2019, Texas Instruments Incorporated

5.11 Timing and Switching Characteristics

5.11.1 Power Supply Sequencing

Table 5-2 lists the characteristics of the SVS and BOR.

Table 5-2. PMM, SVS and BOR

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Figure 5-4)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{BOR, safe}$	Safe BOR power-down level(1)		0.1			V
$t_{BOR, safe}$	Safe BOR reset delay(2)		10			ms
$I_{SVSH,AM}$	SVS_H current consumption, active mode	V_{CC} = 3.6 V			1.5	µA
$I_{SVSH,LPM}$	SVS_H current consumption, low-power modes	V_{CC} = 3.6 V		240		nA
V_{SVSH-}	SVS_H power-down level(3)		1.71	1.80	1.86	V
V_{SVSH+}	SVS_H power-up level(3)		1.74	1.89	1.99	V
V_{SVSH_hys}	SVS_H hysteresis			80		mV
$t_{PD,SVSH, AM}$	SVS_H propagation delay, active mode				10	µs
$t_{PD,SVSH, LPM}$	SVS_H propagation delay, low-power modes				100	µs
$V_{REF, 1.2V}$	1.2-V REF voltage(4)		1.158	1.20	1.242	V

(1) A safe BOR can be correctly generated only if DVCC drops below this voltage before it rises.
(2) When an BOR occurs, a safe BOR can be correctly generated only if DVCC is kept low longer than this period before it reaches V_{SVSH+}.
(3) For additional information, see the Dynamic Voltage Scaling Power Solution for MSP430 Devices With Single-Channel LDO Reference Design.
(4) This is a characterized result with external 1-mA load to ground from –40°C to 85°C.

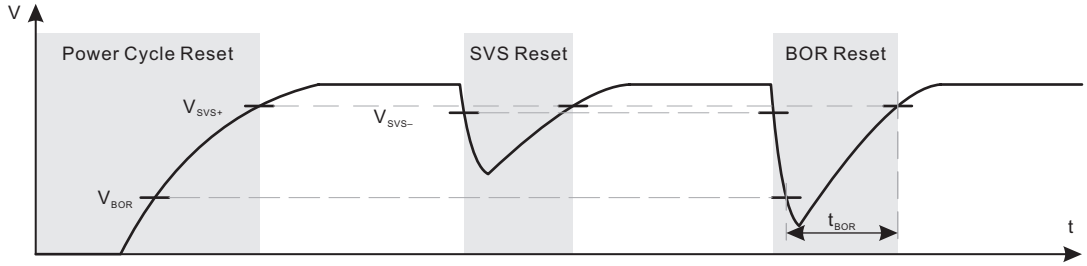


Figure 5-4. Power Cycle, SVS, and BOR Reset Conditions

5.11.2 Reset Timing

Table 5-3 lists the wake-up times.

Table 5-3. Wake-up Times From Low-Power Modes and Reset

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	TYP	MAX	UNIT
$t_{WAKE-UP\ FRAM}$	Additional wake-up time to activate the FRAM in AM if previously disabled by the FRAM controller or from a LPM if immediate activation is selected for wakeup (1)		3 V		10		µs
$t_{WAKE-UP\ LPM0}$	Wake-up time from LPM0 to active mode (1)		3 V			200 + 2.5 / f_{DCO}	ns
$t_{WAKE-UP\ LPM3}$	Wake-up time from LPM3 to active mode (2)		3 V		10		µs
$t_{WAKE-UP\ LPM4}$	Wake-up time from LPM4 to active mode		3 V		10		µs
$t_{WAKE-UP\ LPM3.5}$	Wake-up time from LPM3.5 to active mode (2)		3 V		350		µs
$t_{WAKE-UP\ LPM4.5}$	Wake-up time from LPM4.5 to active mode (2)	SVSHE = 1	3 V		350		µs
		SVSHE = 0			1		ms
$t_{WAKE-UP-RESET}$	Wake-up time from $\overline{RST}$ or BOR event to active mode (2)		3 V		1		ms
t_{RESET}	Pulse duration required at $\overline{RST}$/NMI pin to accept a reset		3 V	2			µs

(1) The wake-up time is measured from the edge of an external wake-up signal (for example, port interrupt or wake-up event) to the first externally observable MCLK clock edge.
(2) The wake-up time is measured from the edge of an external wake-up signal (for example, port interrupt or wake-up event) until the first instruction of the user program is executed.

Copyright © 2015–2019, Texas Instruments Incorporated

5.11.3 Clock Specifications

Table 5-4 lists the characteristics of XT1.

Table 5-4. XT1 Crystal Oscillator (Low Frequency)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)(1)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	TYP	MAX	UNIT
$f_{XT1,\ LF}$	XT1 oscillator crystal, low frequency	LFXTBYPASS = 0			32768		Hz
$DC_{XT1,\ LF}$	XT1 oscillator LF duty cycle	Measured at MCLK, f_{LFXT} = 32768 Hz		30%		70%	
$f_{XT1,SW}$	XT1 oscillator logic-level square-wave input frequency	LFXTBYPASS = 1 (2)(3)			32.768		kHz
$DC_{XT1,\ SW}$	LFXT oscillator logic-level square-wave input duty cycle	LFXTBYPASS = 1		40%		60%	
OA_{LFXT}	Oscillation allowance for LF crystals (4)	LFXTBYPASS = 0, LFXTDRIVE = {3}, f_{LFXT} = 32768 Hz, $C_{L,eff}$ = 12.5 pF			200		kΩ
$C_{L,eff}$	Integrated effective load capacitance(5)	See (6)			1		pF
$t_{START,LFXT}$	Start-up time (7)	f_{OSC} = 32768 Hz, LFXTBYPASS = 0, LFXTDRIVE = {3}, T_A = 25°C, $C_{L,eff}$ = 12.5 pF			1000		ms
$f_{Fault,LFXT}$	Oscillator fault frequency (8)	XTS = 0(9)		0		3500	Hz

(1) To improve EMI on the LFXT oscillator, observe the following guidelines:
- Keep the trace between the device and the crystal as short as possible.
- Design a good ground plane around the oscillator pins.
- Prevent crosstalk from other clock or data lines into oscillator pins XIN and XOUT.
- Avoid running PCB traces underneath or adjacent to the XIN and XOUT pins.
- Use assembly materials and processes that avoid any parasitic load on the oscillator XIN and XOUT pins.
- If conformal coating is used, make sure that it does not induce capacitive or resistive leakage between the oscillator pins.

(2) When LFXTBYPASS is set, LFXT circuits are automatically powered down. Input signal is a digital square wave with parametrics defined in the Schmitt-trigger inputs section of this data sheet. Duty cycle requirements are defined by $DC_{LFXT,\ SW}$.

(3) Maximum frequency of operation of the entire device cannot be exceeded.

(4) Oscillation allowance is based on a safety factor of 5 for recommended crystals. The oscillation allowance is a function of the LFXTDRIVE settings and the effective load. In general, comparable oscillator allowance can be achieved based on the following guidelines, but should be evaluated based on the actual crystal selected for the application:
- For LFXTDRIVE = {0}, $C_{L,eff}$ = 3.7 pF
- For LFXTDRIVE = {1}, 6 pF ≤ $C_{L,eff}$ ≤ 9 pF
- For LFXTDRIVE = {2}, 6 pF ≤ $C_{L,eff}$ ≤ 10 pF
- For LFXTDRIVE = {3}, 6 pF ≤ $C_{L,eff}$ ≤ 12 pF

(5) Includes parasitic bond and package capacitance (approximately 2 pF per pin).

(6) Requires external capacitors at both terminals to meet the effective load capacitance specified by crystal manufacturers. Recommended effective load capacitance values supported are 3.7 pF, 6 pF, 9 pF, and 12.5 pF. Maximum shunt capacitance of 1.6 pF. The PCB adds additional capacitance, so it must also be considered in the overall capacitance. Verify that the recommended effective load capacitance of the selected crystal is met.

(7) Includes start-up counter of 1024 clock cycles.

(8) Frequencies above the MAX specification do not set the fault flag. Frequencies between the MIN and MAX specifications might set the flag. A static condition or stuck at fault condition sets the flag.

(9) Measured with logic-level input frequency but also applies to operation with crystals.

Table 5-5 lists the characteristics of the FLL.

Table 5-5. DCO FLL, Frequency

over recommended operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	TYP	MAX	UNIT
$f_{DCO,\ FLL}$	FLL lock frequency, 16 MHz, 25°C	Measured at MCLK, Internal trimmed REFO as reference	3 V	–1.0%		1.0%	
	FLL lock frequency, 16 MHz, –40°C to 85°C		3 V	–2.0%		2.0%	
	FLL lock frequency, 16 MHz, –40°C to 85°C	Measured at MCLK, XT1 crystal as reference	3 V	–0.5%		0.5%	

Copyright © 2015–2019, Texas Instruments Incorporated

Table 5-5. DCO FLL, Frequency (continued)

over recommended operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	TYP	MAX	UNIT
f_{DUTY}	Duty cycle	Measured at MCLK, XT1 crystal as reference	3 V	40%	50%	60%	
$Jitter_{cc}$	Cycle-to-cycle jitter, 16 MHz		3 V		0.25%		
$Jitter_{long}$	Long term jitter, 16 MHz		3 V		0.022%		
$t_{FLL, lock}$	FLL lock time		3 V		280		ms
$t_{start-up}$	DCO start-up time, 2 MHz	Measured at MCLK	3 V		16		µs

Table 5-6 lists the characteristics of the DCO.

Table 5-6. DCO Frequency

over recommended operating free-air temperature (unless otherwise noted) (also see Figure 5-5)

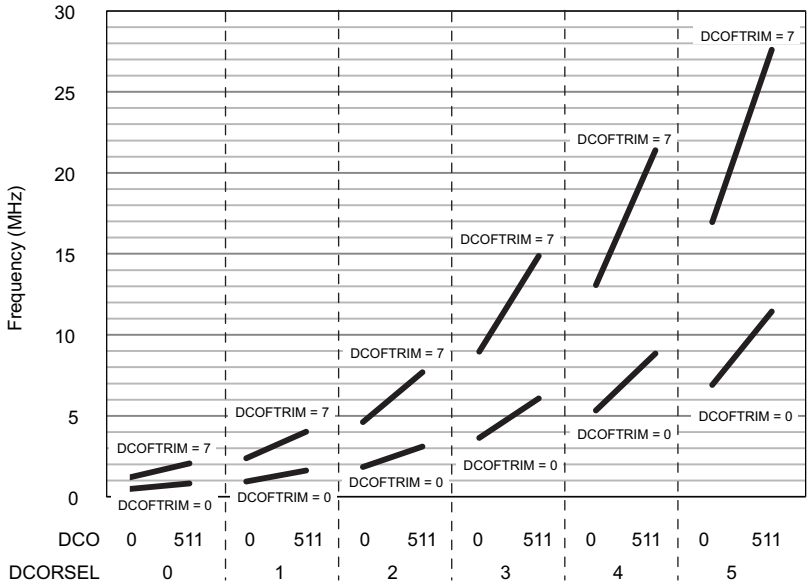
PARAMETER		TEST CONDITIONS	V_{CC}	TYP	UNIT
$f_{DCO, 16MHz}$	DCO frequency, 16 MHz	DCORSEL = 101b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 000b, DCO = 0	3 V	7.46	MHz
		DCORSEL = 101b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 000b, DCO = 511		12.26	
		DCORSEL = 101b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 111b, DCO = 0		17.93	
		DCORSEL = 101b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 111b, DCO = 511		29.1	
$f_{DCO, 12MHz}$	DCO frequency, 12 MHz	DCORSEL = 100b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 000b, DCO = 0	3 V	5.75	MHz
		DCORSEL = 100b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 000b, DCO = 511		9.5	
		DCORSEL = 100b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 111b, DCO = 0		13.85	
		DCORSEL = 100b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 111b, DCO = 511		22.5	
$f_{DCO, 8MHz}$	DCO frequency, 8 MHz	DCORSEL = 011b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 000b, DCO = 0	3 V	3.91	MHz
		DCORSEL = 011b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 000b, DCO = 511		6.49	
		DCORSEL = 011b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 111b, DCO = 0		9.5	
		DCORSEL = 011b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 111b, DCO = 511		15.6	
$f_{DCO, 4MHz}$	DCO frequency, 4 MHz	DCORSEL = 010b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 000b, DCO = 0	3 V	2.026	MHz
		DCORSEL = 010b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 000b, DCO = 511		3.407	
		DCORSEL = 010b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 111b, DCO = 0		4.95	
		DCORSEL = 010b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 111b, DCO = 511		8.26	
$f_{DCO, 2MHz}$	DCO frequency, 2 MHz	DCORSEL = 001b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 000b, DCO = 0	3 V	1.0225	MHz
		DCORSEL = 001b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 000b, DCO = 511		1.729	
		DCORSEL = 001b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 111b, DCO = 0		2.525	
		DCORSEL = 001b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 111b, DCO = 511		4.25	

Copyright © 2015–2019, Texas Instruments Incorporated

Table 5-6. DCO Frequency (continued)

over recommended operating free-air temperature (unless otherwise noted) (also see Figure 5-5)

PARAMETER		TEST CONDITIONS	V_{CC}	TYP	UNIT
$f_{DCO, 1MHz}$	DCO frequency, 1 MHz	DCORSEL = 000b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 000b, DCO = 0	3 V	0.5319	MHz
		DCORSEL = 000b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 000b, DCO = 511		0.9029	
		DCORSEL = 000b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 111b, DCO = 0		1.307	
		DCORSEL = 000b, DISMOD = 1b, DCOFTRIMEN = 1b, DCOFTRIM = 111b, DCO = 511		2.21	



V_{CC} = 3 V T_A = –40°C to 85°C

Figure 5-5. Typical DCO Frequency

Table 5-7 lists the characteristics of the REFO.

Table 5-7. REFO

over recommended operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	TYP	MAX	UNIT
I_{REFO}	REFO oscillator current consumption	T_A = 25°C	3 V		15		µA
f_{REFO}	REFO calibrated frequency	Measured at MCLK	3 V		32768		Hz
	REFO absolute calibrated tolerance	–40°C to 85°C	1.8 V to 3.6 V	–3.5%		+3.5%	
df_{REFO}/d_T	REFO frequency temperature drift	Measured at MCLK(1)	3 V		0.01		%/°C
df_{REFO}/d_{VCC}	REFO frequency supply voltage drift	Measured at MCLK at 25°C(2)	1.8 V to 3.6 V		1		%/V
f_{DC}	REFO duty cycle	Measured at MCLK	1.8 V to 3.6 V	40%	50%	60%	
t_{START}	REFO start-up time	40% to 60% duty cycle			50		µs

(1) Calculated using the box method: (MAX(–40°C to 85°C) – MIN(–40°C to 85°C)) / MIN(–40°C to 85°C) / (85°C – (–40°C))
(2) Calculated using the box method: (MAX(1.8 V to 3.6 V) – MIN(1.8 V to 3.6 V)) / MIN(1.8 V to 3.6 V) / (3.6 V – 1.8 V)

Copyright © 2015–2019, Texas Instruments Incorporated

Table 5-8 lists the characteristics of the VLO.

NOTE

The VLO clock frequency is reduced by 15% (typical) when the device switches from active mode to LPM3 or LPM4, because the reference changes. This lower frequency is not a violation of the VLO specifications (see Table 5-8).

Table 5-8. Internal Very-Low-Power Low-Frequency Oscillator (VLO)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V_{CC}	TYP	UNIT
f_{VLO}	VLO frequency	Measured at MCLK	3 V	10	kHz
df_{VLO}/d_T	VLO frequency temperature drift	Measured at MCLK(1)	3 V	0.5	%/°C
df_{VLO}/dV_{CC}	VLO frequency supply voltage drift	Measured at MCLK(2)	2 V to 3.6 V	4	%/V
$f_{VLO,DC}$	Duty cycle	Measured at MCLK	3 V	50%	

(1) Calculated using the box method: (MAX(–40°C to 85°C) – MIN(–40°C to 85°C)) / MIN(–40°C to 85°C) / (85°C – (–40°C))
(2) Calculated using the box method: (MAX(1.8 V to 3.6 V) – MIN(1.8 V to 3.6 V)) / MIN(1.8 V to 3.6 V) / (3.6 V – 1.8 V)

Table 5-9 lists the characteristics of the MODOSC.

Table 5-9. Module Oscillator (MODOSC)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		V_{CC}	MIN	TYP	MAX	UNIT
f_{MODOSC}	MODOSC frequency	3 V	3.8	4.8	5.8	MHz
f_{MODOSC}/dT	MODOSC frequency temperature drift	3 V		0.102		%/℃
f_{MODOSC}/dV_{CC}	MODOSC frequency supply voltage drift	1.8 V to 3.6 V		1.02		%/V
$f_{MODOSC,DC}$	Duty cycle	3 V	40%	50%	60%	

Copyright © 2015–2019, Texas Instruments Incorporated

5.11.4 Digital I/Os

Table 5-10 lists the characteristics of the digital inputs.

Table 5-10. Digital Inputs

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	TYP	MAX	UNIT
V_{IT+}	Positive-going input threshold voltage		2 V	0.90		1.50	V
			3 V	1.35		2.25	
V_{IT-}	Negative-going input threshold voltage		2 V	0.50		1.10	V
			3 V	0.75		1.65	
V_{hys}	Input voltage hysteresis ($V_{IT+} - V_{IT-}$)		2 V	0.3		0.8	V
			3 V	0.4		1.2	
R_{Pull}	Pullup or pulldown resistor	For pullup: $V_{IN} = V_{SS}$ For pulldown: $V_{IN} = V_{CC}$		20	35	50	kΩ
$C_{I,dig}$	Input capacitance, digital only port pins	$V_{IN} = V_{SS}$ or V_{CC}			3		pF
$C_{I,ana}$	Input capacitance, port pins with shared analog functions	$V_{IN} = V_{SS}$ or V_{CC}			5		pF
$I_{lkg(Px.y)}$	High-impedance leakage current	See (1) (2)	2 V, 3 V	–20		20	nA
$t_{(int)}$	External interrupt timing (external trigger pulse duration to set interrupt flag)(3)	Ports with interrupt capability (see block diagram and terminal function descriptions)	2 V, 3 V	50			ns

(1) The leakage current is measured with V_{SS} or V_{CC} applied to the corresponding pins, unless otherwise noted.
(2) The leakage of the digital port pins is measured individually. The port pin is selected for input and the pullup or pulldown resistor is disabled.
(3) An external signal sets the interrupt flag every time the minimum interrupt pulse duration $t_{(int)}$ is met. It may be set by trigger signals shorter than $t_{(int)}$.

Table 5-11 lists the characteristics of the digital outputs.

Table 5-11. Digital Outputs

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (also see Figure 5-6, Figure 5-7, Figure 5-8, and Figure 5-9)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	TYP	MAX	UNIT
V_{OH}	High-level output voltage	$I_{(OHmax)}$ = –3 mA(1)	2 V	1.4		2.0	V
		$I_{(OHmax)}$ = –5 mA(1)	3 V	2.4		3.0	
V_{OL}	Low-level output voltage	$I_{(OLmax)}$ = 3 mA(1)	2 V	0.0		0.60	V
		$I_{(OHmax)}$ = 5 mA(1)	3 V	0.0		0.60	
f_{Port_CLK}	Clock output frequency	C_L = 20 pF(2)	2 V	16			MHz
			3 V	16			
$t_{rise,dig}$	Port output rise time, digital only port pins	C_L = 20 pF	2 V		10		ns
			3 V		7		
$t_{fall,dig}$	Port output fall time, digital only port pins	C_L = 20 pF	2 V		10		ns
			3 V		5		

(1) The maximum total current, $I_{(OHmax)}$ and $I_{(OLmax)}$, for all outputs combined should not exceed ±48 mA to hold the maximum voltage drop specified.
(2) The port can output frequencies at least up to the specified limit and might support higher frequencies.

Copyright © 2015–2019, Texas Instruments Incorporated

5.11.4.1 Typical Characteristics – Outputs at 3 V and 2 V

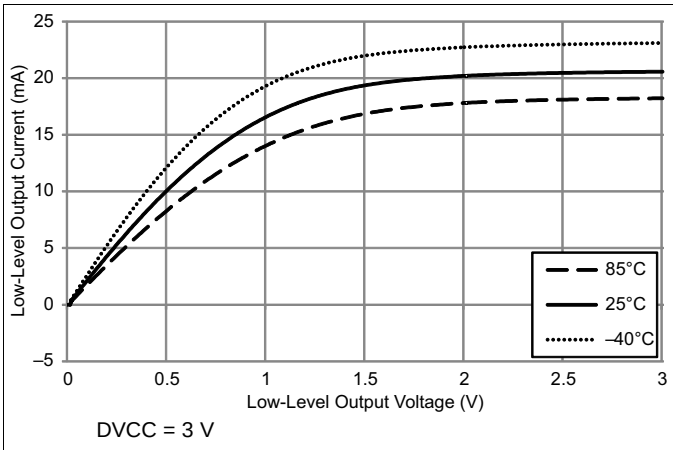


Figure 5-6. Typical Low-Level Output Current vs Low-Level Output Voltage

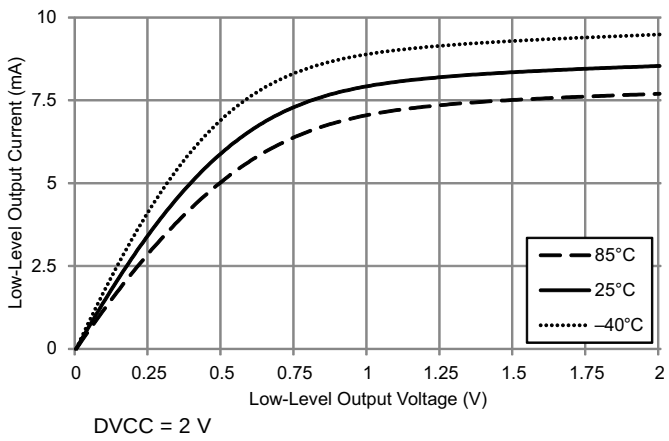


Figure 5-7. Typical Low-Level Output Current vs Low-Level Output Voltage

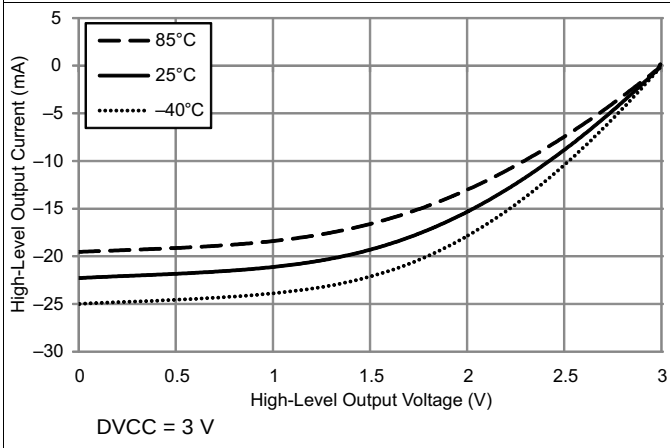


Figure 5-8. Typical High-Level Output Current vs High-Level Output Voltage

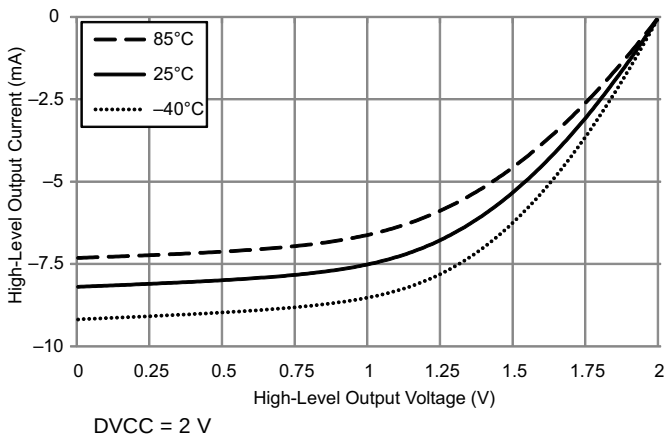


Figure 5-9. Typical High-Level Output Current vs High-Level Output Voltage

Copyright © 2015–2019, Texas Instruments Incorporated

5.11.5 VREF+ Built-in Reference

Table 5-12 lists the characteristics of VREF+.

Table 5-12. VREF+

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	TYP	MAX	UNIT
V_{REF+}	Positive built-in reference voltage	EXTREFEN = 1 with 1-mA load current	2 V, 3 V	1.15	1.19	1.23	V
TC_{REF+}	Temperature coefficient of built-in reference voltage				30		µV/°C

5.11.6 Timer_A

Table 5-13 lists the characteristics of Timer_A.

Table 5-13. Timer_A

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Figure 5-10 and Figure 5-11)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	TYP	MAX	UNIT
f_{TA}	Timer_A input clock frequency	Internal: SMCLK or ACLK, External: TACLK, duty cycle = 50% ±10%	2 V, 3 V			16	MHz
$t_{TA,cap}$	Timer_A capture timing	All capture inputs, minimum pulse duration required for capture	2 V, 3 V	20			ns

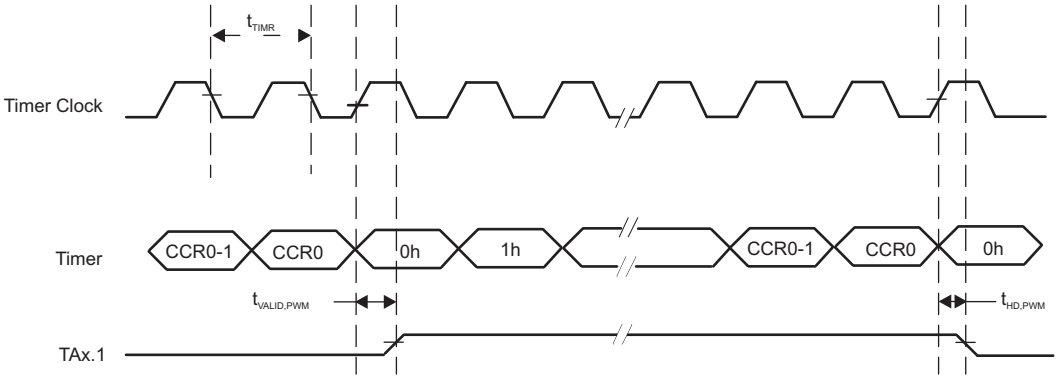


Figure 5-10. Timer PWM Mode

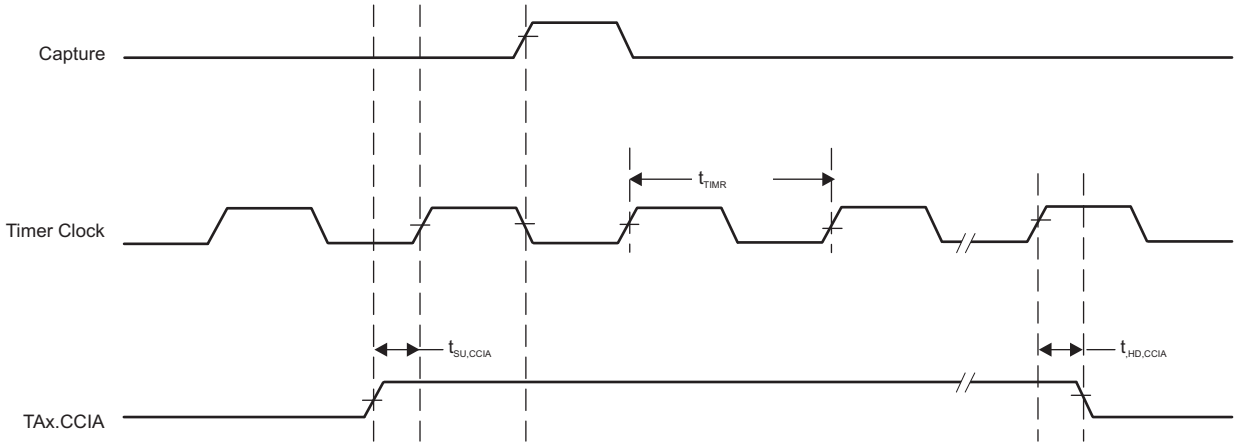


Figure 5-11. Timer Capture Mode

5.11.7 eUSCI

Table 5-14 lists the supported frequencies of the eUSCI in UART mode.

Table 5-14. eUSCI (UART Mode) Clock Frequency

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	MAX	UNIT
f_{eUSCI}	eUSCI input clock frequency	Internal: SMCLK or MODCLK, External: UCLK, duty cycle = 50% ±10%	2 V, 3 V		16	MHz
f_{BITCLK}	BITCLK clock frequency (equals baud rate in Mbaud)		2 V, 3 V		5	MHz

Table 5-15 lists the characteristics of the eUSCI in UART mode.

Table 5-15. eUSCI (UART Mode)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V_{CC}	TYP	UNIT
t_t	UART receive deglitch time (1)	UCGLITx = 0	2 V, 3 V	12	ns
		UCGLITx = 1		40	
		UCGLITx = 2		68	
		UCGLITx = 3		110	

(1) Pulses on the UART receive input (UCxRX) shorter than the UART receive deglitch time are suppressed. To ensure that pulses are correctly recognized, their duration should exceed the maximum specification of the deglitch time.

Table 5-16 lists the supported frequencies of the eUSCI in SPI master mode.

Table 5-16. eUSCI (SPI Master Mode) Clock Frequency

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	MAX	UNIT
f_{eUSCI}	eUSCI input clock frequency	Internal: SMCLK or MODCLK, duty cycle = 50% ±10%		8	MHz

Table 5-17 lists the characteristics of the eUSCI in SPI master mode.

Table 5-17. eUSCI (SPI Master Mode)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (1)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	MAX	UNIT
$t_{STE,LEAD}$	STE lead time, STE active to clock	UCSTEM = 0, UCMODEx = 01 or 10		1		UCxCLK cycles
		UCSTEM = 1, UCMODEx = 01 or 10				
$t_{STE,LAG}$	STE lag time, last clock to STE inactive	UCSTEM = 0, UCMODEx = 01 or 10		1		UCxCLK cycles
		UCSTEM = 1, UCMODEx = 01 or 10				
$t_{SU,MI}$	SOMI input data setup time		2 V	45		ns
			3 V	35		
$t_{HD,MI}$	SOMI input data hold time		2 V	0		ns
			3 V	0		
$t_{VALID,MO}$	SIMO output data valid time (2)	UCLK edge to SIMO valid, C_L = 20 pF	2 V		20	ns
			3 V		20	
$t_{HD,MO}$	SIMO output data hold time (3)	C_L = 20 pF	2 V	0		ns
			3 V	0		

(1) $f_{UCxCLK} = 1 / 2t_{LO/HI}$ with $t_{LO/HI} = \max(t_{VALID,MO(eUSCI)} + t_{SU,SI(Slave)}, t_{SU,MI(eUSCI)} + t_{VALID,SO(Slave)})$
For the slave parameters $t_{SU,SI(Slave)}$ and $t_{VALID,SO(Slave)}$, see the SPI parameters of the attached slave.
(2) Specifies the time to drive the next valid data to the SIMO output after the output changing UCLK clock edge. See the timing diagrams in Figure 5-12 and Figure 5-13.
(3) Specifies how long data on the SIMO output is valid after the output changing UCLK clock edge. Negative values indicate that the data on the SIMO output can become invalid before the output changing clock edge observed on UCLK. See the timing diagrams in Figure 5-12 and Figure 5-13.

Copyright © 2015–2019, Texas Instruments Incorporated

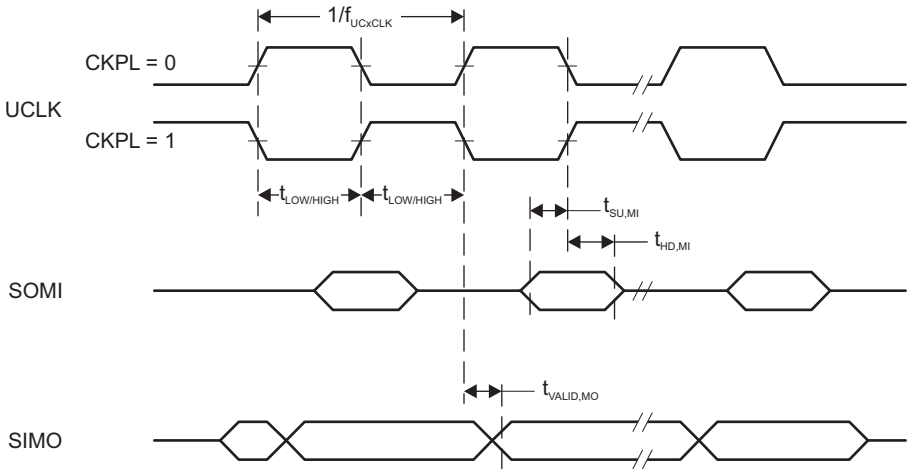


Figure 5-12. SPI Master Mode, CKPH = 0

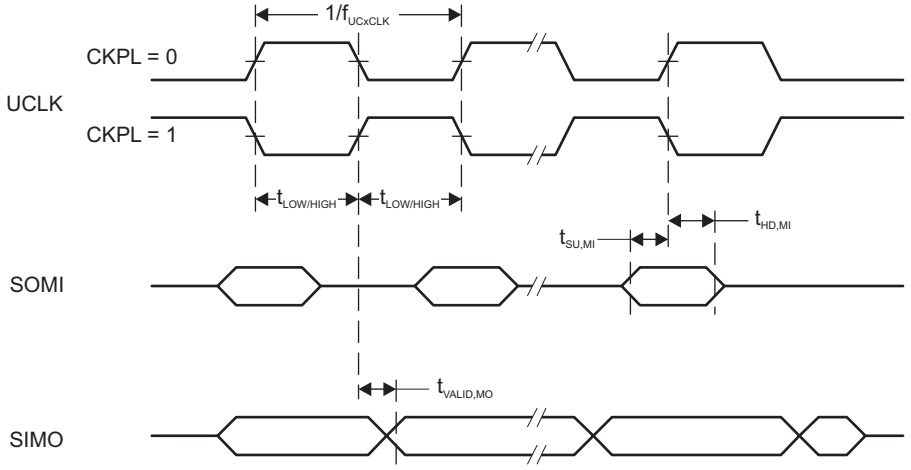


Figure 5-13. SPI Master Mode, CKPH = 1

Table 5-18 lists the characteristics of the eUSCI in SPI slave mode.

Table 5-18. eUSCI (SPI Slave Mode)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)(1)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	MAX	UNIT
$t_{STE,LEAD}$	STE lead time, STE active to clock		2 V	55		ns
			3 V	45		
$t_{STE,LAG}$	STE lag time, Last clock to STE inactive		2 V	20		ns
			3 V	20		
$t_{STE,ACC}$	STE access time, STE active to SOMI data out		2 V		65	ns
			3 V		40	
$t_{STE,DIS}$	STE disable time, STE inactive to SOMI high impedance		2 V		40	ns
			3 V		35	
$t_{SU,SI}$	SIMO input data setup time		2 V	6		ns
			3 V	4		
$t_{HD,SI}$	SIMO input data hold time		2 V	12		ns
			3 V	12		
$t_{VALID,SO}$	SOMI output data valid time(2)	UCLK edge to SOMI valid, C_L = 20 pF	2 V		65	ns
			3 V		40	
$t_{HD,SO}$	SOMI output data hold time (3)	C_L = 20 pF	2 V	5		ns
			3 V	5		

(1) $f_{UCxCLK} = 1/2t_{LO/HI}$ with $t_{LO/HI} \geq \max(t_{VALID,MO(Master)} + t_{SU,SI(eUSCI)}, t_{SU,MI(Master)} + t_{VALID,SO(eUSCI)})$
For the master parameters $t_{SU,MI(Master)}$ and $t_{VALID,MO(Master)}$, see the SPI parameters of the attached master.
(2) Specifies the time to drive the next valid data to the SOMI output after the output changing UCLK clock edge. See the timing diagrams in Figure 5-14 and Figure 5-15.
(3) Specifies how long data on the SOMI output is valid after the output changing UCLK clock edge. See the timing diagrams in Figure 5-14 and Figure 5-15.

Copyright © 2015–2019, Texas Instruments Incorporated

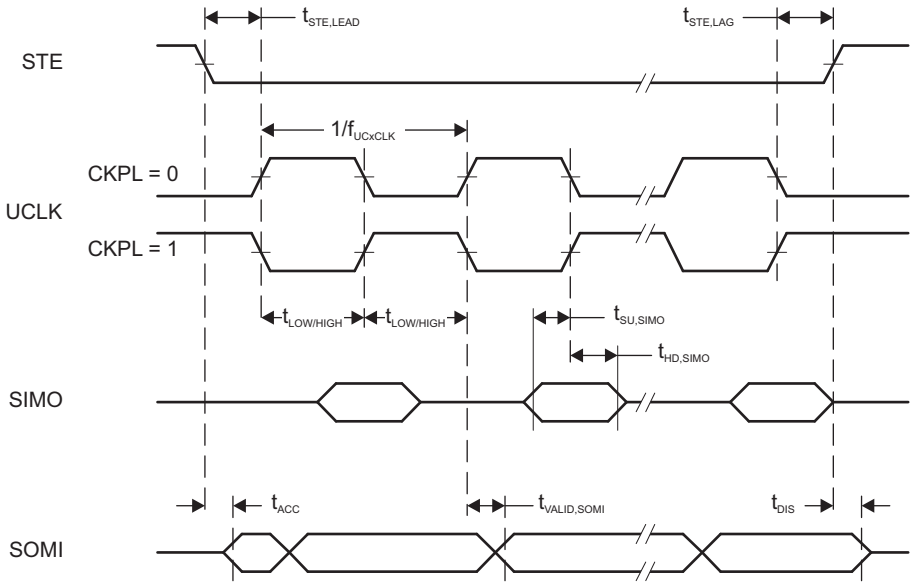


Figure 5-14. SPI Slave Mode, CKPH = 0

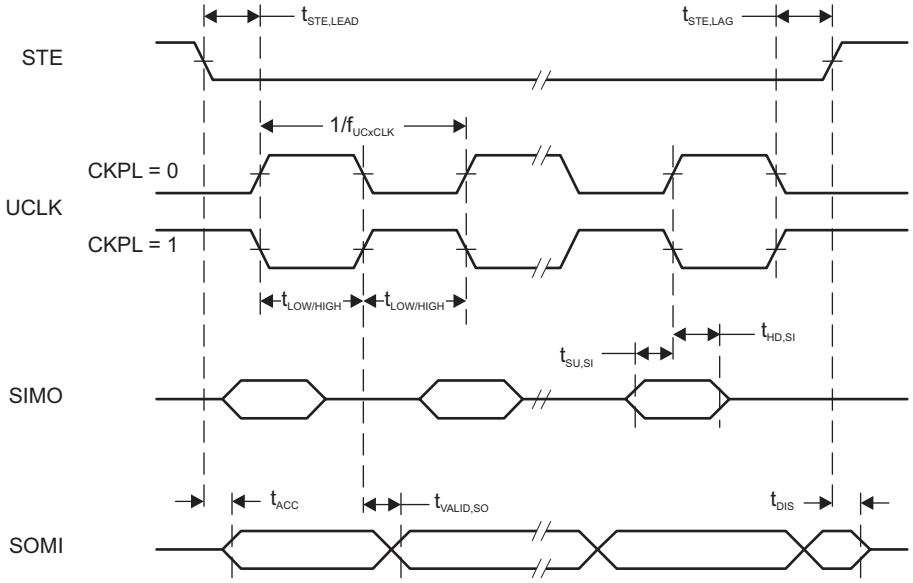


Figure 5-15. SPI Slave Mode, CKPH = 1

Table 5-19 lists the characteristics of the eUSCI in I²C mode.

Table 5-19. eUSCI (I²C Mode)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Figure 5-16)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	TYP	MAX	UNIT
f_{eUSCI}	eUSCI input clock frequency	Internal: SMCLK or MODCLK, External: UCLK Duty cycle = 50% ±10%				16	MHz
f_{SCL}	SCL clock frequency		2 V, 3 V	0		400	kHz
$t_{HD,STA}$	Hold time (repeated) START	f_{SCL} = 100 kHz	2 V, 3 V	4.0			µs
		f_{SCL} > 100 kHz		0.6			
$t_{SU,STA}$	Setup time for a repeated START	f_{SCL} = 100 kHz	2 V, 3 V	4.7			µs
		f_{SCL} > 100 kHz		0.6			
$t_{HD,DAT}$	Data hold time		2 V, 3 V	0			ns
$t_{SU,DAT}$	Data setup time		2 V, 3 V	250			ns
$t_{SU,STO}$	Setup time for STOP	f_{SCL} = 100 kHz	2 V, 3 V	4.0			µs
		f_{SCL} > 100 kHz		0.6			
t_{SP}	Pulse duration of spikes suppressed by input filter	UCGLITx = 0	2 V, 3 V	50		600	ns
		UCGLITx = 1		25		300	
		UCGLITx = 2		12.5		150	
		UCGLITx = 3		6.3		75	
$t_{TIMEOUT}$	Clock low time-out	UCCLTOx = 1	2 V, 3 V		27		ms
		UCCLTOx = 2			30		
		UCCLTOx = 3			33		

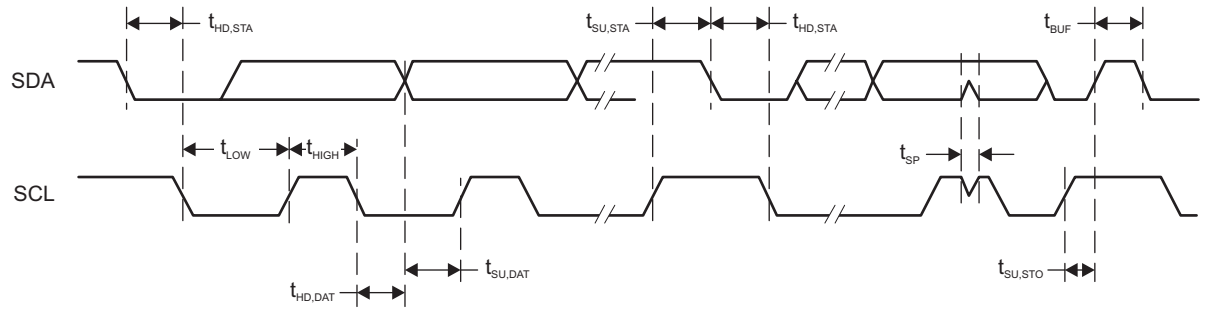


Figure 5-16. I²C Mode Timing

Copyright © 2015–2019, Texas Instruments Incorporated

5.11.8 ADC

Table 5-20 lists the input requirements of the ADC.

Table 5-20. ADC, Power Supply and Input Range Conditions

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	TYP	MAX	UNIT
DV_{CC}	ADC supply voltage			2.0		3.6	V
$V_{(Ax)}$	Analog input voltage range	All ADC pins		0		DV_{CC}	V
I_{ADC}	Operating supply current into DVCC terminal, reference current not included, repeat-single-channel mode	f_{ADCCLK} = 5 MHz, ADCON = 1, REFON = 0, SHT0 = 0, SHT1 = 0, ADCDIV = 0, ADCCONSEQx = 10b	2 V		185		µA
			3 V		207		
C_I	Input capacitance	Only one terminal Ax can be selected at one time, from the pad to the ADC capacitor array, including wiring and pad	2.2 V		1.6	2.0	pF
$R_{I,MUX}$	Input MUX ON resistance	DV_{CC} = 2 V, 0 V ≤ V_{Ax} ≤ DV_{CC}				2	kΩ
$R_{I,Misc}$	Input miscellaneous resistance				34		kΩ

Table 5-21 lists the timing parameters of the ADC.

Table 5-21. ADC, 10-Bit Timing Parameters

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	TYP	MAX	UNIT
f_{ADCCLK}		For specified performance of ADC linearity parameters	2 V to 3.6 V	0.45	5	5.5	MHz
f_{ADCOSC}	Internal ADC oscillator (MODOSC)	ADCDIV = 0, f_{ADCCLK} = f_{ADCOSC}	2 V to 3.6 V	4.5	5.0	5.5	MHz
$t_{CONVERT}$	Conversion time	REFON = 0, Internal oscillator, 10 ADCCLK cycles, 10-bit mode, f_{ADCOSC} = 4.5 MHz to 5.5 MHz	2 V to 3.6 V	2.18		2.67	µs
		External f_{ADCCLK} from ACLK or SMCLK, ADCSSEL ≠ 0	2 V to 3.6 V		12 × 1 / f_{ADCCLK}		
t_{ADCON}	Turnon settling time of the ADC	The error in a conversion started after t_{ADCON} is less than ±0.5 LSB, Reference and input signal already settled				100	ns
t_{Sample}	Sampling time	R_S = 1000 Ω, R_I (1) = 36000 Ω, C_I = 3.5 pF, Approximately 8 Tau (t) are required for an error of less than ±0.5 LSB (2)	2 V	1.5			µs
			3 V	2.0			

(1) $R_I = R_{I,MUX} + R_{I,Misc}$
(2) $t_{Sample} = \ln(2^{n+1}) \times \tau$, where n = ADC resolution, $\tau = (R_I + R_S) \times C_I$

Table 5-22 lists the linearity parameters of the ADC.

Table 5-22. ADC, 10-Bit Linearity Parameters

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	TYP	MAX	UNIT
E_I	Integral linearity error (10-bit mode)	V_{eref+} as reference	2.4 V to 3.6 V	–2		2	LSB
	Integral linearity error (8-bit mode)		2 V to 3.6 V	–2		2	
E_D	Differential linearity error (10-bit mode)	V_{eref+} as reference	2.4 V to 3.6 V	–1		1	LSB
	Differential linearity error (8-bit mode)		2 V to 3.6 V	–1		1	
E_O	Offset error (10-bit mode)	V_{eref+} as reference	2.4 V to 3.6 V	–6.5		6.5	mV
	Offset error (8-bit mode)		2 V to 3.6 V	–6.5		6.5	
E_G	Gain error (10-bit mode)	V_{eref+} as reference	2.4 V to 3.6 V	–2.0		2.0	LSB
		Internal 1.5-V reference		–3.0%		3.0%	
	Gain error (8-bit mode)	V_{eref+} as reference	2 V to 3.6 V	–2.0		2.0	LSB
		Internal 1.5-V reference		–3.0%		3.0%	
E_T	Total unadjusted error (10-bit mode)	V_{eref+} as reference	2.4 V to 3.6 V	–2.0		2.0	LSB
		Internal 1.5-V reference		–3.0%		3.0%	
	Total unadjusted error (8-bit mode)	V_{eref+} as reference	2 V to 3.6 V	–2.0		2.0	LSB
		Internal 1.5-V reference		–3.0%		3.0%	
V_{SENSOR}	See (1)	ADCON = 1, INCH = 0Ch, T_A = 0°C	3 V		913		mV
TC_{SENSOR}	See (2)	ADCON = 1, INCH = 0Ch	3 V		3.35		mV/°C
t_{SENSOR} (sample)	Sample time required if channel 12 is selected (3)	ADCON = 1, INCH = 0Ch, Error of conversion result ≤1 LSB, AM and all LPMs above LPM3	3 V	30			µs
		ADCON = 1, INCH = 0Ch, Error of conversion result ≤1 LSB, LPM3	3 V	100			

(1) The temperature sensor offset can vary significantly. TI recommends a single-point calibration to minimize the offset error of the built-in temperature sensor.
(2) The device descriptor structure contains calibration values for 30°C and 85°C for each available reference voltage level. The sensor voltage can be computed as $V_{SENSE} = TC_{SENSOR} \times (\text{Temperature, °C}) + V_{SENSOR}$, where TC_{SENSOR} and V_{SENSOR} can be computed from the calibration values for higher accuracy.
(3) The typical equivalent impedance of the sensor is 700 kΩ. The sample time required includes the sensor on time, $t_{SENSOR(on)}$.

Copyright © 2015–2019, Texas Instruments Incorporated

5.11.9 CapTIvate

Table 5-23 lists the characteristics of the CapTIvate module.

Table 5-23. CapTIvate Electrical Characteristics

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V_{REG}	Reference voltage output		1.5	1.55	1.6	V
C_{REG}	External buffer capacitor	ESR ≤ 200 mΩ	0.8	1	1.2	µF
$C_{ELECTRODE}$	Maximum capacitance of all external electrodes on all CapTIvate blocks	Running a conversion at 4 MHz			300	pF
$t_{WAKEUP,COLD}$	Voltage regulator wake-up time	LDO completely off then turned on			1	ms
$t_{WAKEUP,WARM}$	Voltage regulator wake-up time	LDO in low-power mode then turned on			300	us
f_{CAPCLK}	Captivate oscillator frequency, nominal	T_A = 25ºC, CAPCLK0, FREQSHFT = 00b	–3%	16	+3%	MHz
DC_{CAPCLK}	CapTIvate oscillator duty cycle	Excluding first clock cycle, DC = t_{high} × f	40%	50%	60%	

Table 5-24 lists the signal-to-noise ratio of the CapTIvate module.

Table 5-24. CapTIvate Signal-to-Noise Ratio Characteristics

over operating free-air temperature range from –40°C to 105°C ambient (T_A), unless otherwise noted

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
SNR	Signal-to-noise ratio(1)	T_A = 25°C, C_t > 0.5 pF, C_p < 20 pF, >2.5% change in capacitance(2)	5:1	36:1		
		T_A = 0°C, C_t > 0.5 pF, C_p < 20 pF, >2.5% change in capacitance(2)		28:1		
		T_A = –40°C, C_t > 0.5 pF, C_p < 20 pF, >2.5% change in capacitance(2)		19:1		

(1) SNR is defined as the ratio of the measured change in electrode capacitance due to a touch compared with the measured change in capacitance due to the device noise floor. For additional detail on SNR in capacitive sensing applications and how to measure it in your system, see Sensitivity, SNR, and Design Margin in Capacitive Touch Applications.
(2) C_t represents the increase or decrease in electrode capacitance due to a touch. C_p represents the inherent parasitic capacitance of the sensing electrode that is present when no touch is applied. Therefore, the touch signal is defined as C_t/C_p, expressed as a percent change in capacitance. Increasing C_t or decreasing C_p increases signal.

5.11.10 FRAM

Table 5-25 lists the characteristics of the FRAM.

Table 5-25. FRAM

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
	Read and write endurance		10^{15}			cycles
$t_{Retention}$	Data retention duration	T_J = 25°C	100			years
		T_J = 70°C	40			
		T_J = 85°C	10			
I_{WRITE}	Current to write into FRAM			I_{READ}(1)		nA
I_{ERASE}	Erase current			N/A(2)		nA
t_{WRITE}	Write time			t_{READ}(3)		ns
t_{READ}	Read time	NWAITSx = 0		$1/f_{SYSTEM}$(4)		ns
		NWAITSx = 1		$2/f_{SYSTEM}$(4)		

(1) Writing to FRAM does not require a setup sequence or additional power when compared to reading from FRAM. The FRAM read current I_{READ} is included in the active mode current consumption parameter $I_{AM,FRAM}$.
(2) FRAM does not require a special erase sequence.
(3) Writing into FRAM is as fast as reading.
(4) The maximum read (and write) speed is specified by f_{SYSTEM} using the appropriate wait state settings (NWAITSx).

Copyright © 2015–2019, Texas Instruments Incorporated

5.11.11 Debug and Emulation

Table 5-26 lists the characteristics of the Spy-Bi-Wire interface.

Table 5-26. JTAG, Spy-Bi-Wire Interface

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Figure 5-17)

PARAMETER		V_{CC}	MIN	TYP	MAX	UNIT
f_{SBW}	Spy-Bi-Wire input frequency	2 V, 3 V	0		10	MHz
$t_{SBW,Low}$	Spy-Bi-Wire low clock pulse duration	2 V, 3 V	0.028		15	µs
$t_{SU,\ SBWTDIO}$	SBWTDIO setup time (before falling edge of SBWTCK in TMS and TDI slot, Spy-Bi-Wire)	2 V, 3 V	4			ns
$t_{HD,\ SBWTDIO}$	SBWTDIO hold time (after rising edge of SBWTCK in TMS and TDI slot, Spy-Bi-Wire)	2 V, 3 V	19			ns
$t_{Valid,\ SBWTDIO}$	SBWTDIO data valid time (after falling edge of SBWTCK in TDO slot, Spy-Bi-Wire)	2 V, 3 V			31	ns
$t_{SBW,\ En}$	Spy-Bi-Wire enable time (TEST high to acceptance of first clock edge) (1)	2 V, 3 V			110	µs
$t_{SBW,Ret}$	Spy-Bi-Wire return to normal operation time (2)	2 V, 3 V	15		100	µs
$R_{internal}$	Internal pulldown resistance on TEST	2 V, 3 V	20	35	50	kΩ

(1) Tools that access the Spy-Bi-Wire interface must wait for the $t_{SBW,En}$ time after pulling the TEST/SBWTCK pin high before applying the first SBWTCK clock edge.
(2) Maximum $t_{SBW,Ret}$ time after pulling or releasing the TEST/SBWTCK pin low until the Spy-Bi-Wire pins revert from their Spy-Bi-Wire function to their application function. This time applies only if the Spy-Bi-Wire mode is selected.

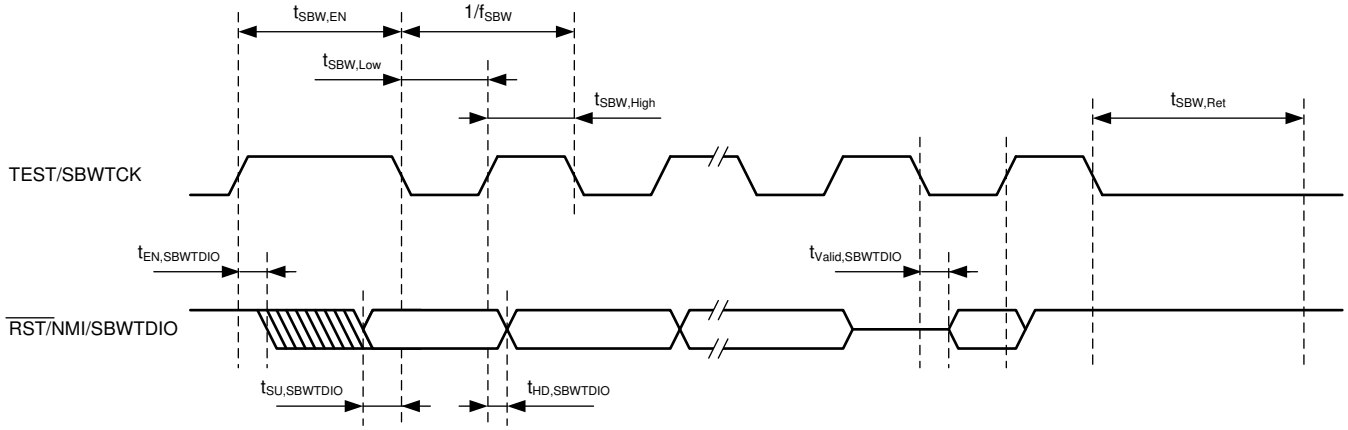


Figure 5-17. JTAG Spy-Bi-Wire Timing

Copyright © 2015–2019, Texas Instruments Incorporated

Table 5-27 lists the characteristics of the 4-wire JTAG interface.

Table 5-27. JTAG, 4-Wire Interface

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Figure 5-18)

PARAMETER		V_{CC}	MIN	TYP	MAX	UNIT
f_{TCK}	TCK input frequency(1)	2 V, 3 V	0		10	MHz
$t_{TCK,Low}$	TCK low clock pulse duration	2 V, 3 V	15			ns
$t_{TCK,High}$	TCK high clock pulse duration	2 V, 3 V	15			ns
$t_{SU,TMS}$	TMS setup time (before rising edge of TCK)	2 V, 3 V	11			ns
$t_{HD,TMS}$	TMS hold time (after rising edge of TCK)	2 V, 3 V	3			ns
$t_{SU,TDI}$	TDI setup time (before rising edge of TCK)	2 V, 3 V	13			ns
$t_{HD,TDI}$	TDI hold time (after rising edge of TCK)	2 V, 3 V	5			ns
$t_{Z\text{-}Valid,TDO}$	TDO high impedance to valid output time (after falling edge of TCK)	2 V, 3 V			26	ns
$t_{Valid,TDO}$	TDO to new valid output time (after falling edge of TCK)	2 V, 3 V			26	ns
$t_{Valid\text{-}Z,TDO}$	TDO valid to high-impedance output time (after falling edge of TCK)	2 V, 3 V			26	ns
$t_{JTAG,Ret}$	Spy-Bi-Wire return to normal operation time		15		100	µs
$R_{internal}$	Internal pulldown resistance on TEST	2 V, 3 V	20	35	50	kΩ

(1) f_{TCK} may be restricted to meet the timing requirements of the module selected.

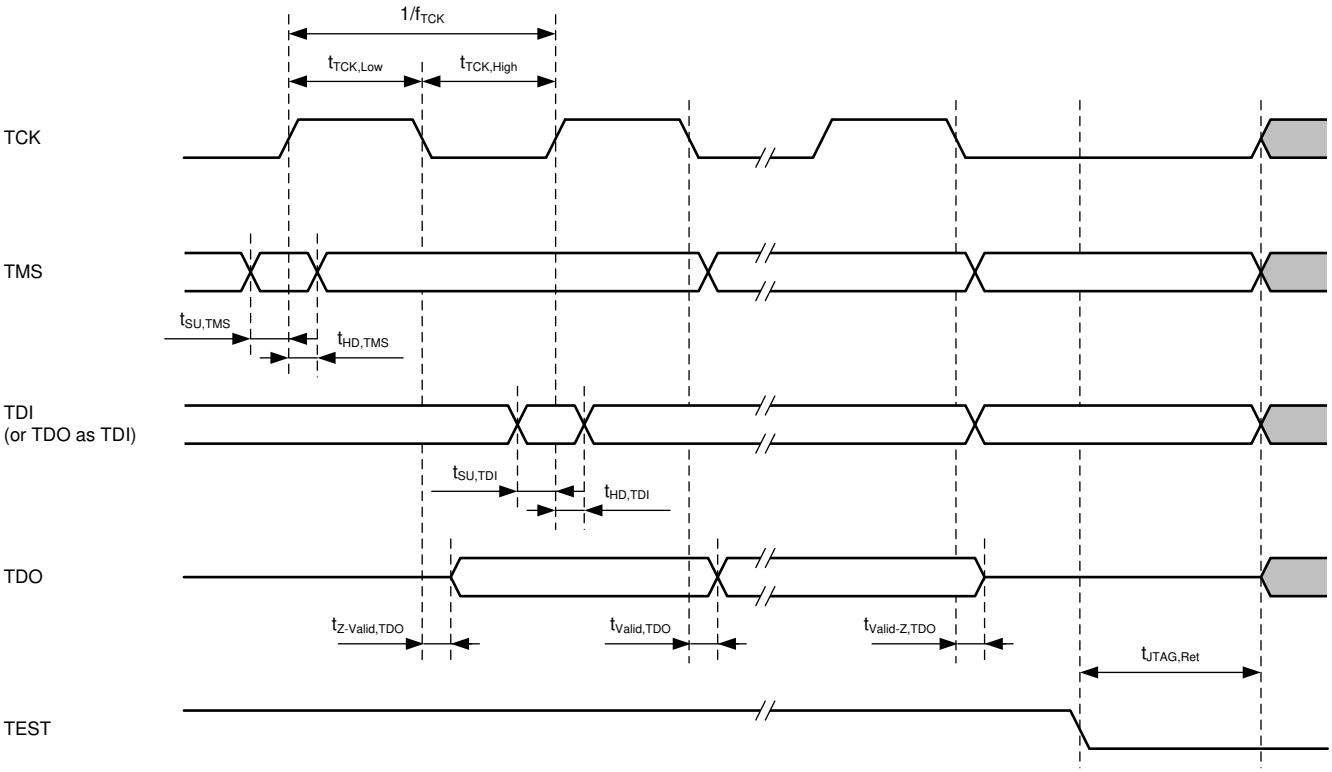


Figure 5-18. JTAG 4-Wire Timing

6 Detailed Description

6.1 Overview

The MSP430FR263x and MSP430FR253x ultra-low-power MCUs are the first FRAM-based MCUs with integrated high-performance charge-transfer CapTIvate technology in ultra-low-power high-reliability high-flexibility MCUs. The MSP430FR263x and MSP430FR253x MCUs feature up to 16 self-capacitance or 64 mutual-capacitance electrodes, proximity sensing, and high accuracy up to 1-fF detection. The MCUs also include four 16-bit timers, eUSCIs that support UART, SPI, and I^2C, a hardware multiplier, an RTC module with alarm capabilities, and a high-performance 10-bit ADC.

6.2 CPU

The MSP430 CPU has a 16-bit RISC architecture that is highly transparent to the application. All operations, other than program-flow instructions, are performed as register operations in conjunction with seven addressing modes for source operand and four addressing modes for destination operand.

The CPU is integrated with 16 registers that provide reduced instruction execution time. The register-to-register operation execution time is one cycle of the CPU clock.

Four of the registers, R0 to R3, are dedicated as program counter (PC), stack pointer (SP), status register (SR), and constant generator (CG), respectively. The remaining registers are general-purpose registers.

Peripherals are connected to the CPU using data, address, and control buses. Peripherals can be managed with all instructions.

6.3 Operating Modes

The MSP430FR263x and MSP430FR253x MCUs have one active mode and several software-selectable low-power modes of operation (see Table 6-1). An interrupt event can wake the MCU from low-power mode (LPM0 or LPM3), service the request, and restore the MCU back to the low-power mode on return from the interrupt program. Low-power modes LPM3.5 and LPM4.5 disable the core supply to minimize power consumption.

Table 6-1. Operating Modes

MODE		AM	LPM0	LPM3	LPM4	LPM3.5	LPM4.5
		ACTIVE MODE (FRAM ON)	CPU OFF	STANDBY	OFF	ONLY RTC	SHUTDOWN
Maximum system clock		16 MHz	16 MHz	40 kHz	0	40 kHz	0
Power consumption at 25°C, 3 V		126 µA/MHz	40 µA/MHz	1.7 µA/button average with 8-Hz scan	0.49 µA without SVS	0.73 µA with RTC counter only in LFXT	16 nA without SVS
Wake-up time		N/A	Instant	10 µs	10 µs	350 µs	350 µs
Wake-up events		N/A	All	All	CapTIvate I/O	RTC I/O	I/O
Power	Regulator	Full Regulation	Full Regulation	Partial Power Down	Partial Power Down	Partial Power Down	Power Down
	SVS	On	On	Optional	Optional	Optional	Optional
	Brownout	On	On	On	On	On	On

Copyright © 2015–2019, Texas Instruments Incorporated

Table 6-1. Operating Modes (continued)

MODE		AM	LPM0	LPM3	LPM4	LPM3.5	LPM4.5
		ACTIVE MODE (FRAM ON)	CPU OFF	STANDBY	OFF	ONLY RTC	SHUTDOWN
Clock[1]	MCLK	Active	Off	Off	Off	Off	Off
	SMCLK	Optional	Optional	Off	Off	Off	Off
	FLL	Optional	Optional	Off	Off	Off	Off
	DCO	Optional	Optional	Off	Off	Off	Off
	MODCLK	Optional	Optional	Off	Off	Off	Off
	REFO	Optional	Optional	Optional	Off	Off	Off
	ACLK	Optional	Optional	Optional	Off	Off	Off
	XT1CLK	Optional	Optional	Optional	Off	Optional	Off
	VLOCLK	Optional	Optional	Optional	Off	Optional	Off
	CapTIvate MODCLK	Optional	Optional	Optional	Off	Off	Off
Core	CPU	On	Off	Off	Off	Off	Off
	FRAM	On	On	Off	Off	Off	Off
	RAM	On	On	On	On	Off	Off
	Backup memory[2]	On	On	On	On	On	Off
Peripherals	Timer0_A3	Optional	Optional	Optional	Off	Off	Off
	Timer1_A3	Optional	Optional	Optional	Off	Off	Off
	Timer2_A2	Optional	Optional	Optional	Off	Off	Off
	Timer3_A2	Optional	Optional	Optional	Off	Off	Off
	WDT	Optional	Optional	Optional	Off	Off	Off
	eUSCI_A0	Optional	Optional	Off	Off	Off	Off
	eUSCI_A1	Optional	Optional	Off	Off	Off	Off
	eUSCI_B0	Optional	Optional	Off	Off	Off	Off
	CRC	Optional	Optional	Off	Off	Off	Off
	ADC	Optional	Optional	Optional	Off	Off	Off
	RTC	Optional	Optional	Optional	Off	Optional	Off
	CapTIvate	Optional	Optional	Optional	Off	Off	Off
I/O	General-purpose digital input/output	On	Optional	State Held	State Held	State Held	State Held

(1) The status shown for LPM4 applies to internal clocks only.
(2) Backup memory contains 32 bytes of register space in peripheral memory. See Table 6-24 and Table 6-43 for its memory allocation.

NOTE

XT1CLK and VLOCLK can be active during LPM4 if requested by low-frequency peripherals, such as RTC, WDT, or CapTIvate.

6.4 Interrupt Vector Addresses

The interrupt vectors and the power-up start address are in the address range 0FFFFh to 0FF80h (see Table 6-2). The vector contains the 16-bit address of the appropriate interrupt-handler instruction sequence.

Table 6-2. Interrupt Sources, Flags, and Vectors

INTERRUPT SOURCE	INTERRUPT FLAG	SYSTEM INTERRUPT	WORD ADDRESS	PRIORITY
System Reset Power up, Brownout, Supply supervisor External reset RST Watchdog time-out, Key violation FRAM access time error FRAM uncorrectable bit error detection Software POR, BOR FLL unlock error	PMMPORIFG, PMMBORIFG, SVSHIFG PMMRSTIFG WDTIFG ACCTEIFG UBDIFG SYSRSTIV FLLUNLOCKIFG	Reset	FFFEh	63, Highest
System NMI Vacant memory access JTAG mailbox FRAM bit error detection	VMAIFG JMBINIFG, JMBOUTIFG CBDIFG, UBDIFG	Nonmaskable	FFFCh	62
User NMI External NMI Oscillator fault	NMIIFG OFIFG	Nonmaskable	FFFAh	61
Timer0_A3	TA0CCR0 CCIFG0	Maskable	FFF8h	60
Timer0_A3	TA0CCR1 CCIFG1, TA0CCR2 CCIFG2, TA0IFG (TA0IV)	Maskable	FFF6h	59
Timer1_A3	TA1CCR0 CCIFG0	Maskable	FFF4h	58
Timer1_A3	TA1CCR1 CCIFG1, TA1CCR2 CCIFG2, TA1IFG (TA1IV)	Maskable	FFF2h	57
Timer2_A2	TA2CCR0 CCIFG0	Maskable	FFF0h	56
Timer2_A2	TA2CCR1 CCIFG1, TA2IFG (TA2IV)		FFEEh	55
Timer3_A2	TA3CCR0 CCIFG0	Maskable	FFECh	54
Timer3_A2	TA3CCR1 CCIFG1, TA3IFG (TA3IV)		FFEAh	53
RTC	RTCIFG	Maskable	FFE8h	52
Watchdog timer interval mode	WDTIFG	Maskable	FFE6h	51
eUSCI_A0 receive or transmit	UCTXCPTIFG, UCSTTIFG, UCRXIFG, UCTXIFG (UART mode) UCRXIFG, UCTXIFG (SPI mode) (UCA0IV)	Maskable	FFE4h	50
eUSCI_A1 receive or transmit	UCTXCPTIFG, UCSTTIFG, UCRXIFG, UCTXIFG (UART mode) UCRXIFG, UCTXIFG (SPI mode) (UCA1IV)	Maskable	FFE2h	49
eUSCI_B0 receive or transmit	UCB0RXIFG, UCB0TXIFG (SPI mode) UCALIFG, UCNACKIFG, UCSTTIFG, UCSTPIFG, UCRXIFG0, UCTXIFG0, UCRXIFG1, UCTXIFG1, UCRXIFG2, UCTXIFG2, UCRXIFG3, UCTXIFG3, UCCNTIFG, UCBIT9IFG (I^2C mode) (UCB0IV)	Maskable	FFE0h	48
ADC	ADCIFG0, ADCINIFG, ADCLOIFG, ADCHIIFG, ADCTOVIFG, ADCOVIFG (ADCIV)	Maskable	FFDEh	47
P1	P1IFG.0 to P1IFG.7 (P1IV)	Maskable	FFDCh	46
P2	P2IFG.0 to P2IFG.7 (P2IV)	Maskable	FFDAh	45
CapTIvate	(See CapTivate Design Center for details)	Maskable	FFD8h	44, Lowest
Reserved	Reserved	Maskable	FFD6h to FF88h	

Copyright © 2015–2019, Texas Instruments Incorporated

Table 6-2. Interrupt Sources, Flags, and Vectors (continued)

INTERRUPT SOURCE	INTERRUPT FLAG	SYSTEM INTERRUPT	WORD ADDRESS	PRIORITY
Signatures	BSL Signature 2		0FF86h	
	BSL Signature 1		0FF84h	
	JTAG Signature 2		0FF82h	
	JTAG Signature 1		0FF80h	

6.5 Bootloader (BSL)

The BSL lets users program the FRAM or RAM using either the UART serial interface or the I^2C interface. Access to the MCU memory through the BSL is protected by an user-defined password. Use of the BSL requires four pins (see Table 6-3 and Table 6-4). BSL entry requires a specific entry sequence on the $\overline{RST}$/NMI/SBWTDIO and TEST/SBWTCK pins. This device supports the blank device detection to automatically invoke the BSL, skipping this special entry sequence, to save time and simplify onboard programming. For a complete description of the features of the BSL, see the MSP430 FRAM Device Bootloader (BSL) User's Guide.

Table 6-3. UART BSL Pin Requirements and Functions

DEVICE SIGNAL	BSL FUNCTION
$\overline{RST}$/NMI/SBWTDIO	Entry sequence signal
TEST/SBWTCK	Entry sequence signal
P1.4	Data transmit
P1.5	Data receive
VCC	Power supply
VSS	Ground supply

Table 6-4. I^2C BSL Pin Requirements and Functions

DEVICE SIGNAL	BSL FUNCTION
$\overline{RST}$/NMI/SBWTDIO	Entry sequence signal
TEST/SBWTCK	Entry sequence signal
P1.2	Data transmit and receive
P1.3	Clock
VCC	Power supply
VSS	Ground supply

Copyright © 2015–2019, Texas Instruments Incorporated

6.6 JTAG Standard Interface

The MSP low-power microcontrollers support the standard JTAG interface, which requires four signals for sending and receiving data. The JTAG signals are shared with general-purpose I/O. The TEST/SBWTCK pin enables the JTAG signals. In addition to these signals, the $\overline{\text{RST}}$/NMI/SBWTDIO is required to interface with MSP430 development tools and device programmers. Table 6-5 lists the JTAG pin requirements. For further details on interfacing to development tools and device programmers, see the *MSP430 Hardware Tools User's Guide*. For details on using the JTAG interface, see *MSP430 Programming With the JTAG Interface*.

Table 6-5. JTAG Pin Requirements and Function

DEVICE SIGNAL	DIRECTION	JTAG FUNCTION
P1.4/UCA0TXD/UCA0SIMO/TA1.2/TCK/A4/VREF+	IN	JTAG clock input
P1.5/UCA0RXD/UCA0SOMI/TA1.1/TMS/A5	IN	JTAG state control
P1.6/UCA0CLK/TA1CLK/TDI/TCLK/A6	IN	JTAG data input, TCLK input
P1.7/UCA0STE/SMCLK/TDO/A7	OUT	JTAG data output
TEST/SBWTCK	IN	Enable JTAG pins
$\overline{\text{RST}}$/NMI/SBWTDIO	IN	External reset
DVCC	–	Power supply
DVSS	–	Ground supply

6.7 Spy-Bi-Wire Interface (SBW)

The MSP low-power microcontrollers support the 2-wire SBW interface. SBW can be used to interface with MSP development tools and device programmers. Table 6-6 lists the SBW interface pin requirements. For further details on interfacing to development tools and device programmers, see the *MSP430 Hardware Tools User's Guide*. For details on using the SBW interface, see the *MSP430 Programming With the JTAG Interface*.

Table 6-6. Spy-Bi-Wire Pin Requirements and Functions

DEVICE SIGNAL	DIRECTION	SBW FUNCTION
TEST/SBWTCK	IN	Spy-Bi-Wire clock input
$\overline{\text{RST}}$/NMI/SBWTDIO	IN, OUT	Spy-Bi-Wire data input and output
DVCC	–	Power supply
DVSS	–	Ground supply

6.8 FRAM

The FRAM can be programmed using the JTAG port, SBW, the BSL, or in-system by the CPU. Features of the FRAM include:

- Byte and word access capability
- Programmable wait state generation
- Error correction coding (ECC)

6.9 Memory Protection

The device features memory protection for user access authority and write protection, including options to:

- Secure the whole memory map to prevent unauthorized access from JTAG port or BSL, by writing JTAG and BSL signatures using the JTAG port, SBW, the BSL, or in-system by the CPU.
- Enable write protection to prevent unwanted write operation to FRAM contents by setting the control bits in the System Configuration 0 register. For detailed information, see the *System Resets, Interrupts, and Operating Modes, System Control Module (SYS)* chapter in the *MP430FR4xx and MP430FR2xx Family User's Guide*.

Copyright © 2015–2019, Texas Instruments Incorporated

6.10 Peripherals

Peripherals are connected to the CPU through data, address, and control buses. All peripherals can be handled by using all instructions in the memory map. For complete module description, see the *MP430FR4xx and MP430FR2xx Family User's Guide*.

6.10.1 Power-Management Module (PMM)

The PMM includes an integrated voltage regulator that supplies the core voltage to the device. The PMM also includes supply voltage supervisor (SVS) and brownout protection. The brownout reset circuit (BOR) is implemented to provide the proper internal reset signal to the device during power on and power off. The SVS circuitry detects if the supply voltage drops below a user-selectable safe level. SVS circuitry is available on the primary supply.

The device contains two on-chip reference: 1.5 V for internal reference and 1.2 V for external reference.

The 1.5-V reference is internally connected to ADC channel 13. DVCC is internally connected to ADC channel 15. When DVCC is set as the reference voltage for ADC conversion, the DVCC can be easily represent as Equation 1 by using ADC sampling 1.5-V reference without any external components support.

$$DVCC = (1023 \times 1.5\ V) \div 1.5\text{-}V\ reference\ ADC\ result \quad (1)$$

A 1.2-V reference voltage can be buffered and output to P1.4/MCLK/TCK/A4/VREF+, when EXTREFEN = 1 in the PMMCTL1 register. ADC channel 4 can also be selected to monitor this voltage. For more detailed information, see the *MP430FR4xx and MP430FR2xx Family User's Guide*.

6.10.2 Clock System (CS) and Clock Distribution

The clock system includes a 32-kHz crystal oscillator (XT1), an internal very-low-power low-frequency oscillator (VLO), an integrated 32-kHz RC oscillator (REFO), an integrated internal digitally controlled oscillator (DCO) that may use frequency-locked loop (FLL) locking with internal or external 32-kHz reference clock, and an on-chip asynchronous high-speed clock (MODOSC). The clock system is designed for cost-effective designs with minimal external components. A fail-safe mechanism is included for XT1. The clock system module offers the following clock signals.

- Main Clock (MCLK): The system clock used by the CPU and all relevant peripherals accessed by the bus. All clock sources except MODOSC can be selected as the source with a predivider of 1, 2, 4, 8, 16, 32, 64, or 128.
- Sub-Main Clock (SMCLK): The subsystem clock used by the peripheral modules. SMCLK derives from the MCLK with a predivider of 1, 2, 4, or 8. This means SMCLK is always equal to or less than MCLK.
- Auxiliary Clock (ACLK): This clock is derived from the external XT1 clock or internal REFO clock up to 40 kHz.

Copyright © 2015–2019, Texas Instruments Incorporated

All peripherals may have one or several clock sources depending on specific functionality. Table 6-7 lists the clock distribution used in this device.

Table 6-7. Clock Distribution

	CLOCK SOURCE SELECT BITS	MCLK	SMCLK	ACLK	MODCLK	XT1CLK	VLOCLK	EXTERNAL PIN
Frequency Range		DC to 16 MHz	DC to 16 MHz	DC to 40 kHz	5 MHz ±10%	DC to 40 kHz	10 kHz ±50%	–
CPU	N/A	Default	–	–	–	–	–	–
FRAM	N/A	Default	–	–	–	–	–	–
RAM	N/A	Default	–	–	–	–	–	–
CRC	N/A	Default	–	–	–	–	–	–
I/O	N/A	Default	–	–	–	–	–	–
TA0	TASSEL	–	10b	01b	–	–	–	00b (TA0CLK pin)
TA1	TASSEL	–	10b	01b	–	–	–	00b (TA1CLK pin)
TA2	TASSEL	–	10b	01b	–	–	–	–
TA3	TASSEL	–	10b	01b	–	–	–	–
eUSCI_A0	UCSSEL	–	10b or 11b	–	01b	–	–	00b (UCA0CLK pin)
eUSCI_A1	UCSSEL	–	10b or 11b	–	01b	–	–	00b (UCA1CLK pin)
eUSCI_B0	UCSSEL	–	10b or 11b	–	01b	–	–	00b (UCB0CLK pin)
WDT	WDTSSEL	–	00b	01b	–	–	10b or 11b	–
ADC	ADCSSEL	–	11b	01b	00b	–	–	–
CapTIvate	CAPTSSEL	–		00b	–	–	01b	–
	CAPCLKSEL	–	1b	–	–	–	–	–
RTC	RTCSS	–	01b	–	–	10b	11b	–

6.10.3 General-Purpose Input/Output Port (I/O)

Up to 19 I/O ports are implemented.

- P1 and P2 are full 8-bit ports; P3 has 3 bits implemented.
- All individual I/O bits are independently programmable.
- Any combination of input, output, and interrupt conditions is possible.
- All ports support programmable pullup or pulldown.
- Edge-selectable interrupt and LPM3.5 and LPM4.5 wake-up input capability is available for P1 and P2.
- Read and write access to port-control registers is supported by all instructions.
- Ports can be accessed byte-wise or word-wise in pairs.
- CapTIvate functionality is supported on all CAPx.y pins.

NOTE

Configuration of digital I/Os after BOR reset

To prevent any cross currents during start-up of the device, all port pins are high-impedance with Schmitt triggers and module functions disabled. To enable the I/O functions after a BOR reset, the ports must be configured first and then the LOCKLPM5 bit must be cleared. For details, see the *Configuration After Reset* section in the *Digital I/O* chapter of the *MP430FR4xx and MP430FR2xx Family User's Guide*.

Copyright © 2015–2019, Texas Instruments Incorporated

6.10.4 Watchdog Timer (WDT)

The primary function of the WDT module is to perform a controlled system restart after a software problem occurs. If the selected time interval expires, a system reset is generated. If the watchdog function is not needed in an application, the module can be configured as interval timer and can generate interrupts at selected time intervals. Table 6-8 lists the system clocks that can be used to source the WDT.

Table 6-8. WDT Clocks

WDTSSEL	NORMAL OPERATION (WATCHDOG AND INTERVAL TIMER MODE)
00	SMCLK
01	ACLK
10	VLOCLK
11	Reserved

Copyright © 2015–2019, Texas Instruments Incorporated

6.10.5 System (SYS) Module

The SYS module handles many of the system functions within the device. These features include power-on reset (POR) and power-up clear (PUC) handling, NMI source selection and management, reset interrupt vector generators, bootloader entry mechanisms, and configuration management (device descriptors). The SYS module also includes a data exchange mechanism through SBW called a JTAG mailbox mail box that can be used in the application. Table 6-9 summarizes the interrupts that are managed by the SYS module.

Table 6-9. System Module Interrupt Vector Registers

INTERRUPT VECTOR REGISTER	ADDRESS	INTERRUPT EVENT	VALUE	PRIORITY
SYSRSTIV, System Reset	015Eh	No interrupt pending	00h	
		Brownout (BOR)	02h	Highest
		RSTIFG $\overline{\text{RST}}$/NMI (BOR)	04h	
		PMMSWBOR software BOR (BOR)	06h	
		LPMx.5 wake up (BOR)	08h	
		Security violation (BOR)	0Ah	
		Reserved	0Ch	
		SVSHIFG SVSH event (BOR)	0Eh	
		Reserved	10h	
		Reserved	12h	
		PMMSWPOR software POR (POR)	14h	
		WDTIFG watchdog time-out (PUC)	16h	
		WDTPW password violation (PUC)	18h	
		FRCTLPW password violation (PUC)	1Ah	
		Uncorrectable FRAM bit error detection	1Ch	
		Peripheral area fetch (PUC)	1Eh	
		PMMPW PMM password violation (PUC)	20h	
		FLL unlock (PUC)	24h	
		Reserved	22h, 26h to 3Eh	Lowest
SYSSNIV, System NMI	015Ch	No interrupt pending	00h	
		SVS low-power reset entry	02h	Highest
		Uncorrectable FRAM bit error detection	04h	
		Reserved	06h	
		Reserved	08h	
		Reserved	0Ah	
		Reserved	0Ch	
		Reserved	0Eh	
		Reserved	10h	
		VMAIFG Vacant memory access	12h	
		JMBINIFG JTAG mailbox input	14h	
		JMBOUTIFG JTAG mailbox output	16h	
		Correctable FRAM bit error detection	18h	
		Reserved	1Ah to 1Eh	Lowest
SYSUNIV, User NMI	015Ah	No interrupt pending	00h	
		NMIIFG NMI pin or SVS_H event	02h	Highest
		OFIFG oscillator fault	04h	
		Reserved	06h to 1Eh	Lowest

Copyright © 2015–2019, Texas Instruments Incorporated

6.10.6 Cyclic Redundancy Check (CRC)

The 16-bit cyclic redundancy check (CRC) module produces a signature based on a sequence of data values and can be used for data checking purposes. The CRC generation polynomial is compliant with CRC-16-CCITT standard of $x^{16} + x^{12} + x^5 + 1$.

6.10.7 Enhanced Universal Serial Communication Interface (eUSCI_A0, eUSCI_B0)

The eUSCI modules are used for serial data communications. The eUSCI_A module supports either UART or SPI communications. The eUSCI_B module supports either SPI or I^2C communications. Additionally, eUSCI_A supports automatic baud-rate detection and IrDA. Table 6-10 lists the pin configurations that are required for each eUSCI mode.

Table 6-10. eUSCI Pin Configurations

	PIN	UART	SPI
eUSCI_A0	P1.4	TXD	SIMO
	P1.5	RXD	SOMI
	P1.6	–	SCLK
	P1.7	–	STE
eUSCI_A1	P2.6	TXD	SIMO
	P2.5	RXD	SOMI
	P2.4	–	SCLK
	P3.1	–	STE
	PIN	**I^2C**	**SPI**
eUSCI_B0	P1.0	–	STE
	P1.1	–	SCLK
	P1.2	SDA	SIMO
	P1.3	SCL	SOMI

6.10.8 Timers (Timer0_A3, Timer1_A3, Timer2_A2 and Timer3_A2)

The Timer0_A3 and Timer1_A3 modules are 16-bit timers and counters with three capture/compare registers each. Both timers support multiple captures or compares, PWM outputs, and interval timing (see Table 6-11 and Table 6-12). Both timers have extensive interrupt capabilities. Interrupts may be generated from the counter on overflow conditions and from each capture/compare register.

The CCR0 registers on Timer0_A3 and Timer1_A3 are not externally connected and can be used only for hardware period timing and interrupt generation. In Up mode, these CCR0 registers can be used to set the overflow value of the counter.

Table 6-11. Timer0_A3 Signal Connections

PORT PIN	DEVICE INPUT SIGNAL	MODULE INPUT NAME	MODULE BLOCK	MODULE OUTPUT SIGNAL	DEVICE OUTPUT SIGNAL
P1.0	TA0CLK	TACLK	Timer	N/A	
	ACLK (internal)	ACLK			
	SMCLK (internal)	SMCLK			
		CCI0A	CCR0	TA0	
		CCI0B			Timer1_A3 CCI0B input
	DVSS	GND			
	DVCC	VCC			
P1.1	TA0.1	CCI1A	CCR1	TA1	TA0.1
	from RTC (internal)	CCI1B			Timer1_A3 CCI1B input
	DVSS	GND			
	DVCC	VCC			
P1.2	TA0.2	CCI2A	CCR2	TA2	TA0.2
		CCI2B			Timer1_A3 CCI2B input, IR Input
	DVSS	GND			
	DVCC	VCC			

Copyright © 2015–2019, Texas Instruments Incorporated

Table 6-12. Timer1_A3 Signal Connections

PORT PIN	DEVICE INPUT SIGNAL	MODULE INPUT NAME	MODULE BLOCK	MODULE OUTPUT SIGNAL	DEVICE OUTPUT SIGNAL
P1.6	TA1CLK	TACLK	Timer	N/A	
	ACLK (internal)	ACLK			
	SMCLK (internal)	SMCLK			
		CCI0A	CCR0	TA0	
	Timer0_A3 CCR0B output (internal)	CCI0B			
	DVSS	GND			
	DVCC	VCC			
P1.5	TA1.1	CCI1A	CCR1	TA1	TA1.1
	Timer0_A3 CCR1B output (internal)	CCI1B			to ADC trigger
	DVSS	GND			
	DVCC	VCC			
P1.4	TA1.2	CCI2A	CCR2	TA2	TA1.2
	Timer0_A3 CCR2B output (internal)	CCI2B			IR Input
	DVSS	GND			
	DVCC	VCC			

The interconnection of Timer0_A3 and Timer1_A3 can be used to modulate the eUSCI_A pin of UCA0TXD/UCA0SIMO in either ASK or FSK mode, with which a user can easily acquire a modulated infrared command for directly driving an external IR diode. The IR functions are fully controlled by SYS configuration registers 1 including IREN (enable), IRPSEL (polarity select), IRMSEL (mode select), IRDSSEL (data select), and IRDATA (data) bits. For more information, see the *System Resets, Interrupts, and Operating Modes, System Control Module (SYS)* chapter in the *MP430FR4xx and MP430FR2xx Family User's Guide*.

The Timer2_A2 and Timer3_A2 modules are 16-bit timers and counters with two capture/compare registers each. Both timers support multiple captures or compares and interval timing (see Table 6-13 and Table 6-14). Both timers have extensive interrupt capabilities. Interrupts may be generated from the counter on overflow conditions and from each capture register.

The CCR0 registers on Timer2_TA2 and Timer3_TA2 are not externally connected and can be used only for hardware period timing and interrupt generation. In Up mode, these CCR0 registers can be used to set the overflow value of the counter. Timer2_A2 and Timer3_A2 are only internally connected and do not support PWM output.

Table 6-13. Timer2_A2 Signal Connections

DEVICE INPUT SIGNAL	MODULE INPUT NAME	MODULE BLOCK	MODULE OUTPUT SIGNAL	DEVICE OUTPUT SIGNAL
ACLK (internal)	ACLK	Timer	N/A	
SMCLK (internal)	SMCLK			
	CCI0A	CCR0	TA0	
	CCI0B			Timer3_A3 CCI0B input
DVSS	GND			
DVCC	VCC			
	CCI1A	CCR1	CCR1	
	CCI1B			Timer3_A3 CCI1B input
DVSS	GND			
DVCC	VCC			

Table 6-14. Timer3_A2 Signal Connections

DEVICE INPUT SIGNAL	MODULE INPUT NAME	MODULE BLOCK	MODULE OUTPUT SIGNAL	DEVICE OUTPUT SIGNAL
ACLK (internal)	ACLK	Timer	N/A	
SMCLK (internal)	SMCLK			
	CCI0A	CCR0	TA0	
Timer3_A3 CCI0B input	CCI0B			
DVSS	GND			
DVCC	VCC			
	CCI1A	CCR1	CCR1	
Timer3_A3 CCI1B input	CCI1B			
DVSS	GND			
DVCC	VCC			

6.10.9 Hardware Multiplier (MPY)

The multiplication operation is supported by a dedicated peripheral module. The module performs operations with 32-, 24-, 16-, and 8-bit operands. The MPY module supports signed multiplication, unsigned multiplication, signed multiply-and-accumulate, and unsigned multiply-and-accumulate operations.

6.10.10 Backup Memory (BAKMEM)

The BAKMEM supports data retention during LPM3.5. This device provides up to 32 bytes that are retained during LPM3.5.

6.10.11 Real-Time Clock (RTC)

The RTC is a 16-bit modulo counter that is functional in AM, LPM0, LPM3, and LPM3.5. This module may periodically wake up the CPU from LPM0, LPM3, and LPM3.5 based on timing from a low-power clock source such as the XT1 and VLO clocks. In AM, SMCLK can drive the RTC to generate high-frequency timing events and interrupts. The RTC overflow events trigger:

- Timer0_A3 CCR1B
- ADC conversion trigger when ADCSHSx bits are set as 01b

Copyright © 2015–2019, Texas Instruments Incorporated

6.10.12 10-Bit Analog-to-Digital Converter (ADC)

The 10-bit ADC module supports fast 10-bit analog-to-digital conversions with single-ended input. The module implements a 10-bit SAR core, sample select control, reference generator and a conversion result buffer. A window comparator with lower and upper limits allows CPU-independent result monitoring with three window comparator interrupt flags.

The ADC supports 10 external inputs and 4 internal inputs (see Table 6-15).

Table 6-15. ADC Channel Connections

ADCINCHx	ADC CHANNELS	EXTERNAL PINOUT
0	A0/Veref+	P1.0
1	A1	P1.1
2	A2/Veref-	P1.2
3	A3	P1.3
4	A4 (1)	P1.4
5	A5	P1.5
6	A6	P1.6
7	A7	P1.7
8	A8	NA
9	A9	NA
10	Not used	N/A
11	Not used	N/A
12	On-chip temperature sensor	N/A
13	Reference voltage (1.5 V)	N/A
14	DVSS	N/A
15	DVCC	N/A

(1) When A4 is used, the PMM 1.2-V reference voltage can be output to this pin by setting the PMM control register. The 1.2-V voltage can be directly measured by A4 channel.

Software or a hardware trigger can start the analog-to-digital conversion. Table 6-16 lists the trigger sources that are available.

Table 6-16. ADC Trigger Signal Connections

ADCSHSx		TRIGGER SOURCE
BINARY	DECIMAL	
00	0	ADCSC bit (software trigger)
01	1	RTC event
10	2	TA1.1B
11	3	--

Copyright © 2015–2019, Texas Instruments Incorporated

6.10.13 CapTIvate Technology

The CapTIvate module detects the capacitance changed with a charge-transfer method and is functional in AM, LPM0, LPM3, and LPM4. The CapTIvate module can periodically wake the CPU from LPM0, LPM3, or LPM4 based on a CapTIvate timer source such as ACLK or VLO clock. The CapTIvate module supports the following touch-sensing capability:

- Up to 64 CapTIvate buttons composed of 4 CapTIvate blocks. Each block consists of 4 I/Os, and these blocks scan in parallel of 4 electrodes.
- Each block can be individually configured in self or mutual mode. Each CapTIvate I/O can be used for either self or mutual electrodes.
- Supports a wake-on-touch state machine.
- Supports synchronized conversion on a zero-crossing event trigger.
- Processing logic to perform filter calculation and threshold detection.

To learn more about MSP MCUs featuring CapTIvate technology, see the CapTIvate™ Technology Guide.

6.10.14 Embedded Emulation Module (EEM)

The EEM supports real-time in-system debugging. The EEM on these devices has the following features:

- Three hardware triggers or breakpoints on memory access
- One hardware trigger or breakpoint on CPU register write access
- Up to four hardware triggers that can be combined to form complex triggers or breakpoints
- One cycle counter
- Clock control on module level
- EEM version: S

Copyright © 2015–2019, Texas Instruments Incorporated

6.11 Input/Output Diagrams

6.11.1 Port P1 Input/Output With Schmitt Trigger

Figure 6-1 shows the port diagram. Table 6-17 summarizes the selection of pin function.

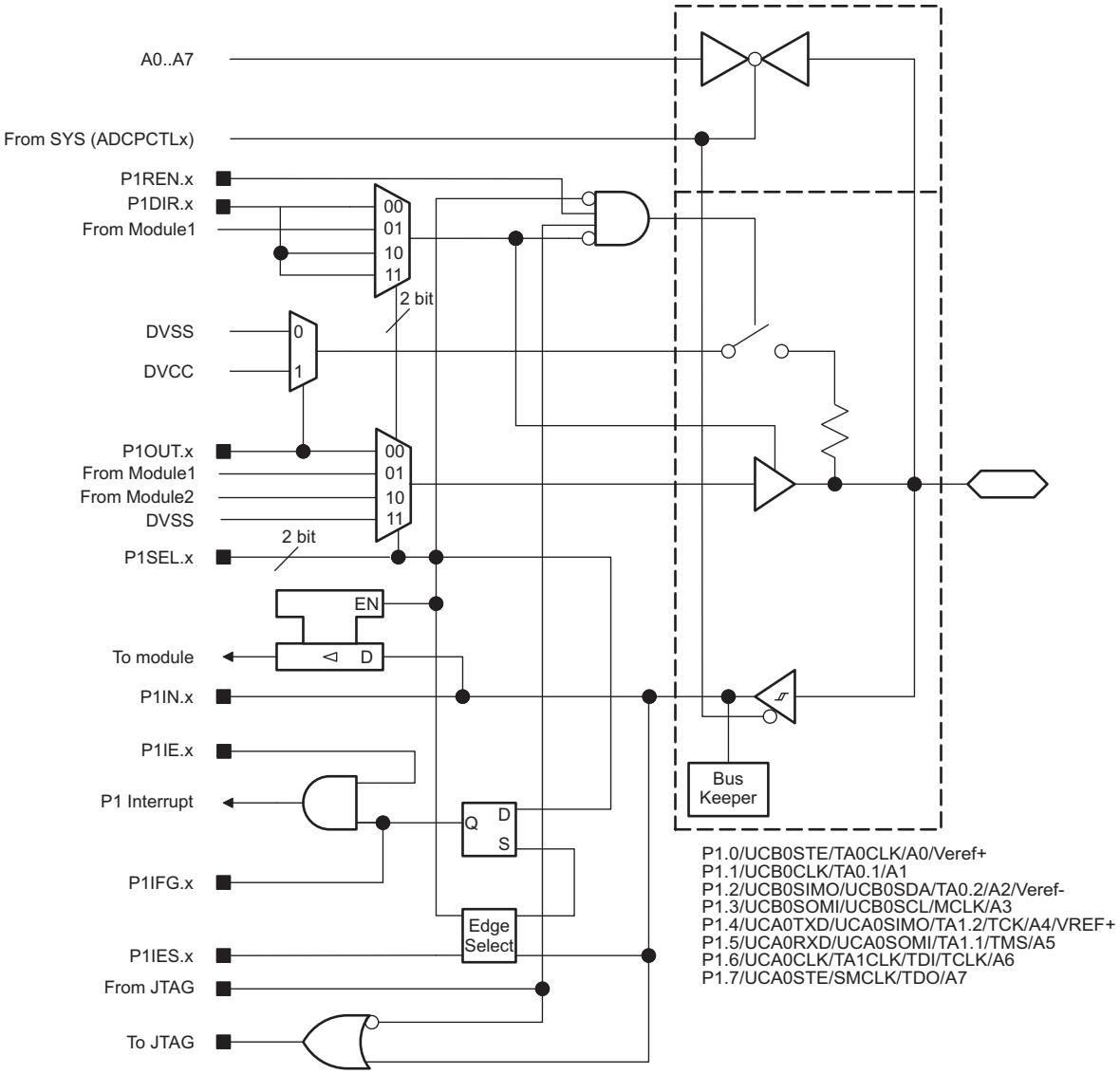


Figure 6-1. Port P1 (P1.0 to P1.7) Input/Output With Schmitt Trigger

Table 6-17. Port P1 (P1.0 to P1.7) Pin Functions

PIN NAME (P1.x)	x	FUNCTION	CONTROL BITS AND SIGNALS[1]			
			P1DIR.x	P1SELx	ADCPCTLx[2]	JTAG
P1.0/UCB0STE/ TA0CLK/A0	0	P1.0 (I/O)	I: 0; O: 1	00	0	N/A
		UCB0STE	X	01	0	N/A
		TA0CLK	0	10	0	N/A
		A0/Veref+	X	X	1 (x = 0)	N/A
P1.1/UCB0CLK/TA0.1/ A1	1	P1.1 (I/O)	I: 0; O: 1	00	0	N/A
		UCB0CLK	X	01	0	N/A
		TA0.CCI1A	0	10	0	N/A
		TA0.1	1			
		A1	X	X	1 (x = 1)	N/A
P1.2/UCB0SIMO/ UCB0SDA/TA0.2/A2	2	P1.2 (I/O)	I: 0; O: 1	00	0	N/A
		UCB0SIMO/UCB0SDA	X	01	0	N/A
		TA0.CCI2A	0	10	0	N/A
		TA0.2	1			
		A2/Veref-	X	X	1 (x = 2)	N/A
P1.3/UCB0SOMI/ UCB0SCL/MCLK/A3	3	P1.3 (I/O)	I: 0; O: 1	00	0	N/A
		UCB0SOMI/UCB0SCL	X	01	0	N/A
		MCLK	1	10	0	N/A
		A3	X	X	1 (x = 3)	N/A
P1.4/UCA0TXD/ UCA0SIMO/TA1.2/TCK/ A4 /VREF+	4	P1.4 (I/O)	I: 0; O: 1	00	0	Disabled
		UCA0TXD/UCA0SIMO	X	01	0	Disabled
		TA1.CCI2A	0	10	0	Disabled
		TA1.2	1			
		A4, VREF+	X	X	1 (x = 4)	Disabled
		JTAG TCK	X	X	X	TCK
P1.5/UCA0RXD/ UCA0SOMI/TA1.1/TMS/ A5	5	P1.5 (I/O)	I: 0; O: 1	00	0	Disabled
		UCA0RXD/UCA0SOMI	X	01	0	Disabled
		TA1.CCI1A	0	10	0	Disabled
		TA1.1	1			
		A5	X	X	1 (x = 5)	Disabled
		JTAG TMS	X	X	X	TMS
P1.6/UCA0CLK/ TA1CLK/TDI/TCLK/A6	6	P1.6 (I/O)	I: 0; O: 1	00	0	Disabled
		UCA0CLK	X	01		Disabled
		TA1CLK	0	10	0	Disabled
		A6	X	X	1 (x = 6)	Disabled
		JTAG TDI/TCLK	X	X	X	TDI/TCLK
P1.7/UCA0STE/SMCLK/ TDO/A7	7	P1.7 (I/O)	I: 0; O: 1	00	0	Disabled
		UCA0STE	X	01	0	Disabled
		SMCLK	1	10	0	Disabled
		A7	X	X	1 (x = 7)	Disabled
		JTAG TDO	X	X	X	TDO

(1) X = don't care
(2) Setting the ADCPCTLx bit in SYSCFG2 register disables both the output driver and input Schmitt trigger to prevent leakage when analog signals are applied.

Copyright © 2015–2019, Texas Instruments Incorporated

6.11.2 Port P2 (P2.0 to P2.2) Input/Output With Schmitt Trigger

Figure 6-2 shows the port diagram. Table 6-18 summarizes the selection of pin function.

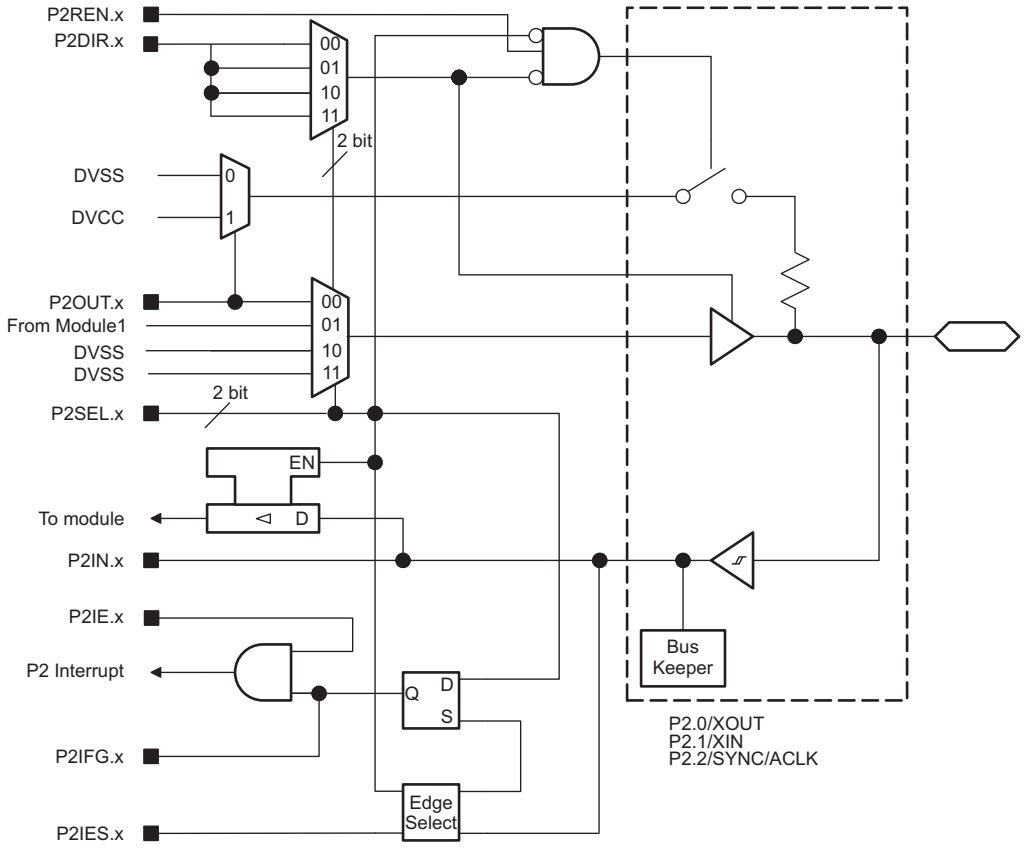


Figure 6-2. Port P2 (P2.0 to P2.2) Input/Output With Schmitt Trigger

Table 6-18. Port P2 (P2.0 to P2.2) Pin Functions

PIN NAME (P2.x)	x	FUNCTION	CONTROL BITS AND SIGNALS(1)	
			P2DIR.x	P2SELx
P2.0/XOUT	0	P2.0 (I/O)	I: 0; O: 1	00
		XOUT	X	01
P2.1/XIN	1	P2.1 (I/O)	I: 0; O: 1	00
		XIN	X	01
P2.2/SYNC/ACLK	2	P2.2 (I/O)	I: 0; O: 1	00
		SYNC	0	01
		ACLK	1	10

(1) X = don't care

6.11.3 Port P2 (P2.3 to P2.7) Input/Output With Schmitt Trigger

Figure 6-3 shows the port diagram. Table 6-19 summarizes the selection of pin function.

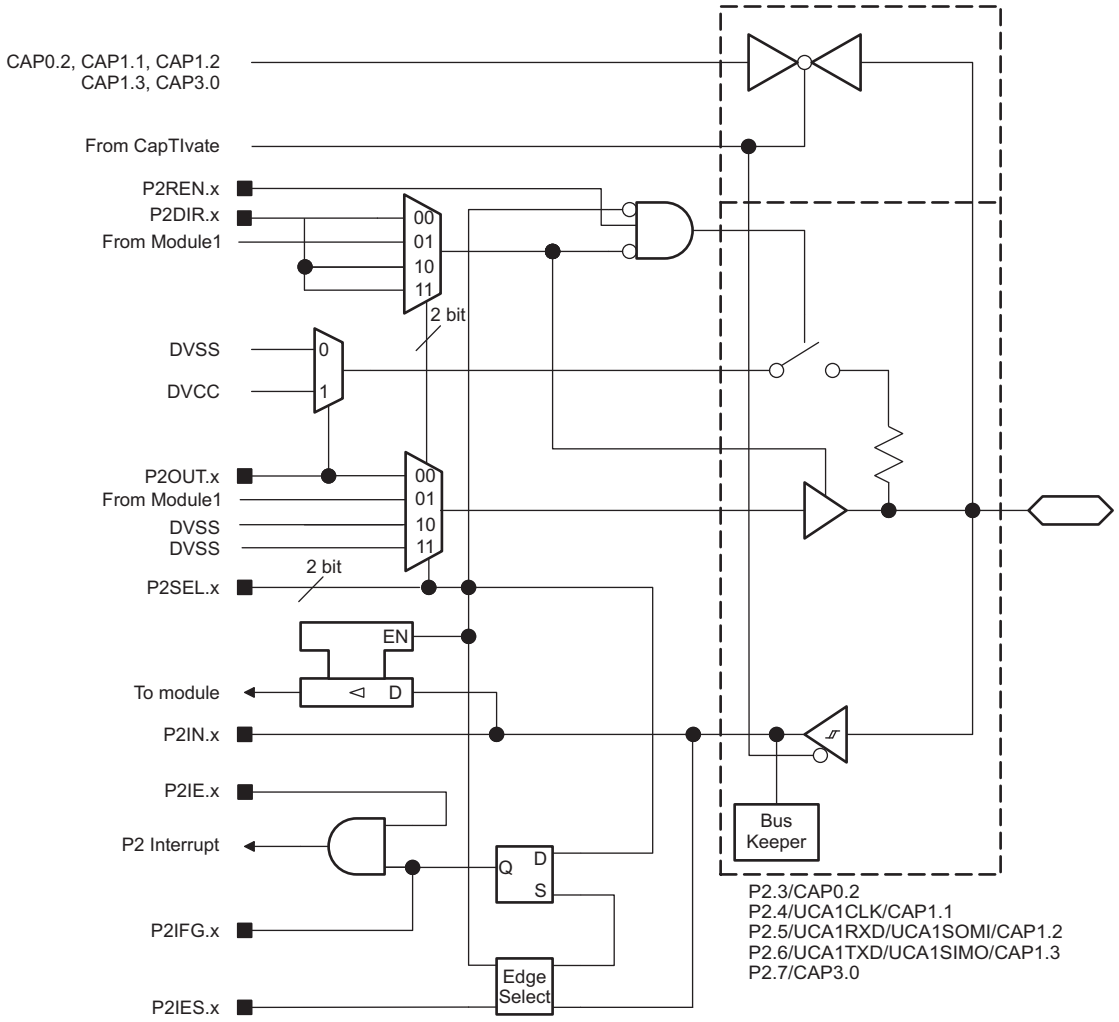


Figure 6-3. Port P2 (P2.3 to P2.7) Input/Output With Schmitt Trigger

Copyright © 2015–2019, Texas Instruments Incorporated

Table 6-19. Port P2 (P2.3 to P2.7) Pin Functions

PIN NAME (P2.x)	x	FUNCTION	CONTROL BITS AND SIGNALS(1)		
			P2DIR.x	P2SELx	ANALOG FUNCTION
P2.3/CAP0.2	3	P2.3 (I/O)	I: 0; O: 1	00	0
		CAP0.2	X	X	1
P2.4/UCA1CLK/ CAP1.1	4	P2.4 (I/O)	I: 0; O: 1	00	0
		UCA1CLK	X	01	0
		CAP1.1	X	X	1
P2.5/UCA1RXD/ UCA1SOMI/CAP1.2	5	P2.5 (I/O)	I: 0; O: 1	00	0
		UCA1RXD/UCA1SOMI	X	01	0
		CAP1.2	X	X	1
P2.6/UCA1TXD/ UCA1SIMO/CAP1.3	6	P2.6 (I/O)	I: 0; O: 1	00	0
		UCA1TXD/UCA1SIMO	X	01	0
		CAP1.3	X	X	1
P2.7/CAP3.0	7	P2.7 (I/O)	I: 0; O: 1	0	0
		CAP3.0	X	X	1

(1) X = don't care

Copyright © 2015–2019, Texas Instruments Incorporated

6.11.4 Port P3 (P3.0 to P3.2) Input/Output With Schmitt Trigger

Figure 6-4 shows the port diagram. Table 6-20 summarizes the selection of pin function.

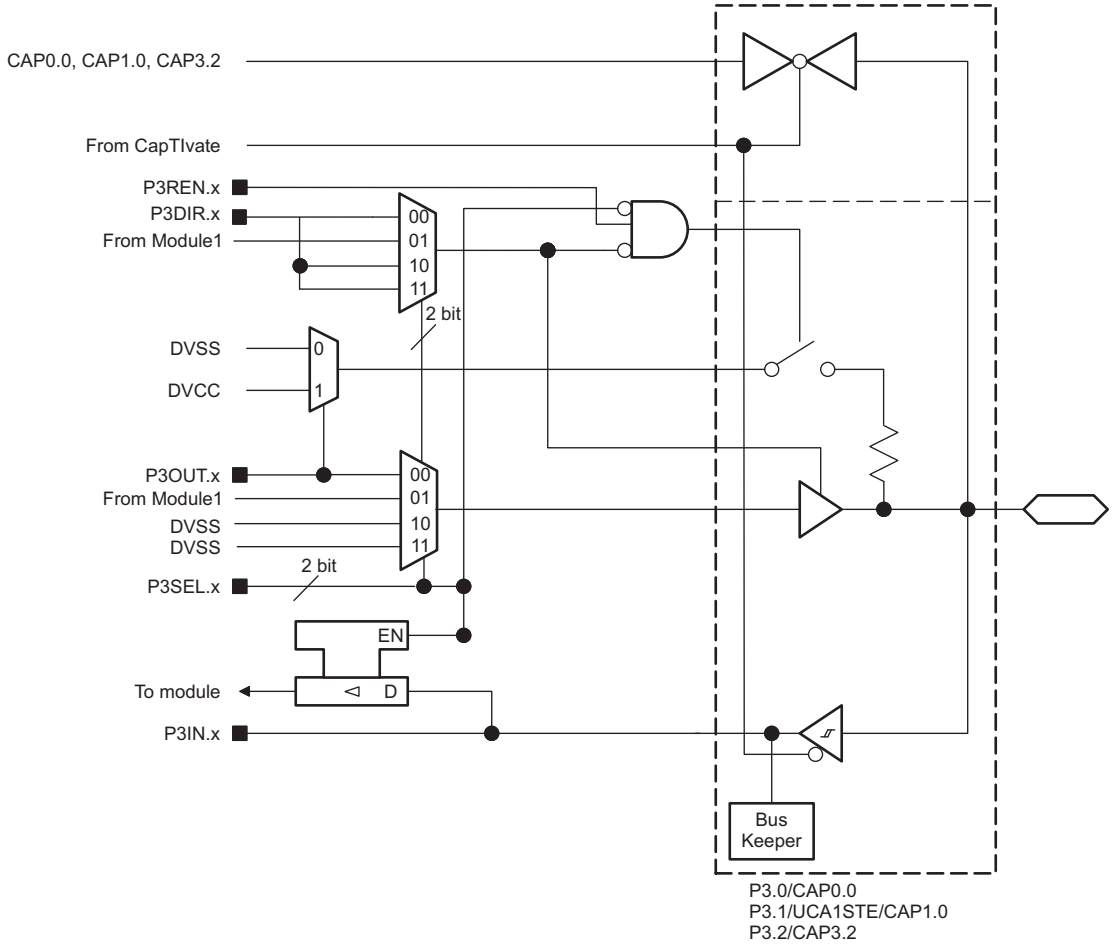


Figure 6-4. Port P3 (P3.0 to P3.2) Input/Output With Schmitt Trigger

NOTE

CapTIvate shared with I/Os configuration

The CapTIvate function and GPIOs are powered by different power supplies (1.5 V and 3.3 V, respectively).

To prevent pad damage when changing the function, TI recommends checking the external application circuit of each pad before enabling the alternate function.

Copyright © 2015–2019, Texas Instruments Incorporated

Table 6-20. Port P3 (P3.0 to P3.2) Pin Functions

PIN NAME (P3.x)	x	FUNCTION	CONTROL BITS AND SIGNALS(1)		
			P3DIR.x	P3SEL.x	ANALOG FUNCTION
P3.0/CAP0.0	0	P3.0 (I/O)	I: 0; O: 1	00	0
		CAP0.0	X	X	1
P3.1/UCA1STE/ CAP1.0	1	P3.1 (I/O)	I: 0; O: 1	00	0
		UCA1STE	X	01	0
		CAP1.0	X	X	1
P3.2/CAP3.2	2	P3.2 (I/O)	I: 0; O: 1	00	0
		CAP3.2	X	X	1

(1) X = don't care

6.12 Device Descriptors

Table 6-21 lists the Device IDs of the devices. Table 6-22 lists the contents of the device descriptor tag-length-value (TLV) structure for the devices.

Table 6-21. Device IDs

DEVICE	DEVICE ID	
	1A05h	1A04h
MSP430FR2633	82h	3Ch
MSP430FR2533	82h	3Dh
MSP430FR2632	82h	3Eh
MSP430FR2532	82h	3Fh

Table 6-22. Device Descriptors

DESCRIPTION		MSP430FR2633, MSP430FR2632, MSP430FR2533, MSP430FR2532	
		ADDRESS	VALUE
Information Block	Info length	1A00h	06h
	CRC length	1A01h	06h
	CRC value(1)	1A02h	Per unit
		1A03h	Per unit
	Device ID	1A04h	See Table 6-21.
		1A05h	
	Hardware revision	1A06h	Per unit
	Firmware revision	1A07h	Per unit
Die Record	Die record tag	1A08h	08h
	Die record length	1A09h	0Ah
	Lot wafer ID	1A0Ah	Per unit
		1A0Bh	Per unit
		1A0Ch	Per unit
		1A0Dh	Per unit
	Die X position	1A0Eh	Per unit
		1A0Fh	Per unit
	Die Y position	1A10h	Per unit
		1A11h	Per unit
	Test result	1A12h	Per unit
		1A13h	Per unit
ADC Calibration	ADC calibration tag	1A14h	Per unit
	ADC calibration length	1A15h	Per unit
	ADC gain factor	1A16h	Per unit
		1A17h	Per unit
	ADC offset	1A18h	Per unit
		1A19h	Per unit
	ADC 1.5-V reference temperature 30°C	1A1Ah	Per unit
		1A1Bh	Per unit
	ADC 1.5-V reference temperature 85°C	1A1Ch	Per unit
		1A1Dh	Per unit

(1) The CRC value covers the checksum from 0x1A04h to 0x1AF5h by applying the CRC-CCITT-16 polynomial of $x^{16} + x^{12} + x^5 + 1$.

Copyright © 2015–2019, Texas Instruments Incorporated

Table 6-22. Device Descriptors (continued)

DESCRIPTION		MSP430FR2633, MSP430FR2632, MSP430FR2533, MSP430FR2532	
		ADDRESS	VALUE
Reference and DCO Calibration	Calibration tag	1A1Eh	12h
	Calibration length	1A1Fh	04h
	1.5-V reference factor	1A20h	Per unit
		1A21h	Per unit
	DCO tap setting for 16 MHz, temperature 30°C(2)	1A22h	Per unit
		1A23h	Per unit

(2) This value can be directly loaded into DCO bits in CSCTL0 registers to get accurate 16-MHz frequency at room temperature, especially when the MCU exits from LPM3 and below. TI suggests using the predivider to decrease the frequency if the temperature drift might result an overshoot beyond 16 MHz.

6.13 Memory

6.13.1 Memory Organization

Table 6-23 summarizes the memory map of the devices.

Table 6-23. Memory Organization

	ACCESS	MSP430FR2633	MSP430FR2632	MSP430FR2533	MSP430FR2532
Memory (FRAM) Main: interrupt vectors and signatures Main: code memory	Read/Write (Optional Write Protect)(1)	15KB FFFFh to FF80h FFFFh to C400h	8KB FFFFh to FF80h FFFFh to E000h	15KB FFFFh to FF80h FFFFh to C400h	8KB FFFFh to FF80h FFFFh to E000h
RAM	Read/Write	4KB 2FFFh to 2000h	2KB 27FFh to 2000h	2KB 27FFh to 2000h	1KB 23FFh to 2000h
Information Memory (FRAM)	Read/Write (Optional Write Protect)(2)	512 bytes 19FFh to 1800h	512 bytes 19FFh to 1800h	512 bytes 19FFh to 1800h	512 bytes 19FFh to 1800h
Bootstrap loader (BSL1) Memory (ROM)	Read only	2KB 17FFh to 1000h	2KB 17FFh to 1000h	2KB 17FFh to 1000h	2KB 17FFh to 1000h
Bootstrap loader (BSL2) Memory (ROM)	Read only	1KB FFFFFh to FFC00h	1KB FFFFFh to FFC00h	1KB FFFFFh to FFC00h	1KB FFFFFh to FFC00h
CapTIvate Libraries and Driver Libraries (ROM)	Read only	12KB 6FFFh to 4000h	12KB 6FFFh to 4000h	12KB 6FFFh to 4000h	12KB 6FFFh to 4000h
Peripherals	Read/Write	4KB 0FFFh to 0000h	4KB 0FFFh to 0000h	4KB 0FFFh to 0000h	4KB 0FFFh to 0000h

(1) The Program FRAM can be write protected by setting the PFWP bit in the SYSCFG0 register. See the SYS chapter in the *MSP430FR4xx and MSP430FR2xx Family User's Guide* for more details.
(2) The Information FRAM can be write protected by setting the DFWP bit in the SYSCFG0 register. See the SYS chapter in the *MSP430FR4xx and MSP430FR2xx Family User's Guide* for more details.

6.13.2 Peripheral File Map

Table 6-24 lists the available peripherals and the register base address for each. Table 6-25 to list the registers and address offsets for each peripheral.

Table 6-24. Peripherals Summary

MODULE NAME	BASE ADDRESS	SIZE
Special Functions (See Table 6-25)	0100h	0010h
PMM (See Table 6-26)	0120h	0020h
SYS (See Table 6-27)	0140h	0040h
CS (See Table 6-28)	0180h	0020h
FRAM (See Table 6-29)	01A0h	0010h
CRC (See Table 6-30)	01C0h	0008h
WDT (See Table 6-31)	01CCh	0002h
Port P1, P2 (See Table 6-32)	0200h	0020h
Port P3 (See Table 6-33)	0220h	0020h
RTC (See Table 6-34)	0300h	0010h
Timer0_A3 (See Table 6-35)	0380h	0030h
Timer1_A3 (See Table 6-36)	03C0h	0030h
Timer2_A2 (See Table 6-37)	0400h	0030h
Timer3_A2 (See Table 6-38)	0440h	0030h
MPY32 (See Table 6-39)	04C0h	0030h
eUSCI_A0 (See Table 6-40)	0500h	0020h
eUSCI_A1 (See Table 6-41)	0520h	0020h
eUSCI_B0 (See Table 6-42)	0540h	0030h
Backup Memory (See Table 6-43)	0660h	0020h
ADC (See Table 6-44)	0700h	0040h
CapTIvate (See CapTivate Design Center for details)	0A00h	0200h

Table 6-25. Special Function Registers (Base Address: 0100h)

REGISTER DESCRIPTION	ACRONYM	OFFSET
SFR interrupt enable	SFRIE1	00h
SFR interrupt flag	SFRIFG1	02h
SFR reset pin control	SFRRPCR	04h

Table 6-26. PMM Registers (Base Address: 0120h)

REGISTER DESCRIPTION	ACRONYM	OFFSET
PMM control 0	PMMCTL0	00h
PMM control 1	PMMCTL1	02h
PMM control 2	PMMCTL2	04h
PMM interrupt flags	PMMIFG	0Ah
PM5 control 0	PM5CTL0	10h

Copyright © 2015–2019, Texas Instruments Incorporated

Table 6-27. SYS Registers (Base Address: 0140h)

REGISTER DESCRIPTION	ACRONYM	OFFSET
System control	SYSCTL	00h
Bootloader configuration area	SYSBSLC	02h
JTAG mailbox control	SYSJMBC	06h
JTAG mailbox input 0	SYSJMBI0	08h
JTAG mailbox input 1	SYSJMBI1	0Ah
JTAG mailbox output 0	SYSJMBO0	0Ch
JTAG mailbox output 1	SYSJMBO1	0Eh
Bus error vector generator	SYSBERRIV	18h
User NMI vector generator	SYSUNIV	1Ah
System NMI vector generator	SYSSNIV	1Ch
Reset vector generator	SYSRSTIV	1Eh
System configuration 0	SYSCFG0	20h
System configuration 1	SYSCFG1	22h
System configuration 2	SYSCFG2	24h

Table 6-28. CS Registers (Base Address: 0180h)

REGISTER DESCRIPTION	ACRONYM	OFFSET
CS control 0	CSCTL0	00h
CS control 1	CSCTL1	02h
CS control 2	CSCTL2	04h
CS control 3	CSCTL3	06h
CS control 4	CSCTL4	08h
CS control 5	CSCTL5	0Ah
CS control 6	CSCTL6	0Ch
CS control 7	CSCTL7	0Eh
CS control 8	CSCTL8	10h

Table 6-29. FRAM Registers (Base Address: 01A0h)

REGISTER DESCRIPTION	ACRONYM	OFFSET
FRAM control 0	FRCTL0	00h
General control 0	GCCTL0	04h
General control 1	GCCTL1	06h

Table 6-30. CRC Registers (Base Address: 01C0h)

REGISTER DESCRIPTION	ACRONYM	OFFSET
CRC data input	CRC16DI	00h
CRC data input reverse byte	CRCDIRB	02h
CRC initialization and result	CRCINIRES	04h
CRC result reverse byte	CRCRESR	06h

Table 6-31. WDT Registers (Base Address: 01CCh)

REGISTER DESCRIPTION	ACRONYM	OFFSET
Watchdog timer control	WDTCTL	00h

Copyright © 2015–2019, Texas Instruments Incorporated

Table 6-32. Port P1, P2 Registers (Base Address: 0200h)

REGISTER DESCRIPTION	ACRONYM	OFFSET
Port P1 input	P1IN	00h
Port P1 output	P1OUT	02h
Port P1 direction	P1DIR	04h
Port P1 pulling enable	P1REN	06h
Port P1 selection 0	P1SEL0	0Ah
Port P1 selection 1	P1SEL1	0Ch
Port P1 interrupt vector word	P1IV	0Eh
Port P1 complement selection	P1SELC	16h
Port P1 interrupt edge select	P1IES	18h
Port P1 interrupt enable	P1IE	1Ah
Port P1 interrupt flag	P1IFG	1Ch
Port P2 input	P2IN	01h
Port P2 output	P2OUT	03h
Port P2 direction	P2DIR	05h
Port P2 pulling enable	P2REN	07h
Port P2 selection 0	P2SEL0	0Bh
Port P2 selection 1	P2SEL1	0Dh
Port P2 interrupt vector word	P2IV	1Eh
Port P2 complement selection	P2SELC	17h
Port P2 interrupt edge select	P2IES	19h
Port P2 interrupt enable	P2IE	1Bh
Port P2 interrupt flag	P2IFG	1Dh

Table 6-33. Port P3 Registers (Base Address: 0220h)

REGISTER DESCRIPTION	ACRONYM	OFFSET
Port P3 input	P3IN	00h
Port P3 output	P3OUT	02h
Port P3 direction	P3DIR	04h
Port P3 pulling enable	P3REN	06h
Port P3 selection 0	P3SEL0	0Ah
Port P3 selection 1	P3SEL1	0
Port P3 complement selection	P3SELC	16h

Table 6-34. RTC Registers (Base Address: 0300h)

REGISTER DESCRIPTION	ACRONYM	OFFSET
RTC control	RTCCTL	00h
RTC interrupt vector	RTCIV	04h
RTC modulo	RTCMOD	08h
RTC counter	RTCCNT	0Ch

Copyright © 2015–2019, Texas Instruments Incorporated

Table 6-35. Timer0_A3 Registers (Base Address: 0380h)

REGISTER DESCRIPTION	ACRONYM	OFFSET
TA0 control	TA0CTL	00h
Capture/compare control 0	TA0CCTL0	02h
Capture/compare control 1	TA0CCTL1	04h
Capture/compare control 2	TA0CCTL2	06h
TA0 counter	TA0R	10h
Capture/compare 0	TA0CCR0	12h
Capture/compare 1	TA0CCR1	14h
Capture/compare 2	TA0CCR2	16h
TA0 expansion 0	TA0EX0	20h
TA0 interrupt vector	TA0IV	2Eh

Table 6-36. Timer1_A3 Registers (Base Address: 03C0h)

REGISTER DESCRIPTION	ACRONYM	OFFSET
TA1 control	TA1CTL	00h
Capture/compare control 0	TA1CCTL0	02h
Capture/compare control 1	TA1CCTL1	04h
Capture/compare control 2	TA1CCTL2	06h
TA1 counter	TA1R	10h
Capture/compare 0	TA1CCR0	12h
Capture/compare 1	TA1CCR1	14h
Capture/compare 2	TA1CCR2	16h
TA1 expansion 0	TA1EX0	20h
TA1 interrupt vector	TA1IV	2Eh

Table 6-37. Timer2_A2 Registers (Base Address: 0400h)

REGISTER DESCRIPTION	ACRONYM	OFFSET
TA2 control	TA2CTL	00h
Capture/compare control 0	TA2CCTL0	02h
Capture/compare control 1	TA2CCTL1	04h
TA2 counter	TA2R	10h
Capture/compare 0	TA2CCR0	12h
Capture/compare 1	TA2CCR1	14h
TA2 expansion 0	TA2EX0	20h
TA2 interrupt vector	TA2IV	2Eh

Table 6-38. Timer3_A2 Registers (Base Address: 0440h)

REGISTER DESCRIPTION	ACRONYM	OFFSET
TA3 control	TA3CTL	00h
Capture/compare control 0	TA3CCTL0	02h
Capture/compare control 1	TA3CCTL1	04h
TA3 counter	TA3R	10h
Capture/compare 0	TA3CCR0	12h
Capture/compare 1	TA3CCR1	14h
TA3 expansion 0	TA3EX0	20h
TA3 interrupt vector	TA3IV	2Eh

Copyright © 2015–2019, Texas Instruments Incorporated

Table 6-39. MPY32 Registers (Base Address: 04C0h)

REGISTER DESCRIPTION	ACRONYM	OFFSET
16-bit operand 1 – multiply	MPY	00h
16-bit operand 1 – signed multiply	MPYS	02h
16-bit operand 1 – multiply accumulate	MAC	04h
16-bit operand 1 – signed multiply accumulate	MACS	06h
16-bit operand 2	OP2	08h
16 × 16 result low word	RESLO	0Ah
16 × 16 result high word	RESHI	0Ch
16 × 16 sum extension	SUMEXT	0Eh
32-bit operand 1 – multiply low word	MPY32L	10h
32-bit operand 1 – multiply high word	MPY32H	12h
32-bit operand 1 – signed multiply low word	MPYS32L	14h
32-bit operand 1 – signed multiply high word	MPYS32H	16h
32-bit operand 1 – multiply accumulate low word	MAC32L	18h
32-bit operand 1 – multiply accumulate high word	MAC32H	1Ah
32-bit operand 1 – signed multiply accumulate low word	MACS32L	1Ch
32-bit operand 1 – signed multiply accumulate high word	MACS32H	1Eh
32-bit operand 2 – low word	OP2L	20h
32-bit operand 2 – high word	OP2H	22h
32 × 32 result 0 – least significant word	RES0	24h
32 × 32 result 1	RES1	26h
32 × 32 result 2	RES2	28h
32 × 32 result 3 – most significant word	RES3	2Ah
MPY32 control 0	MPY32CTL0	2Ch

Table 6-40. eUSCI_A0 Registers (Base Address: 0500h)

REGISTER DESCRIPTION	ACRONYM	OFFSET
eUSCI_A control word 0	UCA0CTLW0	00h
eUSCI_A control word 1	UCA0CTLW1	02h
eUSCI_A control rate 0	UCA0BR0	06h
eUSCI_A control rate 1	UCA0BR1	07h
eUSCI_A modulation control	UCA0MCTLW	08h
eUSCI_A status	UCA0STAT	0Ah
eUSCI_A receive buffer	UCA0RXBUF	0Ch
eUSCI_A transmit buffer	UCA0TXBUF	0Eh
eUSCI_A LIN control	UCA0ABCTL	10h
eUSCI_A IrDA transmit control	lUCA0IRTCTL	12h
eUSCI_A IrDA receive control	lUCA0IRRCTL	13h
eUSCI_A interrupt enable	UCA0IE	1Ah
eUSCI_A interrupt flags	UCA0IFG	1Ch
eUSCI_A interrupt vector word	UCA0IV	1Eh

Copyright © 2015–2019, Texas Instruments Incorporated

Table 6-41. eUSCI_A1 Registers (Base Address: 0520h)

REGISTER DESCRIPTION	ACRONYM	OFFSET
eUSCI_A control word 0	UCA1CTLW0	00h
eUSCI_A control word 1	UCA1CTLW1	02h
eUSCI_A control rate 0	UCA1BR0	06h
eUSCI_A control rate 1	UCA1BR1	07h
eUSCI_A modulation control	UCA1MCTLW	08h
eUSCI_A status	UCA1STAT	0Ah
eUSCI_A receive buffer	UCA1RXBUF	0Ch
eUSCI_A transmit buffer	UCA1TXBUF	0Eh
eUSCI_A LIN control	UCA1ABCTL	10h
eUSCI_A IrDA transmit control	lUCA1IRTCTL	12h
eUSCI_A IrDA receive control	lUCA1IRRCTL	13h
eUSCI_A interrupt enable	UCA1IE	1Ah
eUSCI_A interrupt flags	UCA1IFG	1Ch
eUSCI_A interrupt vector word	UCA1IV	1Eh

Table 6-42. eUSCI_B0 Registers (Base Address: 0540h)

REGISTER DESCRIPTION	ACRONYM	OFFSET
eUSCI_B control word 0	UCB0CTLW0	00h
eUSCI_B control word 1	UCB0CTLW1	02h
eUSCI_B bit rate 0	UCB0BR0	06h
eUSCI_B bit rate 1	UCB0BR1	07h
eUSCI_B status word	UCB0STATW	08h
eUSCI_B byte counter threshold	UCB0TBCNT	0Ah
eUSCI_B receive buffer	UCB0RXBUF	0Ch
eUSCI_B transmit buffer	UCB0TXBUF	0Eh
eUSCI_B I2C own address 0	UCB0I2COA0	14h
eUSCI_B I2C own address 1	UCB0I2COA1	16h
eUSCI_B I2C own address 2	UCB0I2COA2	18h
eUSCI_B I2C own address 3	UCB0I2COA3	1Ah
eUSCI_B receive address	UCB0ADDRX	1Ch
eUSCI_B address mask	UCB0ADDMASK	1Eh
eUSCI_B I2C slave address	UCB0I2CSA	20h
eUSCI_B interrupt enable	UCB0IE	2Ah
eUSCI_B interrupt flags	UCB0IFG	2Ch
eUSCI_B interrupt vector word	UCB0IV	2Eh

Copyright © 2015–2019, Texas Instruments Incorporated

Table 6-43. Backup Memory Registers (Base Address: 0660h)

REGISTER DESCRIPTION	ACRONYM	OFFSET
Backup memory 0	BAKMEM0	00h
Backup memory 1	BAKMEM1	02h
Backup memory 2	BAKMEM2	04h
Backup memory 3	BAKMEM3	06h
Backup memory 4	BAKMEM4	08h
Backup memory 5	BAKMEM5	0Ah
Backup memory 6	BAKMEM6	0Ch
Backup memory 7	BAKMEM7	0Eh
Backup memory 8	BAKMEM8	10h
Backup memory 9	BAKMEM9	12h
Backup memory 10	BAKMEM10	14h
Backup memory 11	BAKMEM11	16h
Backup memory 12	BAKMEM12	18h
Backup memory 13	BAKMEM13	1Ah
Backup memory 14	BAKMEM14	1Ch
Backup memory 15	BAKMEM15	1Eh

Table 6-44. ADC Registers (Base Address: 0700h)

REGISTER DESCRIPTION	ACRONYM	OFFSET
ADC control 0	ADCCTL0	00h
ADC control 1	ADCCTL1	02h
ADC control 2	ADCCTL2	04h
ADC window comparator low threshold	ADCLO	06h
ADC window comparator high threshold	ADCHI	08h
ADC memory control 0	ADCMCTL0	0Ah
ADC conversion memory	ADCMEM0	12h
ADC interrupt enable	ADCIE	1Ah
ADC interrupt flags	ADCIFG	1Ch
ADC interrupt vector word	ADCIV	1Eh

Copyright © 2015–2019, Texas Instruments Incorporated

6.14 Identification

6.14.1 Revision Identification

The device revision information is included as part of the top-side marking on the device package. The device-specific errata sheet describes these markings (see 8.4).

The hardware revision is also stored in the Device Descriptor structure in the Information Block section. For details on this value, see the Hardware Revision entries in Table 6-22.

6.14.2 Device Identification

The device type can be identified from the top-side marking on the device package. The device-specific errata sheet describes these markings (see 8.4).

A device identification value is also stored in the Device Descriptor structure in the Information Block section. For details on this value, see the Device ID entries in Table 6-22.

6.14.3 JTAG Identification

Programming through the JTAG interface, including reading and identifying the JTAG ID, is described in *MSP430 Programming With the JTAG Interface*.

Copyright © 2015–2019, Texas Instruments Incorporated

7 Applications, Implementation, and Layout

NOTE

Information in the following Applications section is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

7.1 Device Connection and Layout Fundamentals

This section discusses the recommended guidelines when designing with the MSP430 devices. These guidelines are to make sure that the device has proper connections for powering, programming, debugging, and optimum analog performance.

7.1.1 Power Supply Decoupling and Bulk Capacitors

TI recommends connecting a combination of a 10-µF and a 100-nF low-ESR ceramic decoupling capacitor to the DVCC and DVSS pins (see Figure 7-1). Higher-value capacitors may be used but can impact supply rail ramp-up time. Decoupling capacitors must be placed as close as possible to the pins that they decouple (within a few millimeters). Additionally, TI recommends separated grounds with a single-point connection for better noise isolation from digital-to-analog circuits on the board and to achieve high analog accuracy.

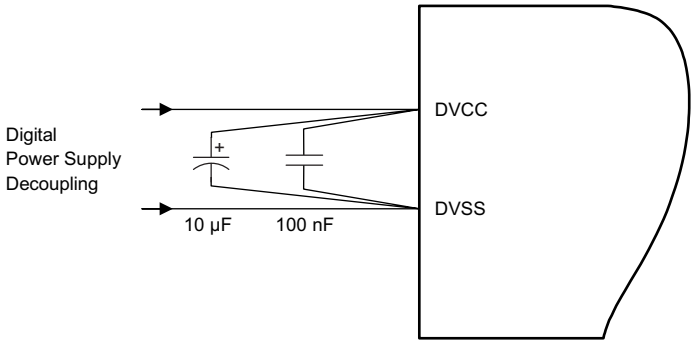


Figure 7-1. Power Supply Decoupling

7.1.2 External Oscillator

This device supports only a low-frequency crystal (32 kHz) on the XIN and XOUT pins. External bypass capacitors for the crystal oscillator pins are required.

It is also possible to apply digital clock signals to the XIN input pin that meet the specifications of the respective oscillator if the appropriate XT1BYPASS mode is selected. In this case, the associated XOUT pin can be used for other purposes. If the XIN and XOUT pins are not used, they must be terminated according to Section 4.6.

Figure 7-2 shows a typical connection diagram.

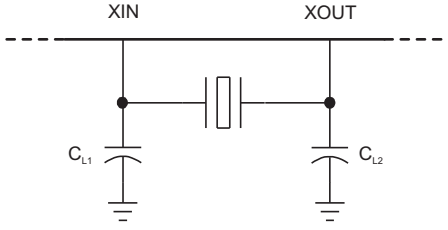


Figure 7-2. Typical Crystal Connection

Copyright © 2015–2019, Texas Instruments Incorporated

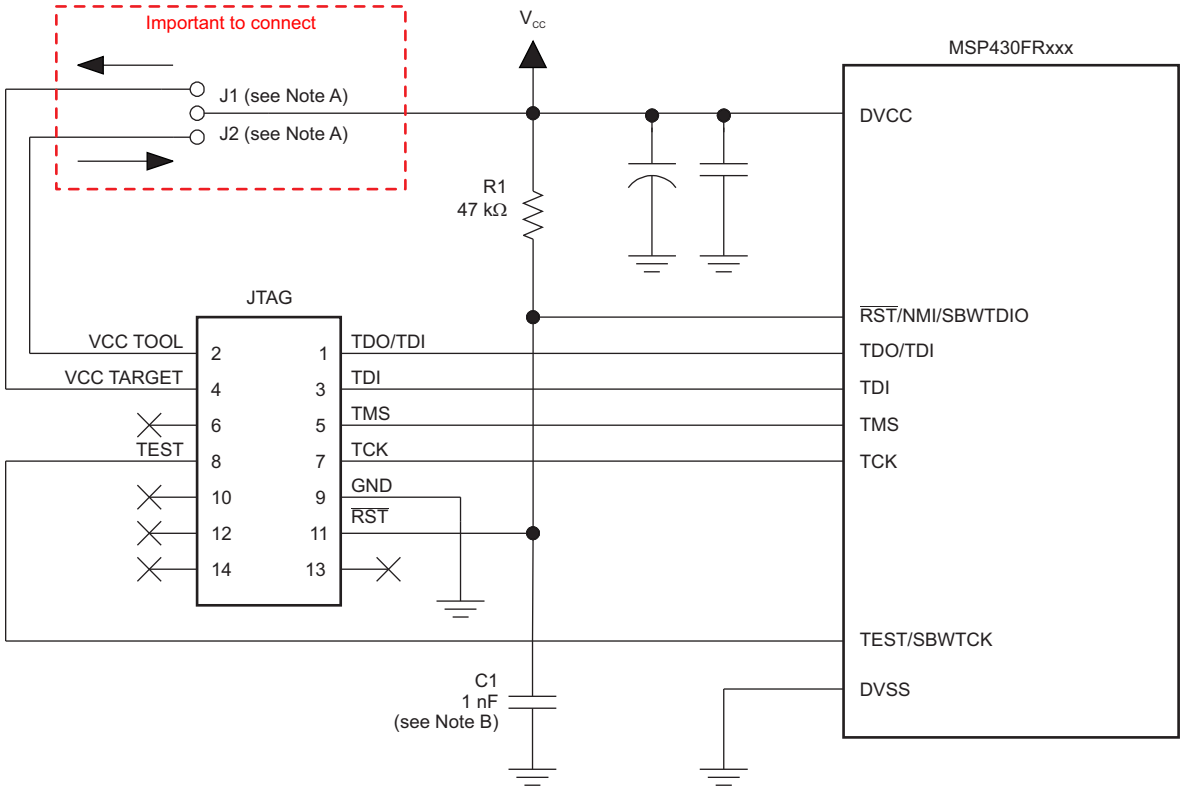
See *MSP430 32-kHz Crystal Oscillators* for more information on selecting, testing, and designing a crystal oscillator with the MSP430 devices.

7.1.3 JTAG

With the proper connections, the debugger and a hardware JTAG interface (such as the MSP-FET or MSP-FET430UIF) can be used to program and debug code on the target board. In addition, the connections also support the MSP-GANG production programmers, thus providing an easy way to program prototype boards, if desired. Figure 7-3 shows the connections between the 14-pin JTAG connector and the target device required to support in-system programming and debugging for 4-wire JTAG communication. Figure 7-4 shows the connections for 2-wire JTAG mode (Spy-Bi-Wire).

The connections for the MSP-FET and MSP-FET430UIF interface modules and the MSP-GANG are identical. Both can supply V_{CC} to the target board (through pin 2). In addition, the MSP-FET and MSP-FET430UIF interface modules and MSP-GANG have a V_{CC} sense feature that, if used, requires an alternate connection (pin 4 instead of pin 2). The V_{CC} sense feature detects the local V_{CC} present on the target board (that is, a battery or other local power supply) and adjusts the output signals accordingly. Figure 7-3 and Figure 7-4 show a jumper block that supports both scenarios of supplying V_{CC} to the target board. If this flexibility is not required, the desired V_{CC} connections may be hard-wired to eliminate the jumper block. Pins 2 and 4 must not be connected at the same time.

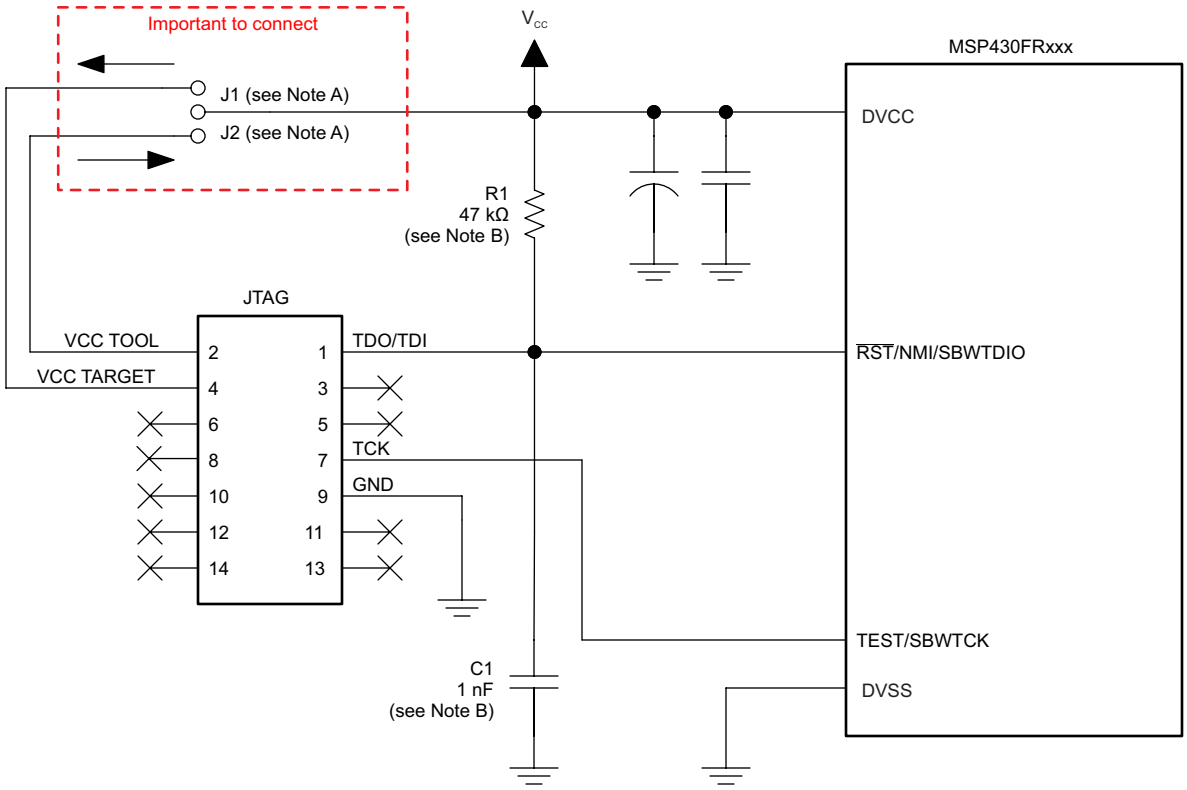
For additional design information regarding the JTAG interface, see the *MSP430 Hardware Tools User's Guide*.



A. If a local target power supply is used, make connection J1. If power from the debug or programming adapter is used, make connection J2.

B. The upper limit for C1 is 1.1 nF when using current TI tools.

Figure 7-3. Signal Connections for 4-Wire JTAG Communication



A. Make connection J1 if a local target power supply is used, or make connection J2 if the target is powered from the debug or programming adapter.

B. The device $\overline{\text{RST}}$/NMI/SBWTDIO pin is used in 2-wire mode for bidirectional communication with the device during JTAG access, and any capacitance that is attached to this signal may affect the ability to establish a connection with the device. The upper limit for C1 is 1.1 nF when using current TI tools.

Figure 7-4. Signal Connections for 2-Wire JTAG Communication (Spy-Bi-Wire)

7.1.4 Reset

The reset pin can be configured as a reset function (default) or as an NMI function in the Special Function Register (SFR), SFRRPCR.

In reset mode, the $\overline{\text{RST}}$/NMI pin is active low, and a pulse applied to this pin that meets the reset timing specifications generates a BOR-type device reset.

Setting SYSNMI causes the $\overline{\text{RST}}$/NMI pin to be configured as an external NMI source. The external NMI is edge sensitive, and its edge is selectable by SYSNMIIES. Setting the NMIIE enables the interrupt of the external NMI. When an external NMI event occurs, the NMIIFG is set.

The $\overline{\text{RST}}$/NMI pin can have either a pullup or pulldown that is enabled or not. SYSRSTUP selects either pullup or pulldown, and SYSRSTRE causes the pullup (default) or pulldown to be enabled (default) or not. If the $\overline{\text{RST}}$/NMI pin is unused, it is required either to select and enable the internal pullup or to connect an external 47-kΩ pullup resistor to the $\overline{\text{RST}}$/NMI pin with a 1.1-nF pulldown capacitor. The pulldown capacitor should not exceed 1.1 nF when using devices with Spy-Bi-Wire interface in Spy-Bi-Wire mode or in 4-wire JTAG mode with TI tools like FET interfaces or GANG programmers.

See the *MSP430FR4xx and MSP430FR2xx Family User's Guide* for more information on the referenced control registers and bits.

7.1.5 Unused Pins

For details on the connection of unused pins, see Section 4.6.

Copyright © 2015–2019, Texas Instruments Incorporated

7.1.6 General Layout Recommendations

- Proper grounding and short traces for external crystal to reduce parasitic capacitance. For recommended layout guidelines, see *MSP430 32-kHz Crystal Oscillators*.
- Proper bypass capacitors on DVCC and reference pins, if used.
- Avoid routing any high-frequency signal close to an analog signal line. For example, keep digital switching signals such as PWM or JTAG signals away from the oscillator circuit and ADC signals.
- Proper ESD level protection should be considered to protect the device from unintended high-voltage electrostatic discharge. For guidelines see *MSP430 System-Level ESD Considerations*.

7.1.7 Do's and Don'ts

During power up, power down, and device operation, DVCC must not exceed the limits specified in Section 5.1. Exceeding the specified limits may cause malfunction of the device including erroneous writes to RAM and FRAM.

7.2 Peripheral- and Interface-Specific Design Information

7.2.1 ADC Peripheral

7.2.1.1 Partial Schematic

Figure 7-5 shows the recommended decoupling circuit when an external voltage reference is used.

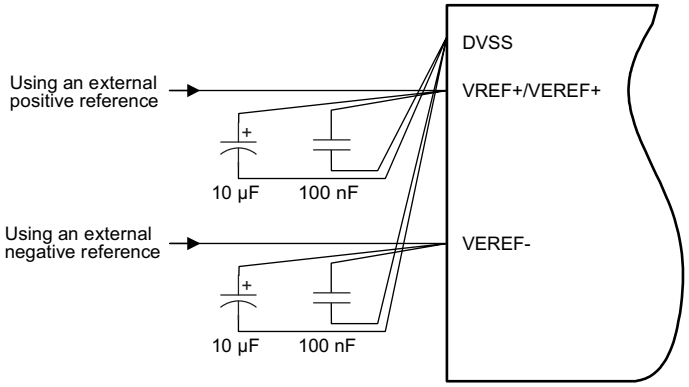


Figure 7-5. ADC Grounding and Noise Considerations

7.2.1.2 Design Requirements

As with any high-resolution ADC, appropriate PCB layout and grounding techniques must be followed to eliminate ground loops, unwanted parasitic effects, and noise.

Ground loops are formed when return current from the ADC flows through paths that are common with other analog or digital circuitry. If care is not taken, this current can generate small unwanted offset voltages that can add to or subtract from the reference or input voltages of the ADC. The general guidelines in Section 7.1.1 combined with the connections shown in Figure 7-5 prevent this.

Quickly switching digital signals and noisy power supply lines can corrupt the conversion results, so keep the ADC input trace shielded from those digital and power supply lines. Putting the MCU in low-power mode during the ADC conversion improves the ADC performance in a noisy environment. If the device includes the analog power pair inputs (AVCC and AVSS), TI recommends a noise-free design using separate analog and digital ground planes with a single-point connection to achieve high accuracy.

Figure 7-5 shows the recommended decoupling circuit when an external voltage reference is used. The internal reference module has a maximum drive current as described in the sections *ADC Pin Enable* and *1.2-V Reference Settings* of the *MSP430FR4xx and MSP430FR2xx Family User's Guide*.

Copyright © 2015–2019, Texas Instruments Incorporated

The reference voltage must be a stable voltage for accurate measurements. The capacitor values that are selected in the general guidelines filter out the high- and low-frequency ripple before the reference voltage enters the device. In this case, the 10-µF capacitor buffers the reference pin and filters any low-frequency ripple. A bypass capacitor of 100 nF filters out any high-frequency noise.

7.2.1.3 Layout Guidelines

Components that are shown in the partial schematic (see Figure 7-5) should be placed as close as possible to the respective device pins to avoid long traces, because they add additional parasitic capacitance, inductance, and resistance on the signal.

Avoid routing analog input signals close to a high-frequency pin (for example, a high-frequency PWM), because the high-frequency switching can be coupled into the analog signal.

7.2.2 CapTIvate Peripheral

This section provides a brief introduction to the CapTIvate technology with examples of PCB layout and performance from the design kit. A more detailed description of the CapTIvate technology and the tools needed to be successful, application development tools, hardware design guides, and software library, can be found in the CapTIvate™ Technology Guide.

7.2.2.1 Device Connection and Layout Fundamentals

To learn more on how to design the CapTIvate Technology, see the Capacitive Touch Design Flow for MSP430™ MCUs With CapTIvate™ Technology application report.

Copyright © 2015–2019, Texas Instruments Incorporated

7.2.2.2 Measurements

The following measurements are taken from the CapTIvate Technology Design Center, using the CAPTIVATE-PHONE and CAPTIVATE-BSWP panels. Unless otherwise stated, the settings used are the out-of-box settings, which can be found in the example projects. The intent of these measurements is to show performance in a configuration that is readily available and reproducible.

Figure 7-6. CAPTIVATE-PHONE and CAPTIVATE-BSWP Panels

7.2.2.2.1 SNR

The Sensitivity, SNR, and Design Margin in Capacitive Touch Applications application report provides a specific view for analyzing the signal-to-noise ratio of each element.

7.2.2.2.2 Sensitivity

To show sensitivity, in terms of farads, the internal reference capacitor is used as the change in capacitance. In the mutual-capacitance case, the 0.1-pF capacitor is used. In the self-capacitance case, the 1-pF reference capacitor is used. For simplicity, the results for only button 1 on both the CAPTIVATE-PHONE and CAPTIVATE-BSWP panels are reported in Table 7-1.

Table 7-1. Button Sensitivity

CONVERSION COUNT	CONVERSION GAIN	CAPTIVATE-PHONE BUTTON 1		CAPTIVATE-BSWP BUTTON 1	
		CONVERSION TIME (µs)	COUNTS FOR 0.1-pF CHANGE	CONVERSION TIME (µs)	COUNTS FOR 1-pF CHANGE
100	100	25	6	50	8
200	200	50	10	100	16
200	100	50	21	100	31
800	400	200	70	400	112
800	200	200	140	400	202
800	100	200	257	400	333

An alternative measure in sensitivity is the ability to resolve capacitance change over a wide range of base capacitance. Table 7-2 shows example conversion times (for a self-mode measurement of discrete capacitors) that can be used to achieve the desired resolution for a given parasitic load capacitance.

Table 7-2. Button Sensitivity

CAPACITANCE, Cp (pF)(1)	CONVERSION COUNT/GAIN	CONVERSION TIME (µs)	COUNTS FOR 0.130-pF CHANGE	COUNTS FOR 0.260-pF CHANGE	COUNTS FOR 0.520-pF CHANGE
23	400/100	200	10	23	35
50	550/100	275	11	24	37
78	650/100	325	11	23	36
150	850/100	425	11	22	35
150(2)	1200/200	600	11	23	37
200(2)	1200/150	600	13	26	41

(1) These measurements were taken with the CapTIvate MCU processor board with the 470-Ω series resistors replaced with 0-Ω resistors.
(2) 0-V discharge voltage is used.

7.2.2.2.3 Power

The low-power mode LPM3 specifications in Section 5.7 are derived from the CapTIvate technology design kit as indicated in the notes.

7.3 CapTIvate Technology Evaluation

Table 7-3 lists tools that demonstrate the use of the MSP430FR263x devices. See CapTIvate Evaluation Tools to get started with evaluating the CapTIvate technology in various real-world application scenarios. Consult these evaluation tool designs for additional guidance regarding schematics, layout, and software implementation.

Table 7-3. Evaluation Tools

NAME	LINK
MSP CapTIvate MCU Development Kit	http://www.ti.com/tool/msp-capt-fr2633
Capacitive Touch Thermostat User Interface Reference Design	http://www.ti.com/tool/tidm-captivate-thermostat-ui

Copyright © 2015–2019, Texas Instruments Incorporated

8 デバイスおよびドキュメントのサポート

8.1 使い始めと次の手順

MSP　低消費電力マイクロコントローラ、および開発に役立つツールやライブラリの詳細については、「MSP430™ 超低消費電力センシング/測定マイコン」ページを参照してください。

8.2 デバイスの項目表記

製品開発サイクルの段階を示すために、TIではMSP　MCUデバイスのすべての型番に接頭辞が割り当てられています。MSP MCU商用ファミリの各番号には、MSP、XMSのいずれかの接頭辞があります。これらの接頭辞は、製品開発の進展段階を表します。段階には、エンジニアリング・プロトタイプ(XMS)から、完全認定済みの量産デバイス(MSP)までがあります。

XMS - 実験段階のデバイスで、最終的なデバイスの電気的仕様を表しているとは限りません。

MSP - 完全に認定済みの量産版デバイスです。

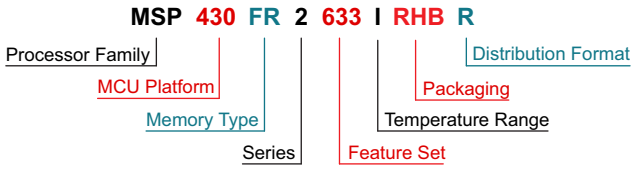
XMSデバイスは、次の免責事項付きで出荷されます。

「開発中の製品は、社内での評価用です。」

MSPデバイスの特性は完全に明確化されており、デバイスの品質と信頼性が十分に示されています。TIの標準保証が適用されます。

プロトタイプ・デバイス(XMS)は標準の量産デバイスよりも故障率が高いことが予想されます。これらのデバイスは、予測される最終使用時の故障率が未定義であるため、TIはそれらのデバイスを量産システムで使用しないよう推奨しています。認定された量産デバイスのみを使用する必要があります。

TIデバイスの項目表記には、デバイス・ファミリ名の接尾辞も含まれます。この接尾辞は、温度範囲、パッケージ・タイプ、配布形式を示しています。デバイス名の各部の読み方を図 8-1に示します。



Processor Family	MSP = Mixed-signal processor XMS = Experimental silicon
MCU Platform	430 = MSP430 16-bit low-power platform
Memory Type	FR = FRAM
Series	2 = Up to 16 MHz without LCD
Feature Set (see note)	**CapTIvate Performance** 633 = 4 CapTIvate blocks, 16KB of FRAM, 4KB of SRAM, up to 16 CapTIvate I/Os 533 = 4 CapTIvate blocks, 16KB of FRAM, 2KB of SRAM, up to 16 CapTIvate I/Os 632 = 4 CapTIvate blocks, 8KB of FRAM, 2KB of SRAM, up to 8 CapTIvate I/Os 532 = 4 CapTIvate blocks, 8KB of FRAM, 1KB of SRAM, up to 8 CapTIvate I/Os
Temperature Range	I = –40°C to 85°C
Packaging	www.ti.com/packaging
Distribution Format	T = Small reel R = Large reel No marking = Tube or tray

NOTE: CapTIvateタッチ・テクノロジを搭載したデバイスの詳細については、*CapTIvateテクノロジ・ガイド*のデバイス・セレクション・ベンチマークを参照してください。

図 8-1. デバイスの項目表記

8.3 ツールとソフトウェア

すべてのMSPマイクロコントローラは、広範なソフトウェアおよびハードウェア開発ツールによりサポートされています。ツールは、TIおよびさまざまなサードパーティーから入手できます。すべてのツールの一覧は、『低消費電力MCU用の開発キットとソフトウェア』で参照できます。

MSP430FR211xマイクロコントローラのデバッグ機能の一覧を、表 8-1に示します。利用可能な機能の詳細については、*『Code Composer Studio™ v5.2 ユーザーズ・ガイド MSP430™ 版ユーザーズ・ガイド』*を参照してください。

表 8-1. ハードウェアのデバッグ機能

MSP430のアーキテクチャ	4線式 JTAG	2線式 JTAG	ブレーク・ポイント (N)	範囲ブレーク・ポイント	クロック制御	状態シーケンサ	トレース・バッファ	LPMx.5デバッグ・サポート	EEM のバージョン
MSP430Xv2	○	○	3	○	○	×	×	×	S

設計キットと評価基板

MSP CapTIvate MCU開発キット

MSP CapTIvate MCU開発キットは、静電容量式タッチ・テクノロジ搭載のMSP430FR2633マイクロコントローラを評価するための使いやすい包括的なプラットフォームです。このキットは、MSP430FR2633を搭載したプロセッサ・ボード、Code Composer Studio IDEを使用して消費エネルギーを測定するためのEnergyTraceテクノロジを搭載したプログラマ/デバッガ・ボード、および自己容量式、相互容量式、ジェスチャ、および近接性センシングを評価するためのセンサ・ボードで構成されています。

ソフトウェア

MSP430Wareソフトウェア

MSP430Wareは、MSP430コードの効果的な作成・構築に役立つ設計リソース集です。MSP430Wareは、MSP430ドライバ・ライブラリやUSBといったデバイス/ペリフェラル別ライブラリからグラフィックス・ライブラリや静電容量式タッチ・ライブラリといった用途別ライブラリまで、高度に抽象化されたソフトウェア・ライブラリを幅広く取り揃えています。特にMSP430ドライバ・ライブラリは重要なライブラリであり、これによりソフトウェア開発者は便利なAPIを活用して下位の複雑なハードウェア・ペリフェラルを制御でき、最終的なコードは読みやすく、保守しやすいものになります。

MSP430FR243x/MSP430FR253x/MSP430FR263xのサンプル・コード

すべての MSP デバイス用に、内蔵の各ペリフェラルをさまざまな用途のニーズに合わせて構成するための C コード・サンプルが用意されています。

MSP ドライバ・ライブラリ

MSPドライバ・ライブラリの抽象化されたAPIには、使いやすい関数呼び出しが含まれているため、MSP430ハードウェアのビットやバイトを直接操作する煩雑さから解放されます。使いやすいAPIガイドにより包括的な技術資料が参照でき、それぞれの関数呼び出しと、認識されるパラメータの詳細が記載されています。開発者は、ドライバ・ライブラリの関数を使用して、最小限のオーバーヘッドで完全なプロジェクトを作成できます。

MSP EnergyTrace™ テクノロジ

MSP430 マイコン向け EnergyTrace テクノロジはエネルギー・ベースのコード分析ツールで、アプリケーションのエネルギー・プロファイルの測定と表示を行うとともに、消費電力の大幅な低減のための最適化も可能です。

ULP (超低消費電力) Advisor

ULP Advisor™ソフトウェアは、MSPおよびMSP432マイクロコントローラの超低消費電力機能を十分に活用できる、最も効率的なコードを開発者が作成できるよう手引きするツールです。ULP Advisorはマイクロコントローラに熟練した開発者と、新しい開発者の両方を対象としており、包括的なULPチェックリストを使用してコードをチェックし、アプリケーションのエネルギー消費を最小化するため役立ちます。ビルド時に、消費電力低減のためさらに最適化が可能なコードの部分を明らかにするため通知と注釈を出力します。

Copyright © 2015–2019, Texas Instruments Incorporated

IEC60730 ソフトウェア・パッケージ

IEC60730 MSP430ソフトウェア・パッケージは、クラスBまでの製品について、お客様がIEC 60730-1:2010 (家庭および同様な用途に使用される自動電気制御 – 第1部: 一般的な要件)に準拠するため役立つよう開発されています。この分類には家電機器、アーク検出器、電力コンバータ、電動工具、電気自転車、その他多くの製品が含まれます。IEC60730 MSP430ソフトウェア・パッケージは、MSP430で実行するお客様のアプリケーションに組み込むことができるため、消費者向けデバイスがIEC 60730-1:2010クラスBの機能安全性に準拠していることの認定作業を簡素化できます。

MSP 用の固定小数点算術ライブラリ

MSP IQmath および Qmath ライブラリは、C プログラマが浮動小数点アルゴリズムを MSP430 および MSP432 デバイスの固定小数点コードにシームレスに移植するための高度に最適化された高精度算術関数のコレクションです。これらのルーチンは通常、最適な実行速度、高精度、超低消費電力が重視される、演算集中型のリアルタイム・アプリケーションで使用されます。IQmathライブラリとQmathライブラリを使用すると、浮動小数点演算を使用して記述した同等のコードに比べて、実行速度を大幅に高速化するとともに、消費電力の大幅な削減が可能です。

MSP430用の浮動小数点算術ライブラリ

低消費電力で低コストのマイクロコントローラ分野にさらなる革新を引き起こすため、TIはMSPMATHLIBを提供します。この浮動小数点算術ライブラリは、弊社デバイスのインテリジェントなペリフェラルを活用し、標準のMSP430算術関数よりも最高で26倍も高速なスカラー関数です。Mathlibは、設計へ簡単に組み入れることができます。このライブラリは無償で、Code Composer Studio IDEとIAR Embedded Workbench IDEの両方に組み込まれています。

開発ツール

Code Composer Studio™: MSPマイクロコントローラ用の統合開発環境

Code Composer Studio (CCS)は、すべてのMSPマイクロコントローラ・デバイスをサポートする統合開発環境(IDE)です。CCSは、組み込みアプリケーションの開発とデバッグに使用される、組み込み用ソフトウェア・ユーティリティのスイートです。最適化C/C++コンパイラ、ソース・コード・エディタ、プロジェクト・ビルド環境、デバッガ、プロファイラなど、多数の機能が含まれています。

コマンドライン・プログラマ

MSP Flasher は、FET プログラマまたは eZ430 を経由し、JTAG または Spy-Bi-Wire (SBW) 通信を使用して MSP マイクロコントローラをプログラムするための、オープン・ソースでシェル・ベースのインターフェイスです。MSP Flasher は、IDE を使用せずにバイナリ・ファイル (.txt または .hex) を MSP マイクロコントローラへ直接ダウンロードできます。

MSP MCU プログラマおよびデバッガ

MSP-FET は、MSP 低消費電力マイクロコントローラ (MCU) でのアプリケーション開発をすばやく開始できる強力なエミュレーション開発ツールです (デバッグ・プローブとも呼ばれます)。MCUのソフトウェアを作成する場合は通常、結果として得られたバイナリ・プログラムをMSPデバイスにダウンロードし、検証とデバッグを行う必要があります。MSP-FETは、ホスト・コンピュータとターゲットMSPの間で、デバッグ通信経路を提供します。さらに MSP-FET は、コンピュータの USB インターフェイスと MSP UART の間のバックチャネル UART 接続にも対応します。これにより MSP のプログラマは、コンピュータ上で動作している端末ソフトウェアと MSP との間でシリアル通信を簡単に行うことができます。

MSP-GANG量産プログラマ

MSP Gang Programmer は、8 つまでの同一の MSP430 または MSP432 のフラッシュまたは FRAM デバイスを同時にプログラムできます。MSP Gang Programmerは、標準のRS-232またはUSB接続を使用してホストPCに接続でき、柔軟なプログラミング・オプションにより、プロセスを完全にカスタマイズ可能です。MSP Gang Programmer には、Gang Splitter と呼ばれる拡張ボードが付属しており、MSP Gang Programmer と複数のターゲット・デバイスとの間で相互接続機能を実装します。

Copyright © 2015–2019, Texas Instruments Incorporated

8.4 ドキュメントのサポート

以下のドキュメントは MSP430FR263x/MSP430FR253x MCU について記載したものです。これらのドキュメントのコピーは、www.ti.comで入手できます。

ドキュメントの更新通知を受け取る方法

ドキュメント更新の通知を、シリコンの正誤表も含めて受け取るには、ti.comでお使いのデバイスの製品フォルダへ移動します(製品フォルダへのリンクについては、 8.5を参照してください)。右上の隅にある「通知を受け取る」ボタンをクリックします。これによって登録が行われ、変更された製品情報の概要を毎週受け取ることができます。変更の詳細については、修正されたドキュメントに含まれている改訂履歴をご覧ください。

正誤表

『MSP430FR2633正誤表』

機能仕様に対する既知の例外が記載されています。

『MSP430FR2533正誤表』

機能仕様に対する既知の例外が記載されています。

『MSP430FR2632正誤表』

機能仕様に対する既知の例外が記載されています。

『MSP430FR2532正誤表』

機能仕様に対する既知の例外が記載されています。

ユーザー・ガイド

『MSP430FR4xxおよびMSP430FR2xxファミリ ユーザー・ガイド』

このデバイス・ファミリで利用可能なモジュールとペリフェラルについての詳細情報です。

『MSP430 FRAMデバイス・ブートローダ(BSL) ユーザー・ガイド』

ブートローダ(BSL)はMSP430 MCUプロジェクトの開発および更新時にメモリをプログラムするための手段を提供します。シリアル・プロトコルを使用してコマンドを送信するユーティリティにより、この機能をアクティブにできます。BSLにより、ユーザーはMSP430 MCUの動作を制御し、パーソナル・コンピュータや他のデバイスを使用してデータを交換できます。

『MSP430ハードウェア・ツール ユーザー・ガイド』

このマニュアルには、TI MSP-FET430フラッシュ・エミュレーション・ツール(FET)のハードウェアについて解説されています。FETは、MSP430超低消費電力マイクロコントローラ用のプログラム開発ツールです。

アプリケーション・レポート

『MSP430 FRAMテクノロジ - ハウツーとベスト・プラクティス』

FRAMは不揮発性メモリ・テクノロジで、SRAMと同様に動作し、多くの新しいアプリケーションを可能にすると同時に、ファームウェアの設計方法に変革をもたらすものです。このアプリケーション・レポートでは、組み込みソフトウェア開発の観点から、MSP430のFRAMテクノロジを使用する方法と、そのベスト・プラクティスについて概説しています。特定用途向けのコード、定数、データ容量の制限、FRAMの使用に従って、アプリケーションのエネルギー消費を最適化するようメモリ・レイアウトを実装する方法について解説します。

『MSP430FR4xxおよびMSP430FR2xxファミリでのVLO較正』

MSP430FR4xxおよびMSP430FR2xx (FR4xx/FR2xx)ファミリのマイクロコントローラ(MCU)には、いくつかの高速高精度クロックや、いくつかの低消費電力でシステム・コストの低いクロックを含めて、各種のクロック・ソースが用意されています。ユーザーは、性能、消費電力、システム・コストを比較して、最良のものを選択できます。オンチップの超低周波数発振器(VLO)は、FR4xx/FR2xxファミリのMCUに内蔵されている、標準周波数10kHzのクロック・ソースです。VLOは消費電力が非常に低いため、広範なアプリケーションに使用されます。

Copyright © 2015–2019, Texas Instruments Incorporated

『MSP430 32kHz水晶発振器』

適切な水晶、正しい負荷回路、および適切な基板レイアウトの選択は、安定した水晶発振器のために重要です。このアプリケーション・レポートでは、水晶発振器の機能について要約し、MSP430の超低消費電力動作用の適切な水晶を選択するためのパラメータについて説明します。また、正しい基板レイアウトについてのヒントや例も紹介しています。このドキュメントには、量産時の安定した発振器の動作を保証するために行うことができる、発振器のテストについての詳細情報も記載されています。

『MSP430 システム・レベルESDの考慮事項』

シリコン・テクノロジのスケーリングによる低電圧化の進行と、コスト効率の優れた超低消費電力コンポーネントを設計する必要性の高まりにより、システム・レベルの ESD の要求はますます高まっています。このアプリケーション・レポートでは、基板設計者と OEM が堅牢なシステム・レベルのデザインを理解し設計できるよう、各種の ESD トピックについて扱います。

8.5 関連リンク

表 8-2 に、クイック・アクセス・リンクの一覧を示します。カテゴリには、技術資料、サポートおよびコミュニティ・リソース、ツールとソフトウェア、およびご注文へのクイック・アクセスが含まれます。

表 8-2. 関連リンク

製品	プロダクト・フォルダ	ご注文はこちら	技術資料	ツールとソフトウェア	サポートとコミュニティ
MSP430FR2633	ここをクリック	ここをクリック	ここをクリック	ここをクリック	ここをクリック
MSP430FR2632	ここをクリック	ここをクリック	ここをクリック	ここをクリック	ここをクリック
MSP430FR2533	ここをクリック	ここをクリック	ここをクリック	ここをクリック	ここをクリック
MSP430FR2532	ここをクリック	ここをクリック	ここをクリック	ここをクリック	ここをクリック

8.6 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

TI E2E™ Community

TI's Engineer-to-Engineer (E2E) Community. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas, and help solve problems with fellow engineers.

TI Embedded Processors Wiki

Texas Instruments Embedded Processors Wiki. Established to help developers get started with embedded processors from Texas Instruments and to foster innovation and growth of general knowledge about the hardware and software surrounding these devices.

8.7 商標

CapTIvate, EnergyTrace, ULP Advisor, Code Composer Studio, E2E are trademarks of Texas Instruments.
All other trademarks are the property of their respective owners.

Copyright © 2015–2019, Texas Instruments Incorporated

8.8 静電気放電に関する注意事項

すべての集積回路は、適切なESD保護方法を用いて、取扱いと保存を行うようにして下さい。

静電気放電はわずかな性能の低下から完全なデバイスの故障に至るまで、様々な損傷を与えます。高精度の集積回路は、損傷に対して敏感であり、極めてわずかなパラメータの変化により、デバイスに規定された仕様に適合しなくなる場合があります。

8.9 Export Control Notice

Recipient agrees to not knowingly export or re-export, directly or indirectly, any product or technical data (as defined by the U.S., EU, and other Export Administration Regulations) including software, or any controlled product restricted by other applicable national regulations, received from disclosing party under nondisclosure obligations (if any), or any direct product of such technology, to any destination to which such export or re-export is restricted or prohibited by U.S. or other applicable laws, without obtaining prior authorization from U.S. Department of Commerce and other competent Government authorities to the extent required by those laws.

8.10 Glossary

TI Glossary This glossary lists and explains terms, acronyms, and definitions.

Copyright © 2015–2019, Texas Instruments Incorporated

9 メカニカル、パッケージ、および注文情報

以降のページには、メカニカル、パッケージ、および注文に関する情報が記載されています。この情報は、そのデバイスについて利用可能な最新のデータです。このデータは予告なく変更されることがあり、ドキュメントが改訂される場合もあります。本データシートのブラウザ版を使用されている場合は、画面左側の説明をご覧ください。

Copyright © 2015–2019, Texas Instruments Incorporated

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
MSP430FR2532IRGER	ACTIVE	VQFN	RGE	24	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	FR2532	Samples
MSP430FR2532IRGET	ACTIVE	VQFN	RGE	24	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	FR2532	Samples
MSP430FR2533IDA	ACTIVE	TSSOP	DA	32	46	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	FR2533	Samples
MSP430FR2533IDAR	ACTIVE	TSSOP	DA	32	2000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	FR2533	Samples
MSP430FR2533IRHBR	ACTIVE	VQFN	RHB	32	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	FR2533	Samples
MSP430FR2533IRHBT	ACTIVE	VQFN	RHB	32	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	FR2533	Samples
MSP430FR2632IRGER	ACTIVE	VQFN	RGE	24	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	FR2632	Samples
MSP430FR2632IRGET	ACTIVE	VQFN	RGE	24	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	FR2632	Samples
MSP430FR2632IYQWR	ACTIVE	DSBGA	YQW	24	3000	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-40 to 85	430FR2632	Samples
MSP430FR2632IYQWT	ACTIVE	DSBGA	YQW	24	250	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-40 to 85	430FR2632	Samples
MSP430FR2633IDA	ACTIVE	TSSOP	DA	32	46	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	FR2633	Samples
MSP430FR2633IDAR	ACTIVE	TSSOP	DA	32	2000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	FR2633	Samples
MSP430FR2633IRHBR	ACTIVE	VQFN	RHB	32	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	FR2633	Samples
MSP430FR2633IRHBT	ACTIVE	VQFN	RHB	32	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	FR2633	Samples
MSP430FR2633IYQWR	ACTIVE	DSBGA	YQW	24	3000	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-40 to 85	430FR2633	Samples
MSP430FR2633IYQWT	ACTIVE	DSBGA	YQW	24	250	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-40 to 85	430FR2633	Samples

(1) The marketing status values are defined as follows:
ACTIVE: Product device recommended for new designs.
LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
OBSOLETE: TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".
RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.
Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

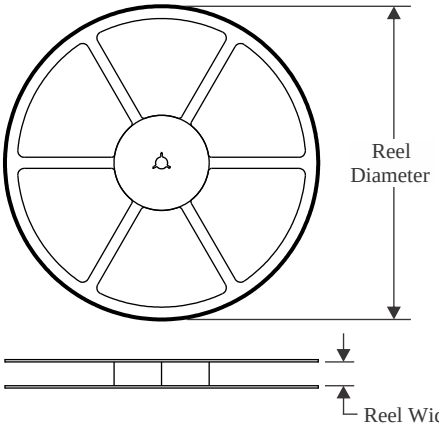
(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

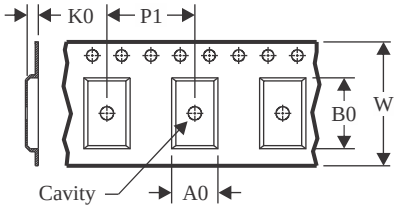
In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

TAPE AND REEL INFORMATION

REEL DIMENSIONS

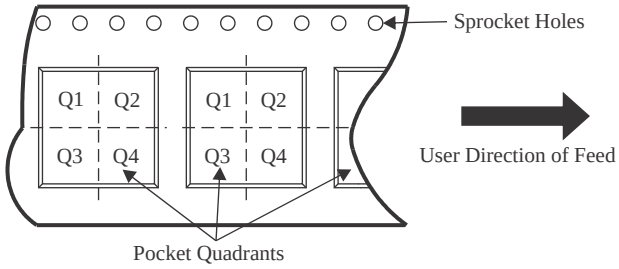


TAPE DIMENSIONS



A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

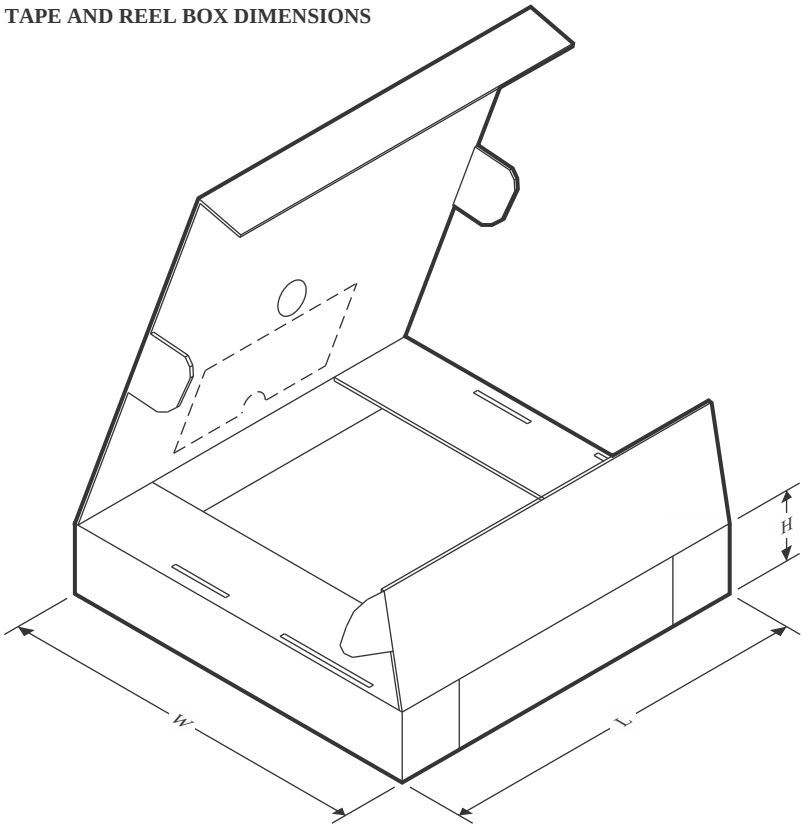


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
MSP430FR2532IRGER	VQFN	RGE	24	3000	330.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
MSP430FR2532IRGER	VQFN	RGE	24	3000	330.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
MSP430FR2532IRGET	VQFN	RGE	24	250	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
MSP430FR2532IRGET	VQFN	RGE	24	250	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
MSP430FR2533IDAR	TSSOP	DA	32	2000	330.0	24.4	8.6	11.5	1.6	12.0	24.0	Q1
MSP430FR2533IRHBR	VQFN	RHB	32	3000	330.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2
MSP430FR2533IRHBR	VQFN	RHB	32	3000	330.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2
MSP430FR2533IRHBT	VQFN	RHB	32	250	180.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2
MSP430FR2533IRHBT	VQFN	RHB	32	250	180.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2
MSP430FR2632IRGER	VQFN	RGE	24	3000	330.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
MSP430FR2632IRGER	VQFN	RGE	24	3000	330.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
MSP430FR2632IRGET	VQFN	RGE	24	250	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
MSP430FR2632IRGET	VQFN	RGE	24	250	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
MSP430FR2632IYQWR	DSBGA	YQW	24	3000	180.0	8.4	2.38	2.4	0.8	4.0	8.0	Q1
MSP430FR2632IYQWT	DSBGA	YQW	24	250	180.0	8.4	2.38	2.4	0.8	4.0	8.0	Q1
MSP430FR2633IDAR	TSSOP	DA	32	2000	330.0	24.4	8.6	11.5	1.6	12.0	24.0	Q1

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
MSP430FR2633IRHBR	VQFN	RHB	32	3000	330.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2
MSP430FR2633IRHBR	VQFN	RHB	32	3000	330.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2
MSP430FR2633IRHBT	VQFN	RHB	32	250	180.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2
MSP430FR2633IRHBT	VQFN	RHB	32	250	180.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2
MSP430FR2633IYQWR	DSBGA	YQW	24	3000	180.0	8.4	2.38	2.4	0.8	4.0	8.0	Q1
MSP430FR2633IYQWT	DSBGA	YQW	24	250	180.0	8.4	2.38	2.4	0.8	4.0	8.0	Q1

TAPE AND REEL BOX DIMENSIONS

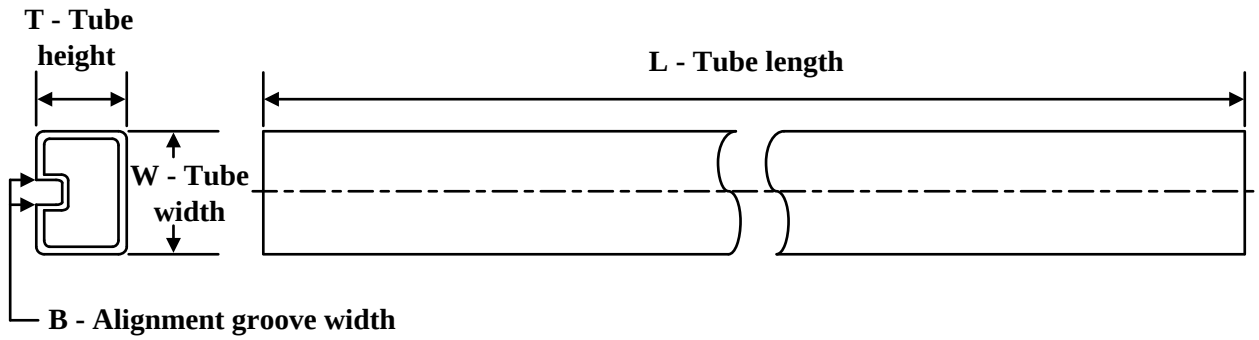


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
MSP430FR2532IRGER	VQFN	RGE	24	3000	367.0	367.0	35.0
MSP430FR2532IRGER	VQFN	RGE	24	3000	346.0	346.0	33.0
MSP430FR2532IRGET	VQFN	RGE	24	250	210.0	185.0	35.0
MSP430FR2532IRGET	VQFN	RGE	24	250	210.0	185.0	35.0
MSP430FR2533IDAR	TSSOP	DA	32	2000	350.0	350.0	43.0
MSP430FR2533IRHBR	VQFN	RHB	32	3000	367.0	367.0	35.0
MSP430FR2533IRHBR	VQFN	RHB	32	3000	346.0	346.0	33.0
MSP430FR2533IRHBT	VQFN	RHB	32	250	210.0	185.0	35.0
MSP430FR2533IRHBT	VQFN	RHB	32	250	210.0	185.0	35.0
MSP430FR2632IRGER	VQFN	RGE	24	3000	367.0	367.0	35.0
MSP430FR2632IRGER	VQFN	RGE	24	3000	346.0	346.0	33.0
MSP430FR2632IRGET	VQFN	RGE	24	250	210.0	185.0	35.0
MSP430FR2632IRGET	VQFN	RGE	24	250	210.0	185.0	35.0
MSP430FR2632IYQWR	DSBGA	YQW	24	3000	182.0	182.0	20.0
MSP430FR2632IYQWT	DSBGA	YQW	24	250	182.0	182.0	20.0
MSP430FR2633IDAR	TSSOP	DA	32	2000	350.0	350.0	43.0
MSP430FR2633IRHBR	VQFN	RHB	32	3000	367.0	367.0	35.0
MSP430FR2633IRHBR	VQFN	RHB	32	3000	346.0	346.0	33.0

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
MSP430FR2633IRHBT	VQFN	RHB	32	250	210.0	185.0	35.0
MSP430FR2633IRHBT	VQFN	RHB	32	250	210.0	185.0	35.0
MSP430FR2633IYQWR	DSBGA	YQW	24	3000	182.0	182.0	20.0
MSP430FR2633IYQWT	DSBGA	YQW	24	250	182.0	182.0	20.0

TUBE



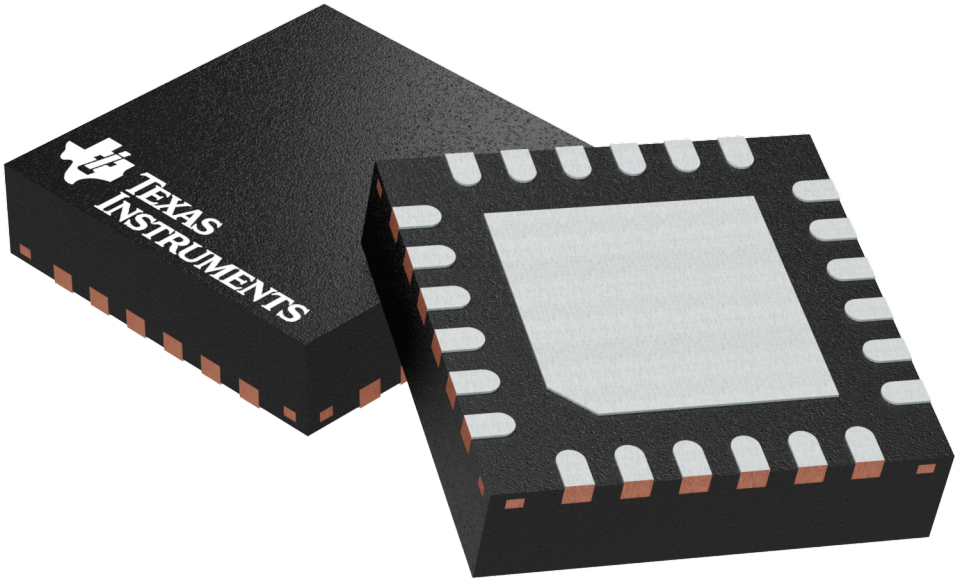
*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (µm)	B (mm)
MSP430FR2533IDA	DA	TSSOP	32	46	530	11.89	3600	4.9
MSP430FR2633IDA	DA	TSSOP	32	46	530	11.89	3600	4.9

RGE 24

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



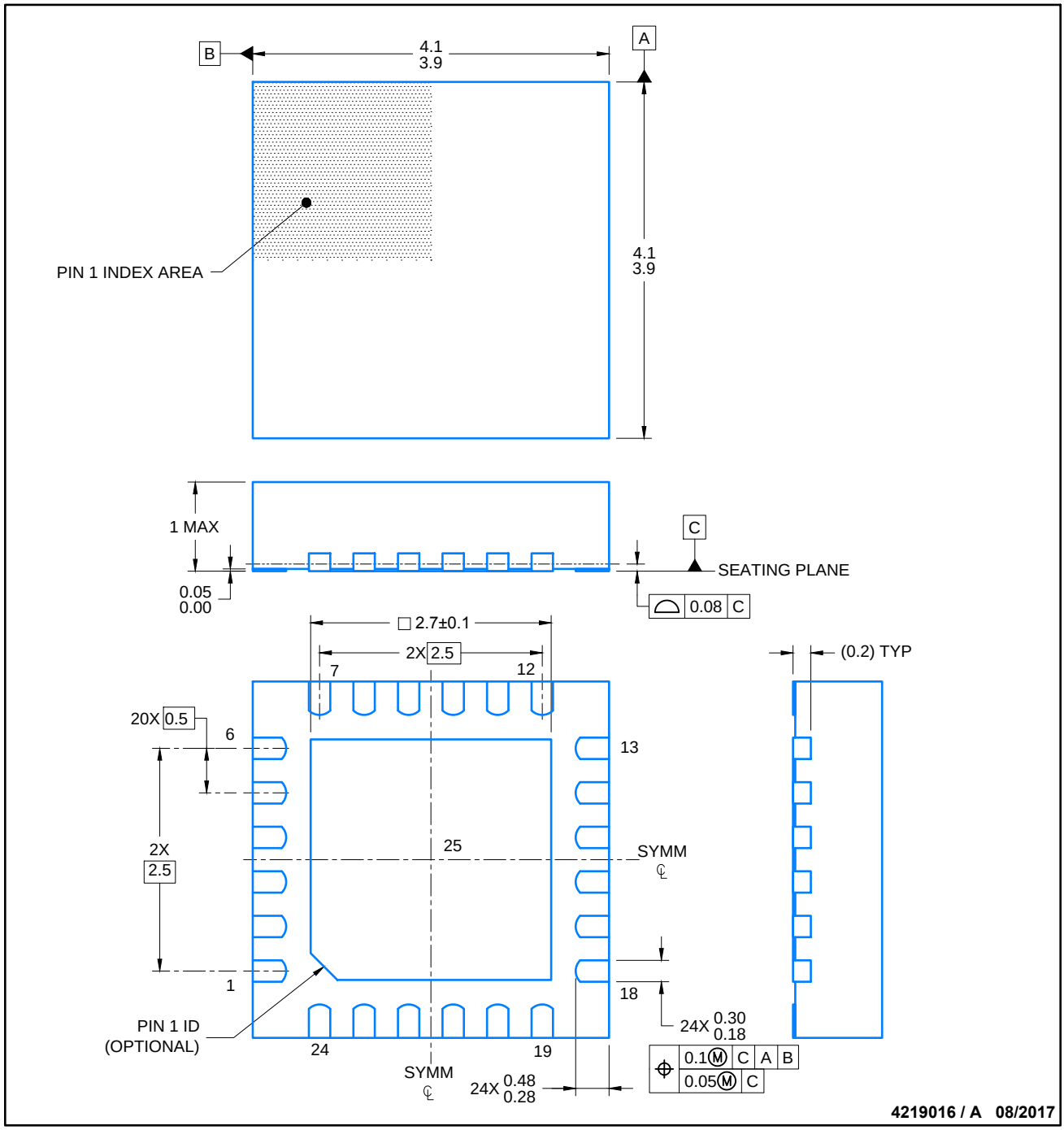
Images above are just a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.

PACKAGE OUTLINE

RGE0024H

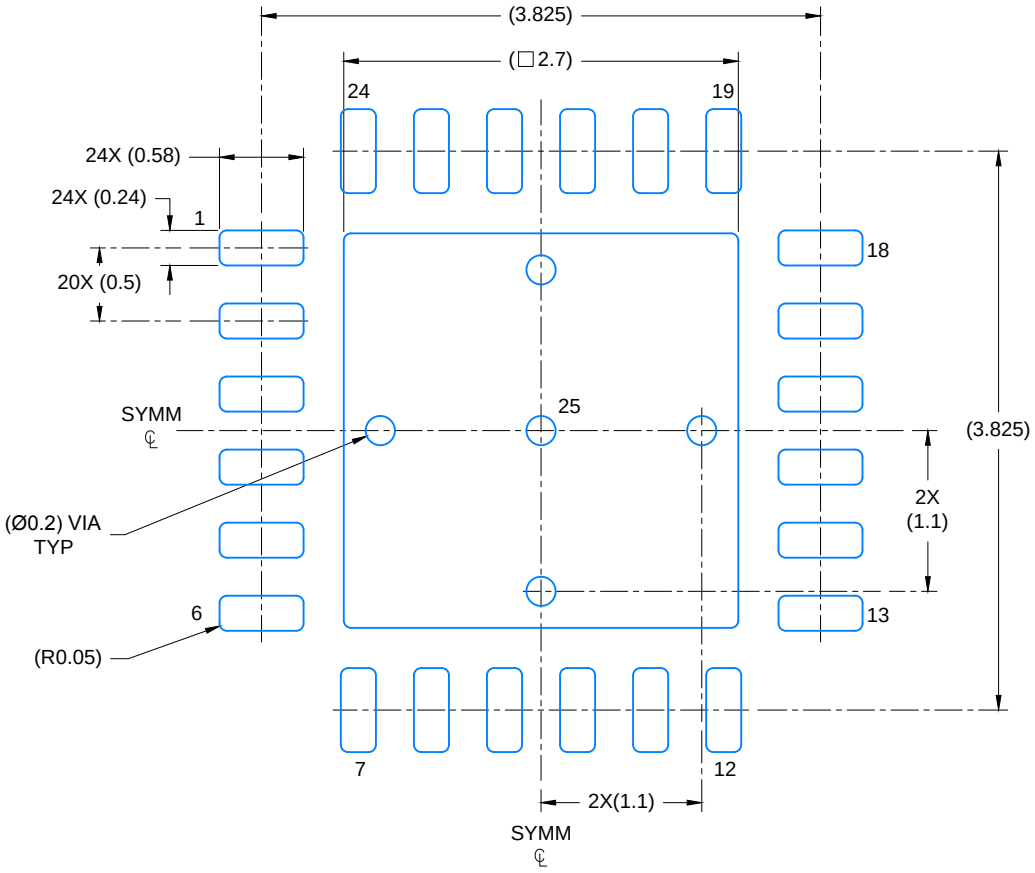
VQFN - 1 mm max height

PLASTIC QUAD FLATPACK- NO LEAD



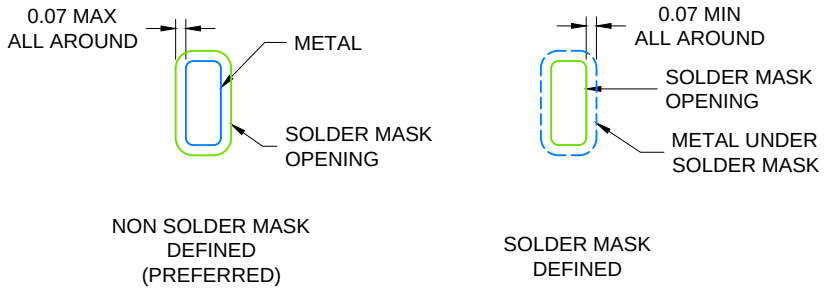
NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.



LAND PATTERN EXAMPLE

SCALE: 20X

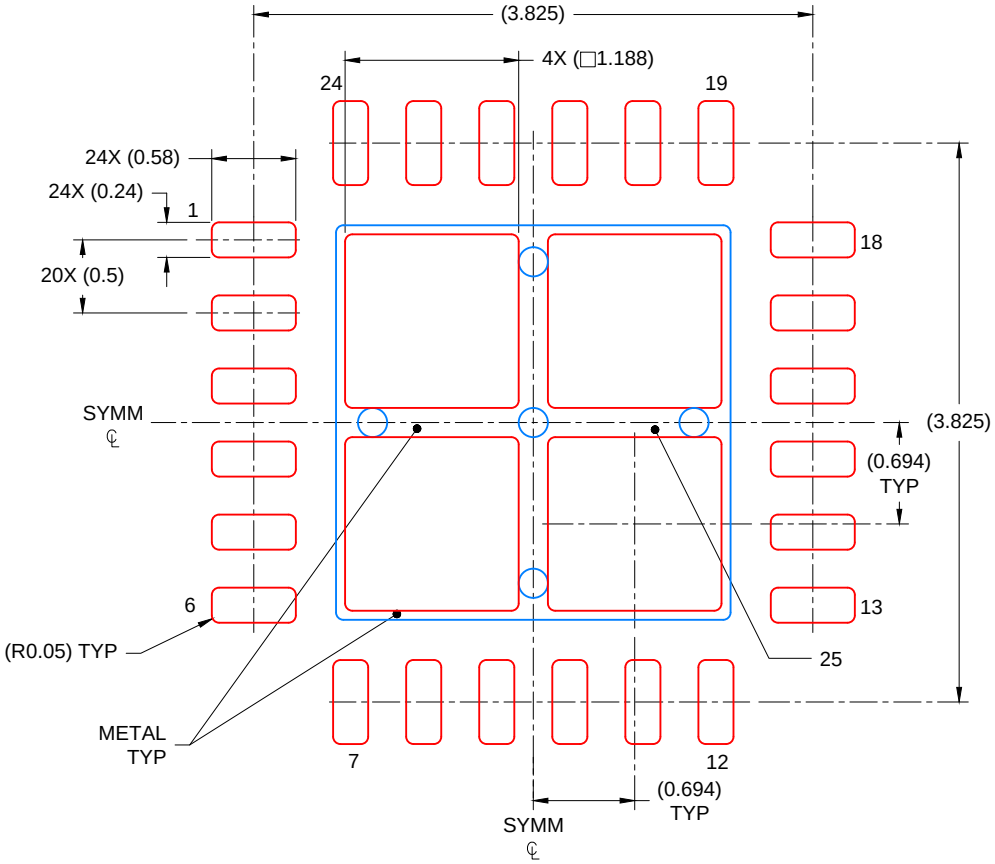


SOLDER MASK DETAILS

4219016 / A 08/2017

NOTES: (continued)

4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
5. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD
78% PRINTED COVERAGE BY AREA
SCALE: 20X

4219016 / A 08/2017

NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations..

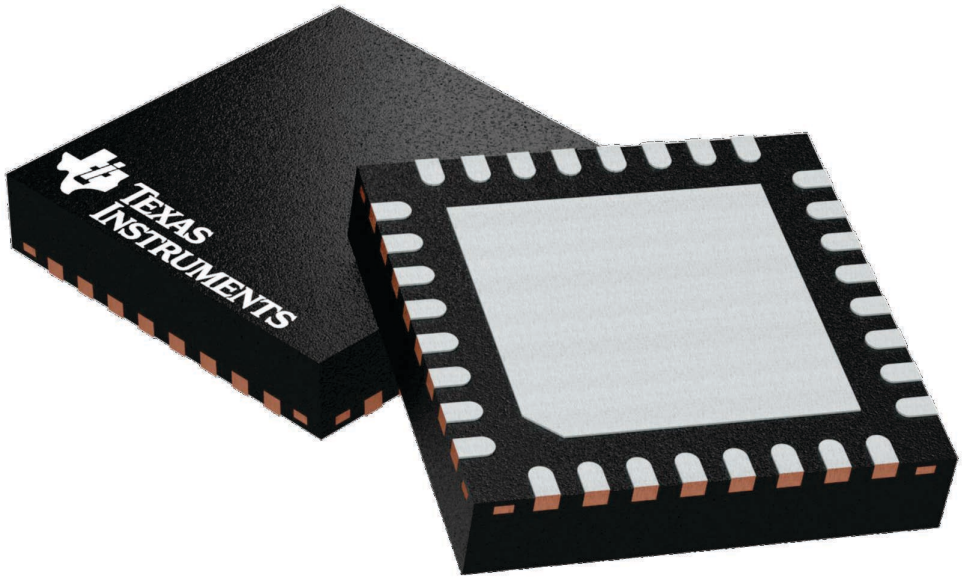
GENERIC PACKAGE VIEW

RHB 32

VQFN - 1 mm max height

5 x 5, 0.5 mm pitch

PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.

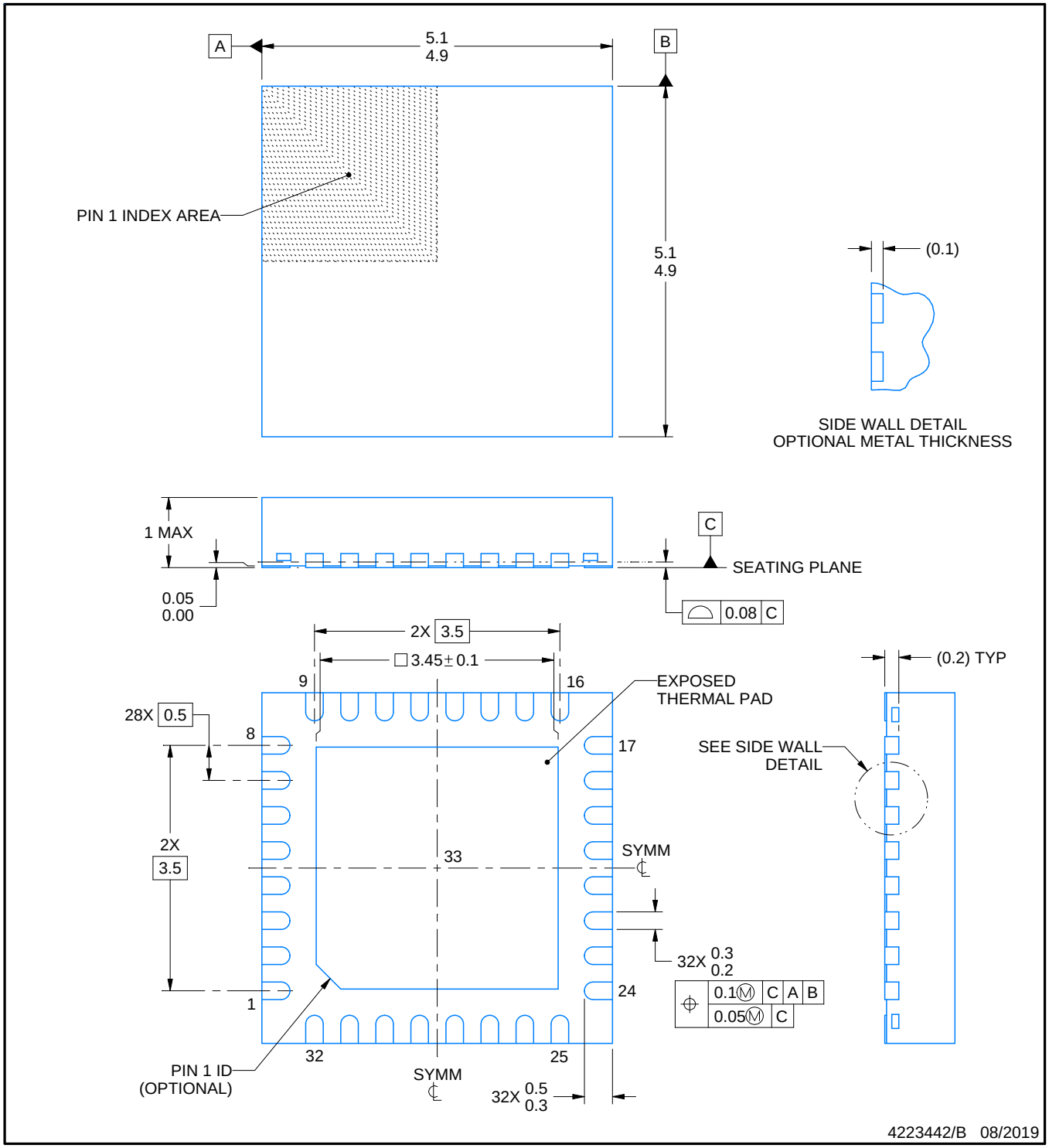
4224745/A

RHB0032E

PACKAGE OUTLINE

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



NOTES:

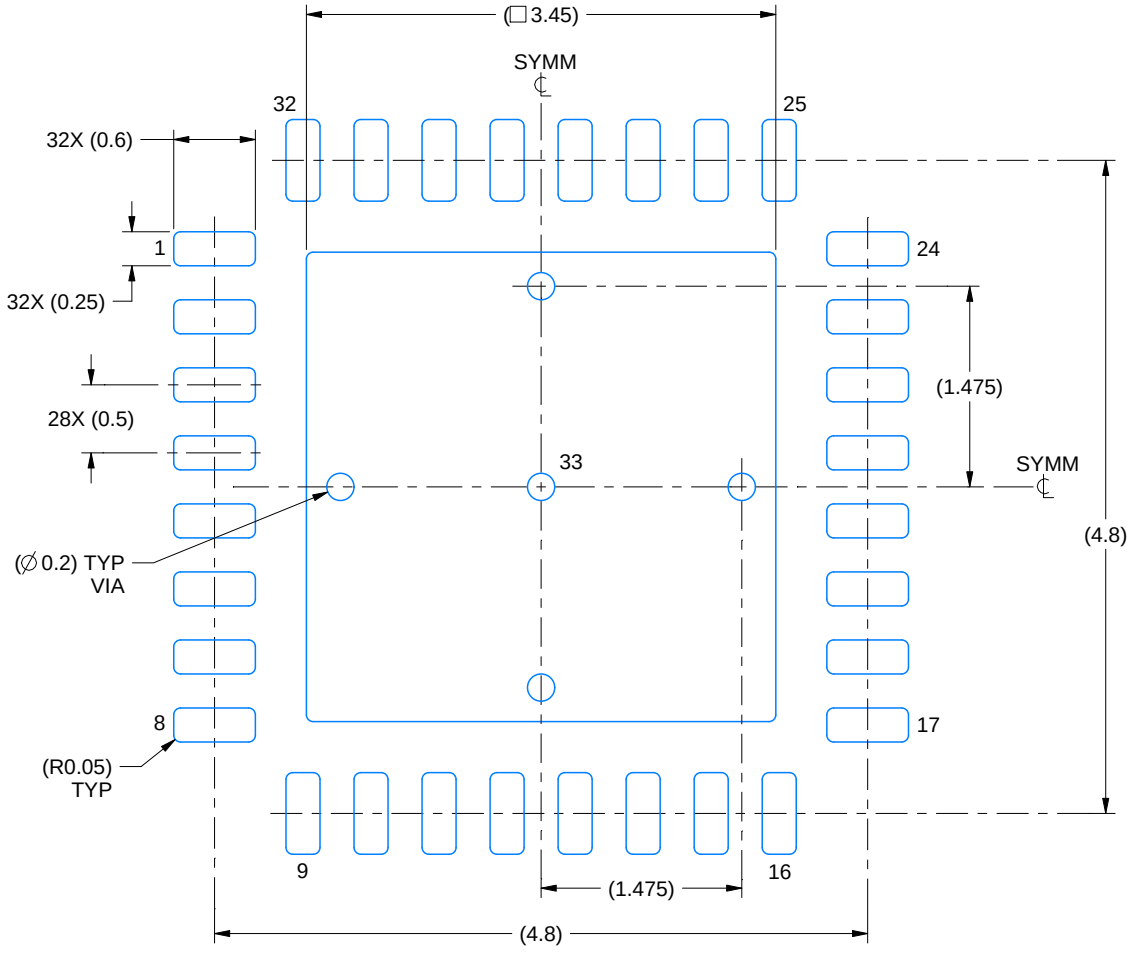
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

EXAMPLE BOARD LAYOUT

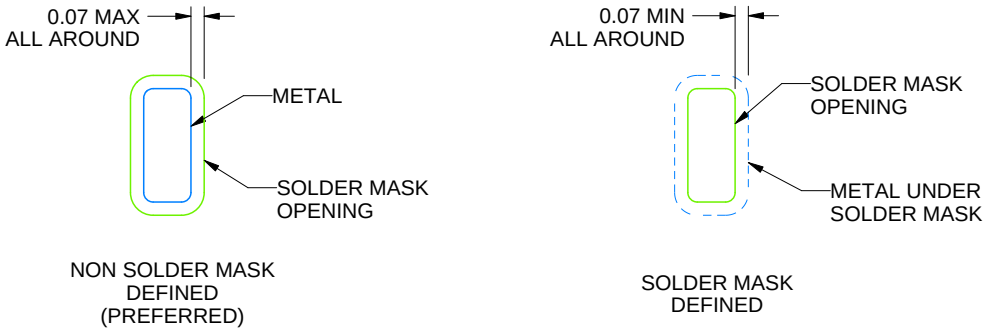
RHB0032E

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



LAND PATTERN EXAMPLE
SCALE:18X

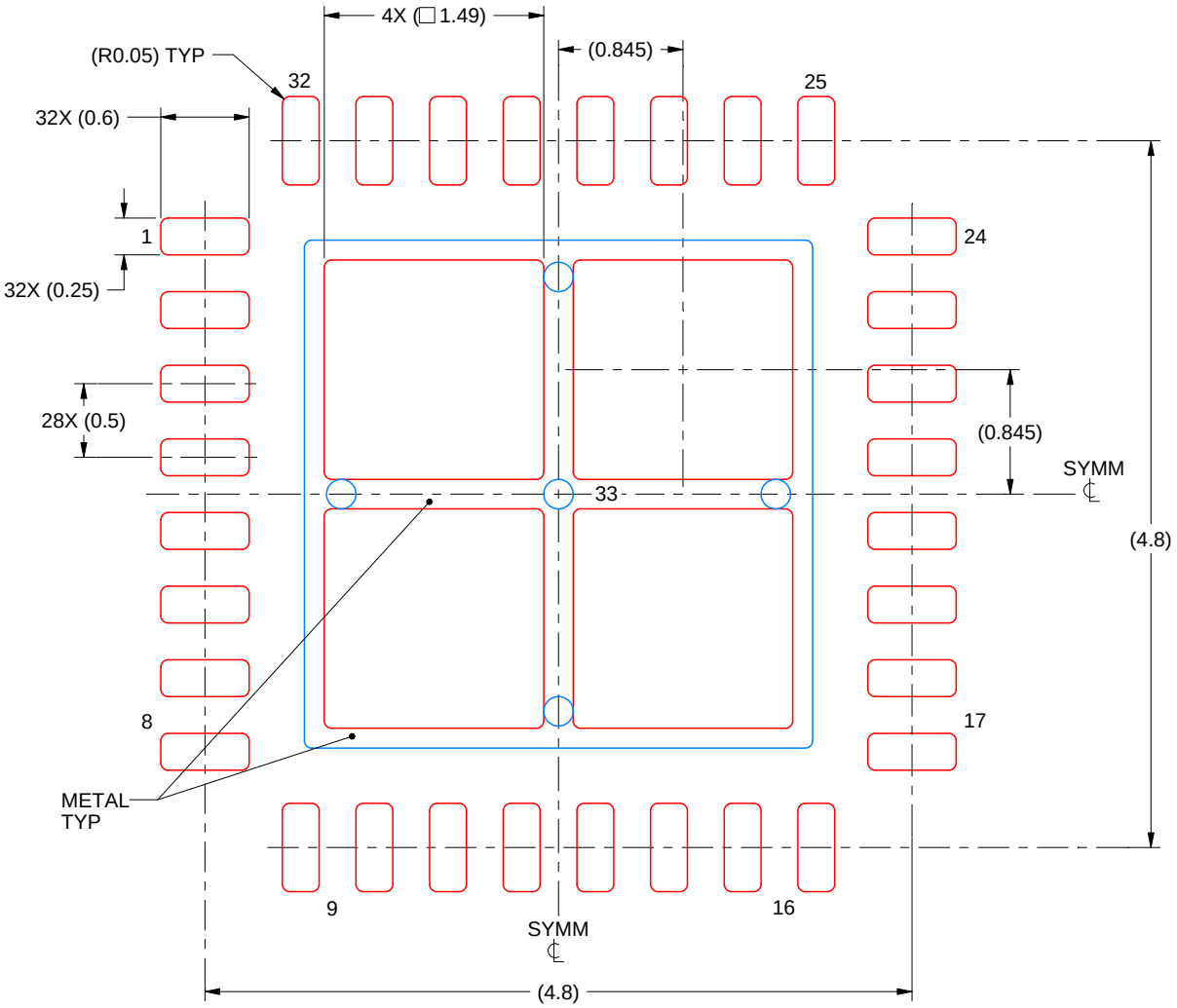


SOLDER MASK DETAILS

4223442/B 08/2019

NOTES: (continued)

4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD 33:
75% PRINTED SOLDER COVERAGE BY AREA UNDER PACKAGE
SCALE:20X

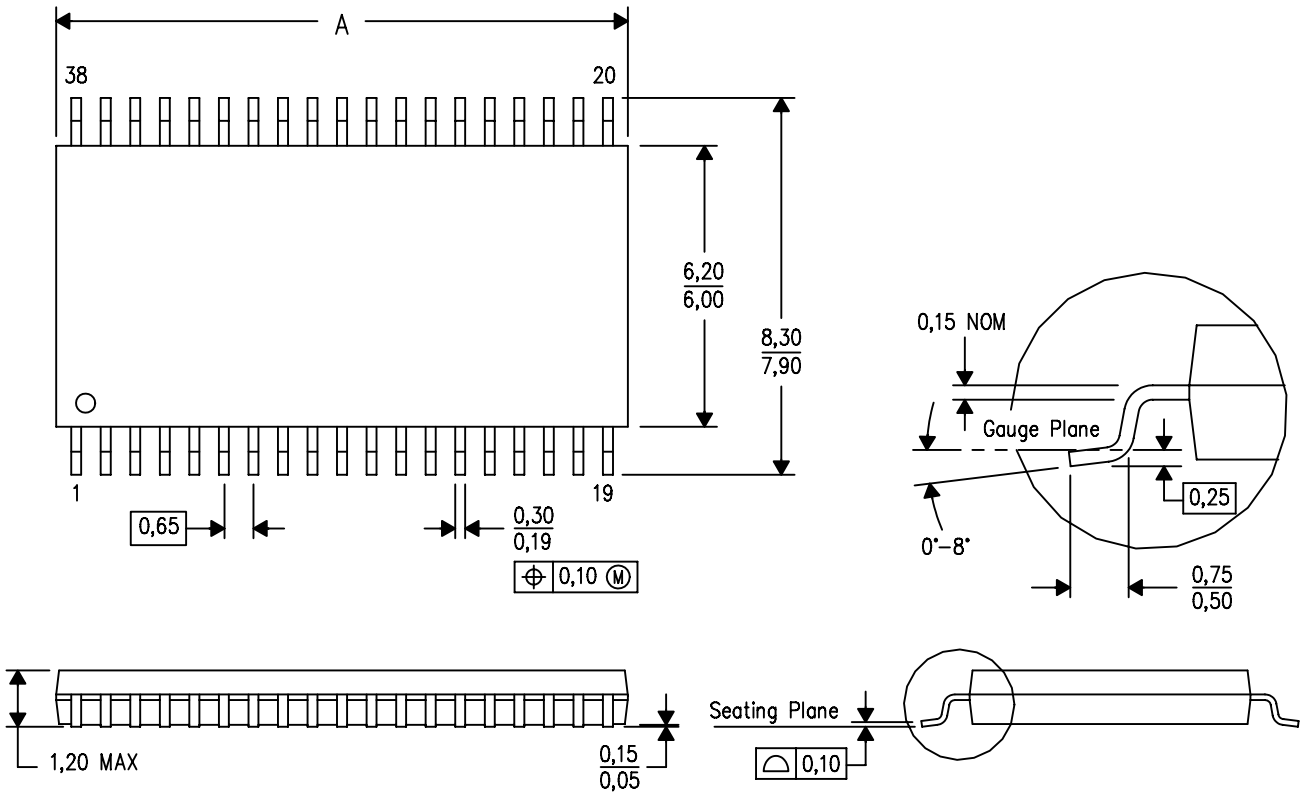
4223442/B 08/2019

NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

DA (R–PDSO–G**) PLASTIC SMALL–OUTLINE PACKAGE

38 PIN SHOWN



DIM \ PINS **	30	32	38
A MAX	11,10	11,10	12,60
A MIN	10,90	10,90	12,40
△D MO–153 Variation	DB–1	DC	DD–1

4040066/F 01/2009

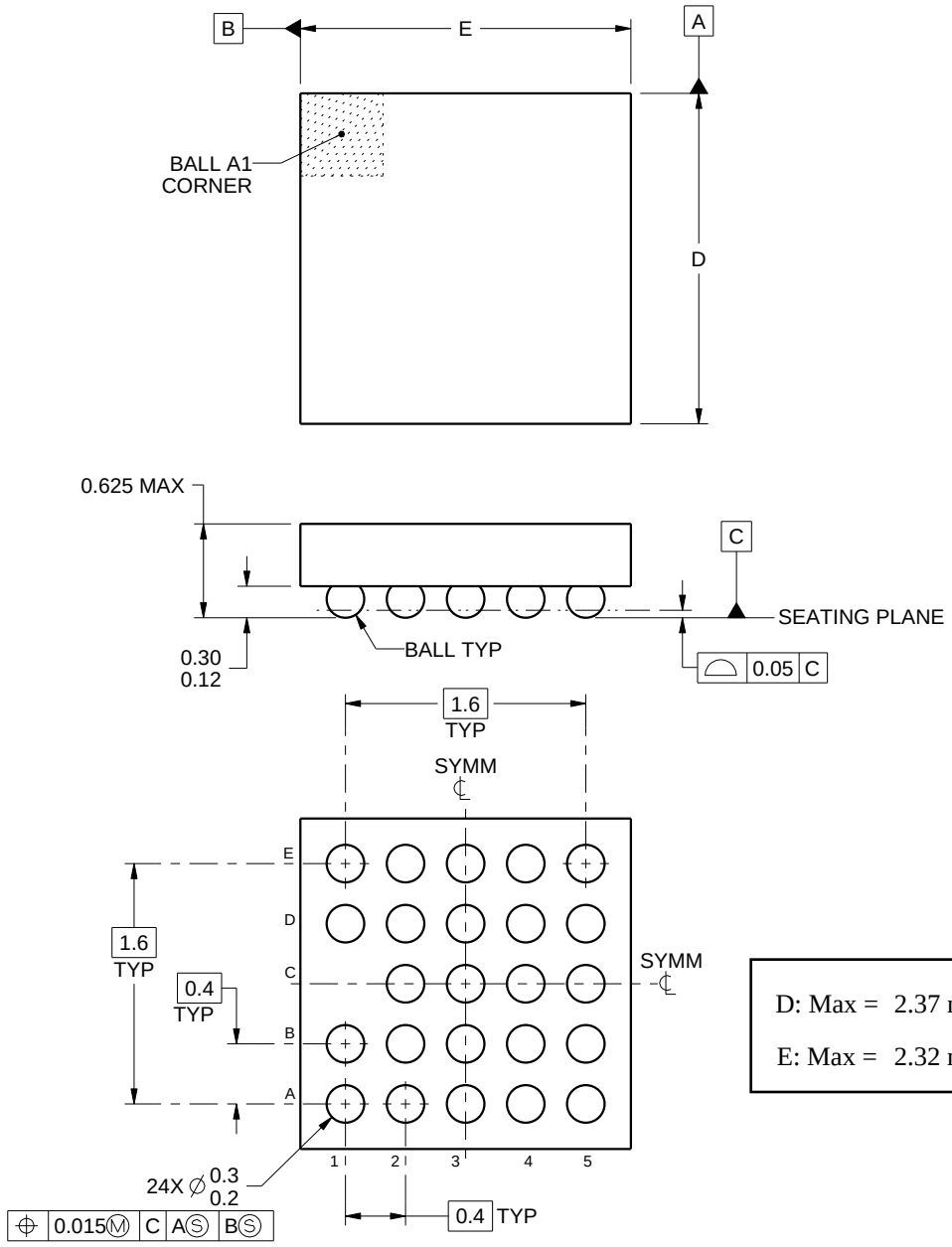
NOTES:
A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion. Mold flash and protrusion shall not exceed 0.15 per side.
△D Falls within JEDEC MO–153, except 30 pin body length.

PACKAGE OUTLINE

YQW0024

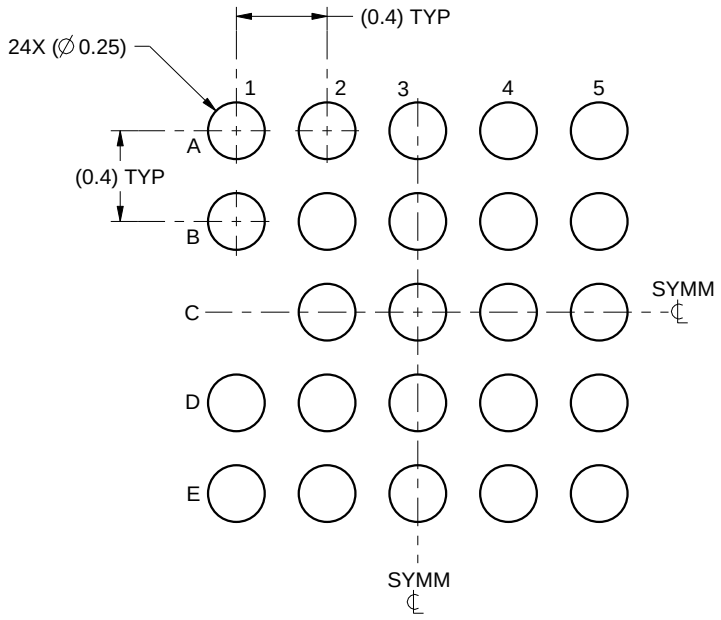
DSBGA - 0.625 mm max height

DIE SIZE BALL GRID ARRAY

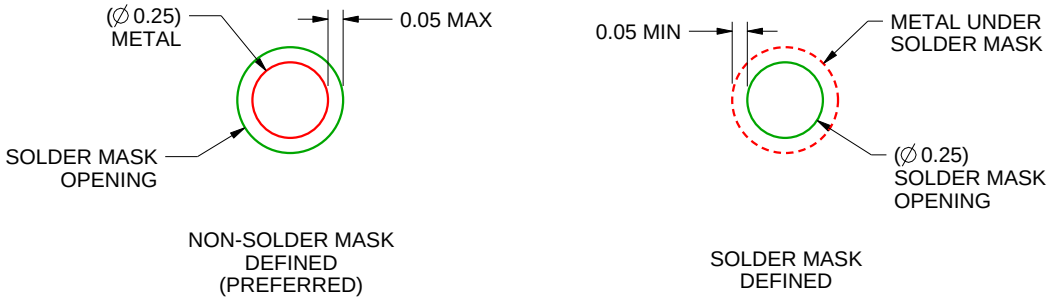


NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.



LAND PATTERN EXAMPLE
SCALE:30X



SOLDER MASK DETAILS
NOT TO SCALE

4221561/A 02/2016

NOTES: (continued)

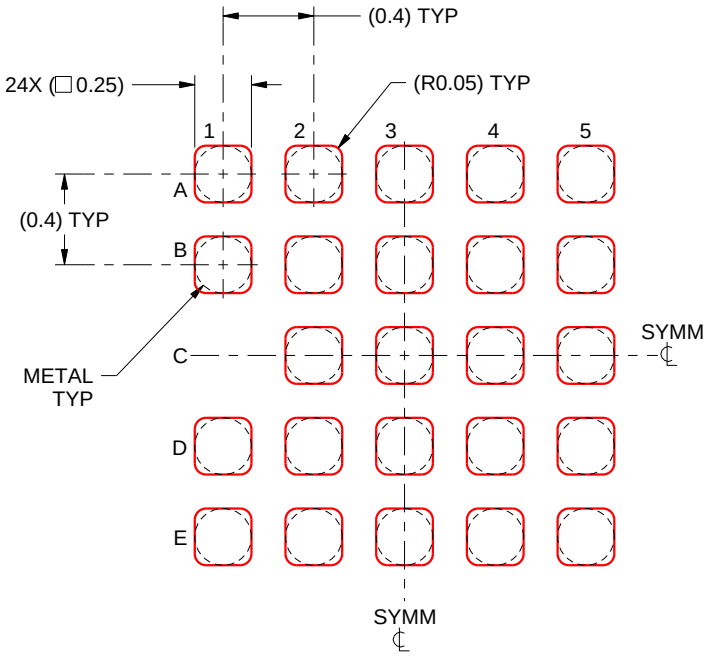
3. Final dimensions may vary due to manufacturing tolerance considerations and also routing constraints.
   See Texas Instruments Literature No. SNVA009 (www.ti.com/lit/snva009).

EXAMPLE STENCIL DESIGN

YQW0024

DSBGA - 0.625 mm max height

DIE SIZE BALL GRID ARRAY



SOLDER PASTE EXAMPLE
BASED ON 0.1 mm THICK STENCIL
SCALE:30X

4221561/A 02/2016

NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release.

重要なお知らせと免責事項

TI は、技術データと信頼性データ (データシートを含みます)、設計リソース (リファレンス· デザインを含みます)、アプリケーションや設計に関する各種アドバイス、Web ツール、安全性情報、その他のリソースを、欠陥が存在する可能性のある「現状のまま」提供しており、商品性および特定目的に対する適合性の黙示保証、第三者の知的財産権の非侵害保証を含むいかなる保証も、明示的または黙示的にかかわらず拒否します。

これらのリソースは、TI 製品を使用する設計の経験を積んだ開発者への提供を意図したものです。(1) お客様のアプリケーションに適した TI 製品の選定、(2) お客様のアプリケーションの設計、検証、試験、(3) お客様のアプリケーションに該当する各種規格や、その他のあらゆる安全性、セキュリティ、規制、または他の要件への確実な適合に関する責任を、お客様のみが単独で負うものとします。

上記の各種リソースは、予告なく変更される可能性があります。これらのリソースは、リソースで説明されている TI 製品を使用するアプリケーションの開発の目的でのみ、TI はその使用をお客様に許諾します。これらのリソースに関して、他の目的で複製することや掲載することは禁止されています。TI や第三者の知的財産権のライセンスが付与されている訳ではありません。お客様は、これらのリソースを自身で使用した結果発生するあらゆる申し立て、損害、費用、損失、責任について、TI およびその代理人を完全に補償するものとし、TI は一切の責任を拒否します。

TI の製品は、TI の販売条件、または ti.com やかかる TI 製品の関連資料などのいずれかを通じて提供する適用可能な条項の下で提供されています。TI がこれらのリソースを提供することは、適用される TI の保証または他の保証の放棄の拡大や変更を意味するものではありません。

お客様がいかなる追加条項または代替条項を提案した場合でも、TI はそれらに異議を唱え、拒否します。

郵送先住所：Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2024, Texas Instruments Incorporated