







UCC27311A-Q1 JAJSR32A - JUNE 2023 - REVISED AUGUST 2023

UCC27311A-Q1 車載用、120V、3.7A/4.5A ハーフブリッジ・ドライバ、8V UVLO、ブートストラップ・ダイオード内蔵、およびイネーブル搭載

1 特長

TEXAS

INSTRUMENTS

- 車載アプリケーション用に認定済み
- 以下の結果で AEC-Q100 認定済み:
 - 温度グレード 1 (T_i = -40℃~150℃)
 - HBM ESD 分類レベル 1B
 - CDM ESD 分類レベル C3
- ハイサイドおよびローサイド構成によって2つのNチ ャネル MOSFET を駆動
- 最大ブート電圧:DC 120V
- 3.7A シンク、4.5A ソース出力電流
- ブートストラップ・ダイオードを内蔵
- 入力ピンは電源電圧範囲に依存せず –10V~+20V を入力可能
- TTL 対応入力
- VDD 動作範囲: UVLO 付き 8V~17V (絶対最大定格 20V)
- 立ち上がり時間 7.2ns、立ち下がり時間 5.5ns (1000pF 負荷時)
- イネーブル / ディセーブル機能、ディセーブル時の低 消費電流 (7µA)
- 高速伝搬遅延時間 (標準 20ns)
- 4ns の遅延マッチング
- 接合部温度定格:--40℃~+150℃

2 アプリケーション

- 車載用 DC/DC コンバータ
- 電動パワー・ステアリング (EPS)
- オンボード・チャージャ (OBC)
- 一体型ベルト・スタータ・ジェネレータ
- ・ 車載用 HVAC (エアコン) コンプレッサ・モジュール

3 概要

UCC27311A-Q1 車載用ハーフ・ブリッジ・ドライバは、 115V の絶対最大スイッチ・ノード (HS) 電圧定格を持つ 堅牢な N チャネル MOSFET ドライバです。 ハーフ・ブリッ ジまたは同期整流降圧構成に基づくトポロジで2つのN チャネル MOSFET を制御できます。 UCC27311A-Q1 は ピーク・ソース電流能力が 3.7A、ピーク・シンク電流能力 が 4.5A であるため、ミラー・プラトー通過時のスイッチング 損失を最小限に抑えて大電力 MOSFET を駆動できま す。UCC27311A-Q1 (HS ピン)の負の過渡電圧を処理 できるため、寄生インダクタンスや浮遊容量によって生じる 固有の負電圧からハイサイド・チャネルを保護できます。

入力構造では DC -10V を直接処理できるため、堅牢性 が増し、整流ダイオードなしでゲート駆動トランスに直接イ ンターフェイスもできます。また、LI および HI 入力は電源 電圧に依存せず、絶対最大定格は 20V です。

制旦椿却

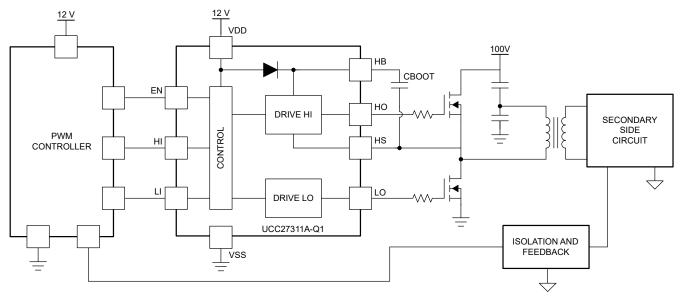
	老女 口口 月 干以		
部品番号	パッケージ ⁽¹⁾	イネーブ ル・ピン	本体サイズ (公 称)
UCC27311A-Q1	DRC (VSON、10)	あり	3.00 × 3.00mm

利用可能なパッケージについては、このデータシートの末尾にあ (1) る注文情報を参照してください。



英語版のTI製品についての情報を翻訳したこの資料は、製品の概要を確認する目的で便宜的に提供しているものです。該当する正式な英語版の最新情報は、 🐼 www.ti.com で閲覧でき、その内容が常に優先されます。 TI では翻訳の正確性および妥当性につきましては一切保証いたしません。 実際の設計などの前には、必ず 最新版の英語版をご参照くださいますようお願いいたします。





代表的なアプリケーションの図



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4 Revision History

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

Changes from Revision * (June 2023) to Revision A (August 2023)

• ステ	ータスを「制限付き APL	_」から「公開 A	PL」に変更	1
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5 概要 (続き)

ローサイドとハイサイドのゲート・ドライバが独立して制御され、それぞれのオン/オフ間に 4ns でマッチングが行われます。 120V 定格のブートストラップ・ダイオードを内蔵しているため、ディスクリート・ブートストラップ・ダイオードは必要はありま せん。ハイサイド・ドライバとローサイド・ドライバの両方に低電圧誤動作防止機能 (UVLO) が搭載され、対称的なオン/オ フ動作を実現しながら、駆動電圧が規定のスレッショルド未満の場合は出力が強制的に Low になります。

4 Submit Document Feedback



6 Pin Configuration and Functions

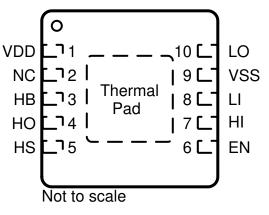


図 6-1. DRC Package 10-Pin SON Top View

表 6-1. Pin Functions

			DESCRIPTION		
NAME	NO. (DRC)	TIPE	DESCRIPTION		
EN	6	P is required. Connect positive side of the bootstrap capacitor to this pin. Typical range of HB bypass capacitor is 0.022 μF to 0.1 μF. The capacitor value is dependant on the gate charge the high-side MOSFET and must also be selected based on speed and ripple criteria. I High-side input. ⁽¹⁾ O High-side output. Connect to the gate of the high-side power MOSFET.			
EN6IEnable input. When this pin is pulled high, it will enable the driver. If left floating or pull will disable the driver. A filter capacitor, typically 1-10nF, is recommended to be placed to VSS (pin 7) to increase noise immunity in sensitive applications.HB3High-side bootstrap supply. The bootstrap diode is on-chip but the external bootstrap is required. Connect positive side of the bootstrap capacitor to this pin. Typical range bypass capacitor is 0.022 μF to 0.1 μF. The capacitor value is dependant on the gate the high-side MOSFET and must also be selected based on speed and ripple criteria.HI7IHigh-side output. Connect to the gate of the high-side power MOSFET.HS5PHigh-side source connection. Connect to source of high-side power MOSFET.LI8ILO10OLow-side input. (1)	bypass capacitor is 0.022 µF to 0.1 µF. The capacitor value is dependent on the gate charge of				
н	7	I	High-side input. ⁽¹⁾		
НО	4	0	High-side output. Connect to the gate of the high-side power MOSFET.		
нѕ	5	Р	High-side source connection. Connect to source of high-side power MOSFET. Connect the negative side of bootstrap capacitor to this pin.		
LI	8	I	Low-side input. ⁽¹⁾		
LO	10	0	Low-side output. Connect to the gate of the low-side power MOSFET.		
		Positive supply to the lower-gate driver. Decouple this pin to V _{SS} (GND). Typical decoupling capacitor range is 0.22 μ F to 4.7 μ F (see ⁽²⁾).			
VSS	9 G Negative supply terminal for the device that is generally grounded.		Negative supply terminal for the device that is generally grounded.		
Thermal pad ⁽³⁾		_	Electrically referenced to V_{SS} (GND). Connect to a large thermal mass trace or GND plane to dramatically improve thermal performance.		

(1) HI, LI, and EN inputs are assumed to connect to a low impedance source signal. The source output impedance is assumed less than 100Ω . If the source impedance is greater than 100Ω , add a bypassing capacitor, each, between HI to VSS, LI to VSS, and EN to VSS. The added capacitor value depends on the noise levels presented on the pins, typically from 1 nF to 10 nF should be effective to eliminate the possible noise effect. When noise is present on two pins, HI or LI, the effect is to cause HO and LO malfunctions to have wrong logic outputs.

For cold temperature applications TI recommends the upper capacitance range. Follow the Layout Guidelines for PCB layout.
The thermal pad is not directly connected to any leads of the package; however, it is electrically and thermally connected to the

- substrate which is the ground of the device.
- (4) G = Ground, I = Input, O = Output, and P = Power.



7 Specifications

7.1 Absolute Maximum Ratings

Over operating free-air temperature range and all voltages are with respect to V_{ss} (unless otherwise noted).⁽¹⁾

			MIN	MAX	UNIT
V _{DD}	Supply voltage		-0.3	20	V
V _{HI} , V _{LI}	Input voltages on HI and LI		-10	20	V
V _{EN}	Input voltages on EN	Input voltages on EN	-10	20	V
V		DC	-0.3	V _{DD} + 0.3	0.3
V _{LO}	Output voltage on LO	Repetitive pulse < 100 ns ⁽²⁾	-2	V _{DD} + 0.3	V
		DC	V _{HS} – 0.3	V _{HB} + 0.3	V
V _{HO}	Output voltage on HO	Repetitive pulse < 100 ns ⁽²⁾	V _{HS} – 2	V _{HB} + 0.3	
	Voltage on HS	DC	-1	115	
V _{HS}		Repetitive pulse < 100 ns ⁽²⁾	–(24V - V _{DD})	115	V
V _{HB}	Voltage on HB	1	-0.3	120	V
	Voltage on HB-HS		-0.3	20	V
TJ	Operating junction temperature		-40	150	°C
	Lead temperature (soldering, 10 sec.)			300	°C
T _{stg}	Storage temperature		-65	150	°C

(1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

(2) Values are verified by characterization and are not production tested.

7.2 ESD Ratings

			VALUE	UNIT
V.===	Electrostatic discharge	Human-body model (HBM), per AEC Q100-002 ⁽¹⁾	±2000	V
V _(ESD)		Charged-device model (CDM), per AEC Q100-011	±1500	v

(1) AEC Q100-002 indicates that HBM stressing shall be in accordance with the ANSI/ESDA/JEDEC JS-001 specification.

7.3 Recommended Operating Conditions

Over operating free-air temperature range and all voltages are with respect to V_{ss} (unless otherwise noted).

		MIN	NOM	MAX	UNIT
V _{DD}	Supply voltage	8	12	17	V
V	Voltage on HS	-1		105	
V _{HS}	Voltage on HS (repetitive pulse < 100 ns) ⁽¹⁾	-(24V - V _{DD})		110	V
V _{HB}	Voltage on HB	V _{HS} + 8.0, V _{DD} - 1		V _{HS} + 17, 115	
SR _{HS}	Voltage slew rate on HS			50	V/ns
TJ	Operating junction temperature	-40		150	°C

(1) Values are verified by characterization and are not production tested.

7.4 Thermal Information

		UCC27311A-Q1	
	THERMAL METRIC ⁽¹⁾	DRC (VSON)	UNIT
		10 Pins	
R _{θJA}	Junction-to-ambient thermal resistance	51.9	°C/W
R _{0JC(top)}	Junction-to-case (top) thermal resistance	58.3	°C/W
$R_{ heta JB}$	Junction-to-board thermal resistance	24.6	°C/W

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7.4 Thermal Information (continued)

		UCC27311A-Q1	
	THERMAL METRIC ⁽¹⁾	DRC (VSON)	UNIT
		10 Pins	
Ψ _{JT}	Junction-to-top characterization parameter	1.7	°C/W
Ψјв	Junction-to-board characterization parameter	24.6	°C/W
R _{0JC(bot)}	Junction-to-case (bottom) thermal resistance	9.2	°C/W

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report, SPRA953.

7.5 Electrical Characteristics

 $V_{DD} = V_{HB} = 12 \text{ V}, V_{HS} = V_{SS} = 0 \text{ V}, \text{ No load on LO or HO}, T_A = T_J = -40^{\circ}\text{C to } +150^{\circ}\text{C}, \text{ (unless otherwise noted)}.$

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
SUPPLY C	URRENTS	1				
I _{DD}	VDD quiescent current	V _{LI} = V _{HI} = 0, V _{EN} = 3V	0.05	0.085	0.17	mA
I _{DDO}	VDD operating current	f = 500 kHz, C _{LOAD} = 0, V _{EN} = 3V	2.1	2.5	6.5	mA
I _{HB}	Boot voltage quiescent current	V _{LI} = V _{HI} = 0 V, V _{EN} = 3V	0.015	0.065	0.1	mA
I _{HBO}	Boot voltage operating current	f = 500 kHz, C _{LOAD} = 0, V _{EN} = 3V	1.5	2.5	5.1	mA
I _{HBS}	HB to VSS quiescent current	V _{HS} = V _{HB} = 105 V, V _{EN} = 3V		0.0005	1	μA
I _{HBSO}	HB to VSS operating current	f = 500 kHz, C _{LOAD} = 0, V _{EN} = 3V		0.07	1.2	mA
I _{DD_DIS}	Driver Current when EN pin is pulled low (Disabled)	V _{EN} = 0		7		μA
INPUT		1				
V _{HIT_HI}	Input voltage high threshold		1.7	2.3	2.55	V
V _{HIT_LI}	Input voltage high threshold		1.7	2.3	2.55	V
V _{LIT_HI}	Input voltage low threshold		1.2	1.6	1.9	V
V _{LIT_LI}	Input voltage low threshold		1.2	1.6	1.9	V
V _{IHYS HI}	Input voltage Hysteresis			0.7		V
VIHYS LI	Input voltage Hysteresis			0.7		V
R _{IN_HI}	Input pulldown resistance	V _{IN} = 3V		68		kΩ
R _{IN_LI}	Input pulldown resistance	V _{IN} = 3V		68		kΩ
ENABLE	1	•				
V _{EN}	Voltage threshold on EN pin to enable the driver		1.7	2.3	2.55	V
V _{DIS}	Voltage threshold on EN pin to disable the driver		1.2	1.6	1.9	V
V _{ENHYS}	Enable pin Hysteresis			0.7		V
R _{EN}	EN pin internal pull-down resistance	V _{EN} = 3V		80		kΩ
T _{EN}	EN pin response time	V _{EN} = 3V		18	70	μs
T _{DIS}	EN pin response time	V _{EN} = 0V		1.5	10	μs
UNDERVO	LTAGE PROTECTION (UVLO)					
V _{DDR}	VDD rising threshold		6.2	7	7.8	V
V _{DDHYS}	VDD threshold hysteresis			0.5		V
V _{HBR}	VHB rising threshold		5.6	6.7	7.9	V
V _{HBHYS}	VHB threshold hysteresis			1.1		V
BOOTSTR	AP DIODE	•			I	
V _F	Low-current forward voltage	Ι _{VDD - HB} = 100 μA		0.65	0.8	V
V _{FI}	High-current forward voltage	I _{VDD - HB} = 100 mA		0.9	1.05	V
R _D	Dynamic resistance, ΔVF/ΔI	$I_{VDD - HB}$ = 160 mA and 180 mA	0.3	0.5	0.85	Ω
LO GATE I	DRIVER					
V _{LOL}	Low level output voltage	I _{LO} = 100 mA		0.1	0.19	V

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7.5 Electrical Characteristics (continued)

 $V_{DD} = V_{HB} = 12 \text{ V}, V_{HS} = V_{SS} = 0 \text{ V}$, No load on LO or HO, $T_A = T_J = -40^{\circ}\text{C}$ to +150°C, (unless otherwise noted).

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V _{LOH}	High level output voltage	I_{LO} = -100 mA, V_{LOH} = $V_{DD} - V_{LO}$		0.16	0.29	V
	Peak pullup current ⁽¹⁾	V _{LO} = 0 V		3.7		А
	Peak pulldown current ⁽¹⁾	V _{LO} = 12 V		4.5		А
HO GATE	DRIVER					
V _{HOL}	Low level output voltage	I _{HO} = 100 mA		0.1	0.19	V
V _{HOH}	High level output voltage	I_{HO} = -100 mA, V_{HOH} = V_{HB} - V_{HO}		0.16	0.29	V
	Peak pullup current ⁽¹⁾	V _{HO} = 0 V		3.7		А
	Peak pulldown current ⁽¹⁾	V _{HO} = 12 V		4.5		А

(1) Parameter not tested in production.

7.6 Switching Characteristics

 $V_{DD} = V_{HB} = 12 \text{ V}, V_{HS} = V_{SS} = 0 \text{ V}$, No load on LO or HO, $T_A = T_J = -40^{\circ}\text{C}$ to +150°C, (unless otherwise noted).

	PARAMETER	TEST CONDITIONS	MIN TYP	MAX	UNIT
PROPAGAT	ION DELAYS				
t _{DLFF}	VLI falling to VLO falling	C_{LOAD} = 0 pF, from V_{LIT} of LI to 90% of LO falling			ns
t _{DHFF}	VHI falling to VHO falling	C_{LOAD} = 0 pF, from V _{LIT} of HI to 90% of HO falling	16		ns
t _{DLRR}	VLI rising to VLO rising	C_{LOAD} = 0 pF, from V _{HIT} of LI to 10% of LO rising	20		ns
t _{DHRR}	VHI rising to VHO rising	C_{LOAD} = 0 pF, C_{LOAD} = 0 pF, from V _{HIT} of HI to 10% of HO rising	20		ns
DELAY MAT	CHING				
t _{MON}	LI ON, HI OFF	$T_J = 25^{\circ}$ C, from 10% of LO rising to 90% of HO falling	4	9.5	ns
t _{MON}	LI ON, HI OFF	T_J = -40°C to 150°C, from 10% of LO rising to 90% of HO falling			ns
t _{MOFF}	LI OFF, HI ON	$T_J = 25^{\circ}$ C, from 90% of LO falling to 10% of HO rising	o 10%		ns
t _{MOFF}	LI OFF, HI ON	$T_J = -40^{\circ}$ C to 150°C, from 90% of LO falling to 10% of HO rising	4	17	ns
OUTPUT RIS	SE AND FALL TIME				
t _{R_LO}	LO rise time	C _{LOAD} = 1000 pF, from 10% to 90%	7.2		ns
t _{R_HO}	HO rise time	C _{LOAD} = 1000 pF, from 10% to 90%	7.2		ns
t _{F_LO}	LO fall time	C _{LOAD} = 1000 pF, from 10% to 90%	5.5		ns
t _{F_HO}	HO fall time	C _{LOAD} = 1000 pF, from 10% to 90%	5.5		ns
t _{R_LO_p1}	LO rise time (3 V to 9 V)	C _{LOAD} = 0.1 µF, (3V to 9V)	0.36	0.6	μs
t _{R_HO_p1}	HO rise time (3 V to 9 V)	C _{LOAD} = 0.1 µF, (3V to 9V)	0.36	0.6	μs
t _{F_LO_p1}	LO fall time (9 V to 3 V)	C _{LOAD} = 0.1 µF, (9V to 3V)	0.15	0.4	μs
t _{F_HO_p1}	HO fall time (9 V to 3 V)	C _{LOAD} = 0.1 µF, (9V to 3V)	0.15	0.4	μs
MISCELLAN	IEOUS				
t _{IN_PW}	Minimum input pulse width that changes the output LO			50	ns
t _{IN_PW}	Minimum input pulse width that changes the output HO			50	ns
t _{OFF_BSD}	Bootstrap diode turnoff time ⁽¹⁾ ⁽²⁾	I _F = 20 mA, I _{REV} = 0.5 A ⁽³⁾	20		ns

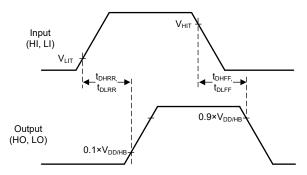
(1) Parameter not tested in production.

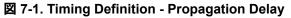
(2) Typical values for $T_A = 25^{\circ}C$.

(3) I_F: Forward current applied to bootstrap diode, I_{REV}: Reverse current applied to bootstrap diode.



7.7 Timing Diagrams





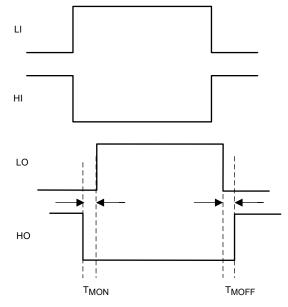


図 7-2. Timing Definition - Delay Matching



8 Detailed Description

8.1 Overview

The UCC27311A-Q1 is a high-voltage gate driver designed to drive both the high-side and the low-side Nchannel MOSFETs in a synchronous buck or a half-bridge configurations. The two outputs are independently controlled with two TTL-compatible input signals. The device can also work with CMOS type control signals at its inputs as long as the signals meet the turn-on and turn-off threshold specifications of the device. The floating high-side driver is capable of operating with an HB voltage up to 115 V with respect to VSS. A 120-V bootstrap diode is integrated in the UCC27311A-Q1 device to charge the high-side gate drive bootstrap capacitor. A robust level shifter operates at high speed while consuming low power and provides clean level transitions from the control logic to the high-side gate driver. Undervoltage lockout (UVLO) is provided on both the low-side and the high-side power rails. EN pin is provided (in DRC packaged parts) to enable or disable the driver.

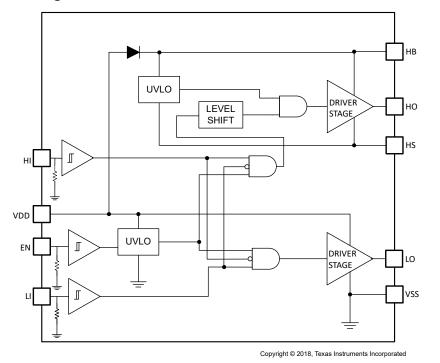
In the UCC27311A-Q1 automotive device, the high side and low side have seperate inputs that allow maximum flexibility of input control signals in the application. The boot diode for the high-side driver bias supply is internal to the UCC27311A-Q1. The high-side driver is referenced to the switch node (HS), which is typically the source pin of the high-side MOSFET and drain pin of the low-side MOSFET. The low-side driver is referenced to V_{SS} , which is typically ground. The UCC27311A-Q1 functions are divided into the input stages, UVLO protection, level shift, boot diode, and output driver stages.

FEATURE	BENEFIT
+3.7-A/-4.5-A peak source and sink currents	High peak current ideal for driving large power MOSFETs with minimal power loss (fast-drive capability at Miller plateau)
Input pins (HI and LI) can directly handle –10 VDC up to 20 VDC	Increased robustness and ability to handle undershoot and overshoot can interface directly to gate-drive transformers without having to use rectification diodes.
120-V internal boot diode	Provides voltage margin to meet telecom 100-V surge requirements
Switch node (HS pin) able to handle –18 V maximum for 100 ns	Allows the high-side channel to have extra protection from inherent negative voltages caused by parasitic inductance and stray capacitance
Robust ESD circuitry to handle voltage spikes	Excellent immunity to large dV/dT conditions
16-ns/20-ns propagation delays with 7.2-ns rise time and 5.5-ns fall time	Best-in-class switching characteristics and extremely low-pulse transmission distortion
Enable/disable functionality	Offers additional control over the driver for different system states (such as powerup sequencing) and a low quiescent current consumption when disabled
4-ns (typical) delay matching between channels	Avoids transformer volt-second offset in bridge
Symmetrical UVLO circuit	Ensures high-side and low-side shut down at the same time
TTL optimized thresholds with increased hysteresis	Complementary to analog or digital PWM controllers; increased hysteresis offers added noise immunity

表 8-1. UCC27311A-Q1 Highlights



8.2 Functional Block Diagram



8.3 Feature Description

8.3.1 Input Stages

The two inputs operate independently. The independence allows for full control of two outputs compared to the gate drivers that have a single input. There is no other fixed time de-glitch filter implemented in the device and therefore propagation delay and delay matching are not sacrificed. In other words, there is no built-in dead-time.

The inputs are TTL-logic compatible. The device can also work with CMOS type control signals at its inputs as long as the signals meet the turn-on and turn-off threshold specifications of the device. Because the inputs are independent of supply voltage, they can be connected to outputs of either digital controller or analog controller. Inputs can accept wide slew rate signals and input can withstand negative voltage to increase the robustness. Small filter at the inputs of the driver further improves system robustness in noise prone applications. The inputs have internal pull down resistors with typical value of 68 k Ω . Thus, when the inputs are floating, the outputs are held low.

8.3.2 Enable

The device has an enable (EN) pin. The outputs will be active only if the EN pin voltage is above the threshold voltage. Outputs will be held low if EN pin is left floating or pulled-down to ground. An internal 80-k Ω resistor pulls the EN pin to VSS. Thus, leaving the EN pin floating disables the device. Externally pulling EN pin to ground shall also disable the device. If the EN pin is not used, then it is recommended to tie it to VDD pin. If a pull-up resistor needs to be used then a strong pull-up resistor is recommended. For 12-V supply voltage, a 10-k Ω pull-up is suggested. In noise prone application, a small filter capacitor, 1 nF to 10 nF, should be connected from the EN pin to VSS pin as close to the device. Built-in hysteresis helps prevent any nuisance tripping or chattering of the outputs.

8.3.3 Undervoltage Lockout (UVLO)

Both the high-side and the low-side driver stages include UVLO protection circuitry which monitors the supply voltage (VDD) and the bootstrap capacitor voltage (V_{HB} to V_{HS}). The UVLO circuit inhibits each output until sufficient supply voltage is available to turn on the external MOSFETs. The built-in UVLO hysteresis prevents chattering during supply voltage variations. When the supply voltage is applied to the VDD pin of the device,



both the outputs are held low until VDD exceeds the UVLO threshold. Any UVLO condition on the bootstrap capacitor (VHB–HS) disables only the high-side output (HO).

8.3.4 Level Shifter

The level shift circuit is the interface from the high-side input, which is a VSS referenced signal, to the high-side driver stage which is referenced to the switch node (HS pin). The level shift allows control of the HO output which is referenced to the HS pin. The delay introduced by the level shifter is kept as low as possible and therefore the device provides excellent propagation delay characteristic and delay matching with the low-side driver output. Low delay matching allows power stages to operate with less dead time. The reduction in dead time is very important in applications where high efficiency is required.

8.3.5 Boot Diode

The boot diode necessary to generate the high-side bias is included in the UCC27311A-Q1 family of drivers. The diode anode is connected to V_{DD} and cathode connected to V_{HB} . With the V_{HB} capacitor connected to HB and the HS pins, the V_{HB} capacitor charge is refreshed every switching cycle when HS transitions to ground. The boot diode provides fast recovery times, low diode resistance, and voltage rating margin to allow for efficient and reliable operation.

8.3.6 Output Stages

The output stages are the interface to the power MOSFETs in the power train. High slew rate, low resistance and high peak current capability of both output drivers allow for efficient switching of the power MOSFETs. The low-side output stage is referenced from V_{DD} to V_{SS} and the high side is referenced from V_{HB} to V_{HS} . The device output stages feature a pull-up structure which delivers the highest peak source current when it is most needed, during the Miller plateau region of the power switch turn on transition. The output pull-up and pull-down structure of the device is totem pole NMOS-PMOS structure.

8.3.7 Negative Voltage Transients

In most applications, the body diode of the external low-side power MOSFET clamps the HS node to ground. In some situations, board capacitance and inductance can cause the HS node to transiently swing several volts below ground, before the body diode of the external low-side MOSFET clamps this swing. The HS pin in the device is allowed to swing below ground as long as specifications are not violated and conditions mentioned in this section are followed.

Ensure that the HB to HS operating voltage is within the recommended operating conditions. Hence, if the HS pin transient voltage is –5 V, then VDD (and thus HB) is ideally limited to 12 V to keep the HB to HS voltage below 17 V. Generally when HS swings negative, HB follows HS instantaneously and therefore the HB to HS voltage does not significantly overshoot.

HS must always be at a lower potential than HO. Pulling HO more negative than specified conditions can activate parasitic transistors which may result in excessive current flow from the HB supply. This may result in damage to the device. The same relationship is true with LO and VSS. If necessary, a Schottky diode can be placed externally between HO and HS or LO and VSS to protect the device from this type of transient. The diode must be placed as close to the device pins as possible in order to be effective.

Low ESR bypass capacitors from HB to HS and from VDD to VSS are essential for proper operation of the gate driver device. The capacitor should be located at the leads of the device to minimize series inductance. The peak currents from LO and HO can be quite large. Any series inductance with the bypass capacitor causes voltage ringing at the leads of the device which must be avoided for reliable operation.

Based on application board design and other operating parameters, along with HS pin, other pins such as HI and LI input pins might also transiently swing below ground. To accommodate such operating conditions, the input pins of the device are capable of handling absolute maximum of -10 V. Based on the layout and other design constraints, sometimes the outputs, HO and LO, might also see transient voltages for short durations. Therefore, the device can also handle -2-V transients with less than 100-ns duration on the HO and LO output pins.



8.4 Device Functional Modes

When the device is enabled, the device operates in normal mode and UVLO mode. See $222 \times 8.3.3$ for more information on UVLO operation mode. In normal mode when the VDD and VHB–HS are above UVLO threshold, the output stage is dependent on the states of the EN, HI and LI pins. The output HO and LO will be low if input state is floating.

EN ⁽¹⁾	HI	LI	HO ²	LO ³
L	Х	Х	L	L
Н	L	L	L	L
Н	L	Н	L	Н
Н	Н	L	Н	L
Н	Н	Н	Н	Н

表 8-2. Device Logic Table

(1) EN pin is available only in DRC package.

(2) HO is measured with respect to HS.

(3) LO is measured with respect to VSS.



9 Application and Implementation

注

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

9.1 Application Information

To affect fast switching of power devices and reduce associated switching power losses, a powerful gate driver is employed between the PWM output of controllers and the gates of the power semiconductor devices. Also, gate drivers are indispensable when it is impossible for the PWM controller to directly drive the gates of the switching devices. With the advent of digital power, this situation will be often encountered because the PWM signal from the digital controller is often a 3.3-V logic signal which cannot effectively turn on a power switch. Level shifting circuitry is needed to boost the 3.3-V signal to the gate-drive voltage (such as 12 V) in order to fully turn on the power device and minimize conduction losses. Traditional buffer drive circuits based on NPN/PNP bipolar transistors in totem-pole arrangement, being emitter follower configurations, prove inadequate with digital power because they lack level-shifting capability. Gate drivers effectively combine both the level-shifting and buffer-drive functions. Gate drivers also find other needs such as minimizing the effect of high-frequency switching noise by locating the high-current driver physically close to the power switch, driving gate-drive transformers, and controlling floating power-device gates, reducing power dissipation and thermal stress in controllers by moving gate charge power losses from the controller into the driver.

9.2 Typical Application

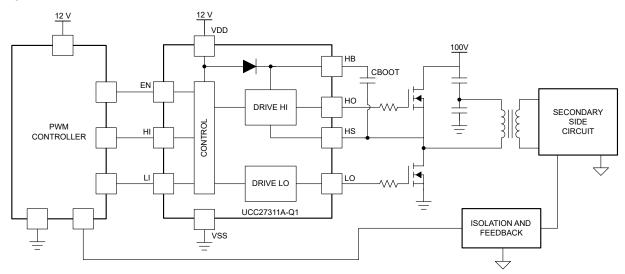
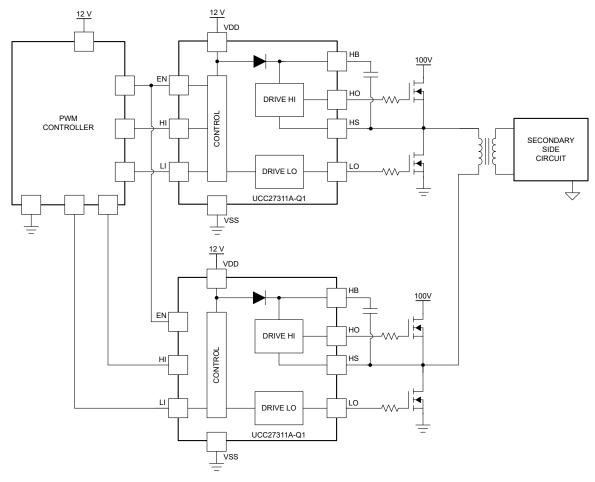


図 9-1. UCC27311A-Q1 Typical Application Diagram







9.2.1 Design Requirements

For this design example, use the parameters listed in \pm 9-1.

表 9-1.	Design	Specifications	

DESIGN PARAMETER	EXAMPLE VALUE				
Supply voltage, VDD	12 V				
Voltage on HS, VHS	0 V to 100 V				
Voltage on HB, VHB	12 V to 112 V				
Output current rating, IO	-4.5 A to 3.7A				
Operating frequency	500 kHz				



9.2.2 Detailed Design Procedure

9.2.2.1 Input Threshold Type

The UCC27311A-Q1 device has an input absolute maximum voltage range from -10 V to 20 V. This increased robustness means that both parts can be directly interfaced to gate drive transformers. The device features TTL compatible input threshold logic with wide hysteresis. The threshold voltage levels are low voltage and independent of the VDD supply voltage, which allows compatibility with both logic-level input signals from microcontrollers as well as higher-voltage input signals from analog controllers. See the Electrical Characteristics section for the actual input threshold voltage levels and hysteresis specifications of the device.

9.2.2.2 V_{DD} Bias Supply Voltage

The bias supply voltage to be applied to the VDD pin of the device should never exceed the values listed in the Electrical Characteristics table. However, different power switches demand different voltage levels to be applied at the gate terminals for effective turnon and turnoff. With certain power switches, a positive gate voltage may be required for turnon and a negative gate voltage may be required for turnoff, in which case the VDD bias supply equals the voltage differential. With a wide operating range from 8 V to 17 V, the device can be used to drive a variety of power switches, such as Si MOSFETs, IGBTs, and wide-bandgap power semiconductors (such as GaN, certain types of which allow no higher than 6 V to be applied to the gate terminals).

9.2.2.3 Peak Source and Sink Currents

Generally, the switching speed of the power switch during turnon and turnoff should be as fast as possible in order to minimize switching power losses. The gate driver device must be able to provide the required peak current for achieving the targeted switching speeds with the targeted power MOSFET. The system requirement for the switching speed is typically described in terms of the slew rate of the drain-to-source voltage of the power MOSFET (such as dV_{DS}/dt). For example, the system requirement might state that a SPP20N60C3 power MOSFET must be turned-on with a dV_{DS}/dt of 20 V/ns or higher with a DC bus voltage of 400 V in a continuous-conduction-mode (CCM) boost PFC-converter application. This type of application is an inductive hard-switching application and reducing switching power losses is critical. This requirement means that the entire drain-to-source voltage swing during power MOSFET turnon event (from 400 V in the OFF state to $V_{DS(on)}$ in on state) must be completed in approximately 20 ns or less. When the drain-to-source voltage swing occurs, the Miller charge of the power MOSFET (Q_{GD} parameter in the SPP20N60C3 data sheet is 33 nC typical) is supplied by the peak current of gate driver. According to power MOSFET inductive switching mechanism, the gate-to-source voltage of the power MOSFET at this time is the Miller plateau voltage, which is typically a few volts higher than the threshold voltage of the power MOSFET, $V_{GS(TH)}$.

To achieve the targeted dV_{DS}/dt, the gate driver must be capable of providing the Q_{GD} charge in 20 ns or less. In other words a peak current of 1.65 A (= 33 nC / 20 ns) or higher must be provided by the gate driver. The UCC27311A-Q1 gate driver is capable of providing 3.7-A peak sourcing current which clearly exceeds the design requirement and has the capability to meet the switching speed needed. The 2.4× overdrive capability provides an extra margin against part-to-part variations in the Q_{GD} parameter of the power MOSFET along with additional flexibility to insert external gate resistors and fine tune the switching speed for efficiency versus EMI optimizations. However, in practical designs the parasitic trace inductance in the gate drive circuit of the PCB will have a definitive role to play on the power MOSFET switching speed. The effect of this trace inductance is to limit the dl/dt of the output current pulse of the gate driver. In order to illustrate this, consider output current pulse waveform from the gate driver to be approximated to a triangular profile, where the area under the triangle $(\frac{1}{2} \times I_{PFAK} \times time)$ would equal the total gate charge of the power MOSFET (Q_G parameter in SPP20N60C3) power MOSFET datasheet = 87 nC typical). If the parasitic trace inductance limits the dl/dt then a situation may occur in which the full peak current capability of the gate driver is not fully achieved in the time required to deliver the Q_G required for the power MOSFET switching. In other words the time parameter in the equation would dominate and the IPFAK value of the current pulse would be much less than the true peak current capability of the device, while the required Q_G is still delivered. Because of this, the desired switching speed may not be realized, even when theoretical calculations indicate the gate driver is capable of achieving the targeted switching speed. Thus, placing the gate driver device very close to the power MOSFET and designing a tight gate drive-loop with minimal PCB trace inductance is important to realize the full peak-current capability of the gate driver.

9.2.2.4 Propagation Delay

The acceptable propagation delay from the gate driver is dependent on the switching frequency at which it is used and the acceptable level of pulse distortion to the system. The UCC27311A-Q1 device features 16-ns and 20-ns (typical) propagation delays, which ensures very little pulse distortion and allows operation at very high-frequencies. See the Switching Characteristics table for the propagation and switching characteristics of the device.

9.2.2.5 Power Dissipation

Power dissipation of the gate driver has two portions as shown in \neq 1.

$$P_{DISS} = P_{DC} + P_{SW}$$

Use \neq 2 to calculate the DC portion of the power dissipation (PDC).

$$PDC = I_Q \times V_{DD}$$

where

• I_Q is the quiescent current for the driver.

The quiescent current is the current consumed by the device to bias all internal circuits such as input stage, reference voltage, logic circuits, protections, and also any current associated with switching of internal devices when the driver output changes state (such as charging and discharging of parasitic capacitances, parasitic shoot-through, and so forth). The UCC27311A-Q1 features very low quiescent currents and contains internal logic to eliminate any shoot-through in the output driver stage. Thus the effect of the PDC on the total power dissipation within the gate driver can be safely assumed to be negligible. The power dissipated in the gate-driver package during switching (PSW) depends on the following factors:

- Gate charge required of the power device (usually a function of the drive voltage VG, which is very close to input bias supply voltage VDD)
- Switching frequency
- Use of external gate resistors. When a driver device is tested with a discrete, capacitive load calculating the power that is required from the bias supply is fairly simple. The energy that must be transferred from the bias supply to charge the capacitor is given by 式 3.

$$EG = \frac{1}{2}C_{LOAD} \times V_{DD}^{2}$$

- C_{LOAD} is load capacitor
- V_{DD} is bias voltage feeding the driver

There is an equal amount of energy dissipated when the capacitor is charged and when it is discharged. This leads to a total power loss given by ± 4 .

$$PG = C_{LOAD} \times V_{DD}^{2} \times f_{SW}$$

where

• f_{SW} is the switching frequency

The switching load presented by a power MOSFET/IGBT is converted to an equivalent capacitance by examining the gate charge required to switch the device. This gate charge includes the effects of the input capacitance plus the added charge needed to swing the drain voltage of the power device as it switches between the ON and OFF states. Most manufacturers provide specifications of typical and maximum gate charge, in nC, to switch the device under specified conditions. Using the gate charge Qg, determine the power that must be dissipated when switching a capacitor which is calculated using the equation $Q_G = C_{LOAD} \times V_{DD}$ to provide \vec{x} 5 for power.

(2)

(3)

(4)

(1)



(5)

$P_{G} = C_{LOAD} \times V_{DD}^{2} \times f_{SW} = Q_{G} \times V_{DD} \times f_{SW}$

This power P_G is dissipated in the resistive elements of the circuit when the MOSFET/IGBT is being turned on and off. Half of the total power is dissipated when the load capacitor is charged during turnon, and the other half is dissipated when the load capacitor is discharged during turnoff. When no external gate resistor is employed between the driver and MOSFET/IGBT, this power is completely dissipated inside the driver package. With the use of external gate-drive resistors, the power dissipation is shared between the internal resistance of driver and external gate resistor.

10 Power Supply Recommendations

The bias supply voltage range for which the device is recommended to operate is from 8 V to 17 V. The lower end of this range is governed by the internal undervoltage-lockout (UVLO) protection feature on the V_{DD} pin supply circuit blocks. Whenever the driver is in UVLO condition when the V_{DD} pin voltage is below the $V_{(ON)}$ supply start threshold, this feature holds the output low, regardless of the status of the inputs. The upper end of this range is driven by the 20-V absolute maximum voltage rating of the V_{DD} pin of the device (which is a stress rating). Keeping a 3-V margin to allow for transient voltage spikes, the maximum recommended voltage for the V_{DD} pin is 17 V. The UVLO protection feature also involves a hysteresis function, which means that when the V_{DD} pin bias voltage has exceeded the threshold voltage and device begins to operate, and if the voltage drops, then the device continues to deliver normal functionality unless the voltage drop exceeds the hysteresis specification $V_{DD(hys)}$. Therefore, ensuring that, while operating at or near the 8-V range, the voltage ripple on the auxiliary power supply output is smaller than the hysteresis specification of the device is important to avoid triggering device shutdown. During system shutdown, the device operation continues until the V_{DD} pin voltage has dropped below the $V_{(OFF)}$ threshold, which must be accounted for while evaluating system shutdown timing design requirements. Likewise, at system start-up the device does not begin operation until the V_{DD} pin voltage has exceeded the $V_{(ON)}$ threshold.

The quiescent current consumed by the internal circuit blocks of the device is supplied through the V_{DD} pin. Although this fact is well known, it is important to recognize that the charge for source current pulses delivered by the HO pin is also supplied through the same V_{DD} pin. As a result, every time a current is sourced out of the HO pin, a corresponding current pulse is delivered into the device through the V_{DD} pin. Thus, ensure that a local bypass capacitor is provided between the V_{DD} and GND pins and located as close to the device as possible for the purpose of decoupling is important. A lo-ESR, ceramic surface-mount capacitor is required. TI recommends using a capacitor in the range 0.22 µF to 4.7 µF between V_{DD} and GND. In a similar manner, the current pulses delivered by the LO pin are sourced from the HB pin. Therefore a 0.022-µF to 0.1-µF local decoupling capacitor is recommended between the HB and HS pins.

11 Layout

11.1 Layout Guidelines

To improve the switching characteristics and efficiency of a design, the following layout rules must be followed.

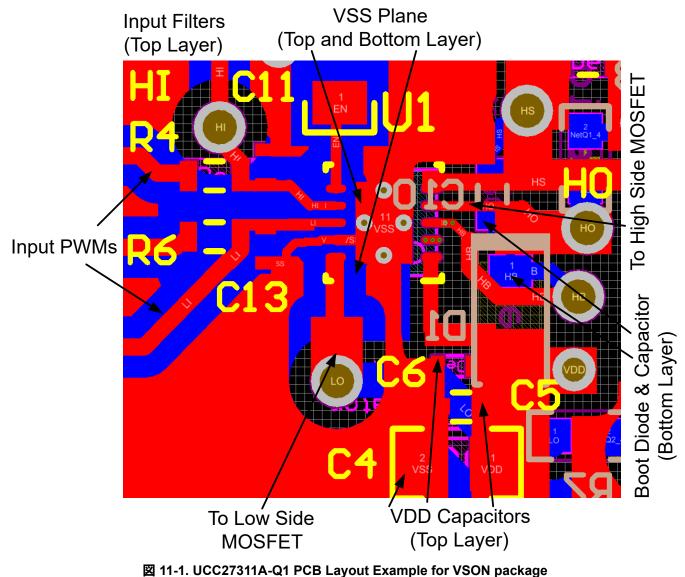
- Locate the driver as close as possible to the MOSFETs.
- Locate the $V_{DD} V_{SS}$ and V_{HB} - V_{HS} (bootstrap) capacitors as close as possible to the device.
- Pay close attention to the GND trace. Use the thermal pad of the DRM package as GND by connecting it to the VSS pin (GND). The GND trace from the driver goes directly to the source of the MOSFET, but must not be in the high current path of the MOSFET drain or source current.
- Use similar rules for the HS node as for GND for the high-side driver.
- For systems using multiple UCC27311A-Q1 devices, TI recommends that dedicated decoupling capacitors be located at V_{DD}-V_{SS} for each device.
- Care must be taken to avoid placing VDD traces close to LO, HS, and HO signals.
- Use wide traces for LO and HO closely following the associated GND or HS traces. A width of 60 to 100 mils is preferable where possible.
- Use as least two or more vias if the driver outputs or SW node must be routed from one layer to another. For GND, the number of vias must be a consideration of the thermal pad requirements as well as parasitic inductance.
- Avoid LI and HI (driver input) going close to the HS node or any other high dV/dT traces that can induce significant noise into the relatively high impedance leads.

A poor layout can cause a significant drop in efficiency or system malfunction, and it can even lead to decreased reliability of the whole system.

11.2 Layout Example

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11.3 Thermal Considerations

The useful range of a driver is greatly affected by the drive-power requirements of the load and the thermal characteristics of the package. For a gate driver to be useful over a particular temperature range, the package must allow for efficient removal of the heat produced while keeping the junction temperature within rated limits. The thermal metrics for the driver package are listed in Thermal Information section. For detailed information regarding the table, refer to the Application Note from Texas Instruments entitled *Semiconductor and IC Package Thermal Metrics* (SPRA953). The UCC27311A-Q1 device is offered in a 10-pin VSON package (DRC).



12 Device and Documentation Support

12.1 Device Support

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12.2 Documentation Support

12.2.1 Related Documentation

PowerPAD™ Thermally Enhanced Package, Application Report (SLMA002)

PowerPAD™ Made Easy, Application Report (SLMA004)

12.3 ドキュメントの更新通知を受け取る方法

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13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

13.1 Package Option Addendum



Packaging Information

Orderable Device	Status ⁽¹⁾	Package Type	Package Drawing	Pins	Package Qty	Eco Plan ⁽²⁾	Lead/Ball Finish ⁽⁶⁾	MSL Peak Temp ⁽³⁾	Op Temp (°C)	Device Marking ^{(4) (5)}
PUCC27311AQ DRCRQ1	PREVIEW	VSON	DRC	10	3000	RoHS & Green	NIPDAU		-40 to 125	

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PRE_PROD Unannounced device, not in production, not available for mass market, nor on the web, samples not available.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material).

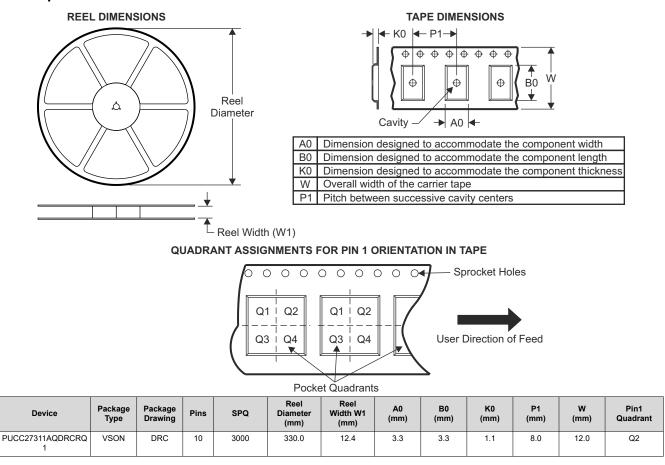
- (3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead/Ball Finish Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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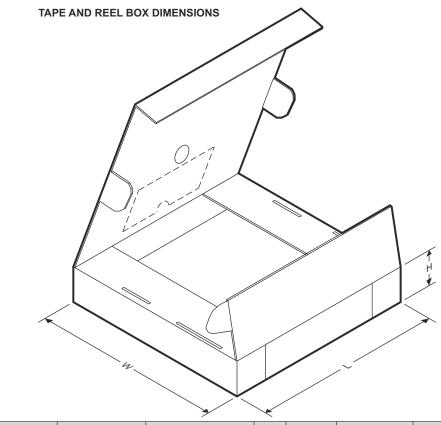
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13.2 Tape and Reel Information





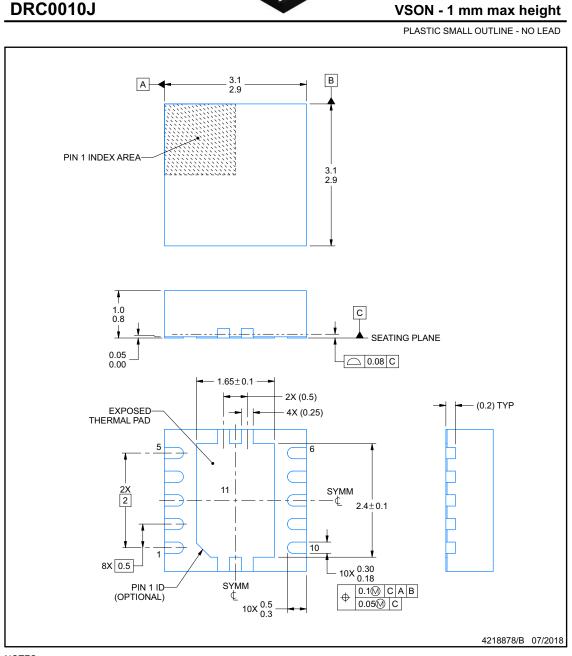


Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
PUCC27311AQDRCRQ1	VSON	DRC	10	3000	367.0	367.0	35



PACKAGE OUTLINE

13.3 Mechanical Data



NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M. 2. This drawing is subject to change without notice.

3. The package thermal pad must be soldered to the printed circuit board for optimal thermal and mechanical performance.



ADVANCE INFORMATION

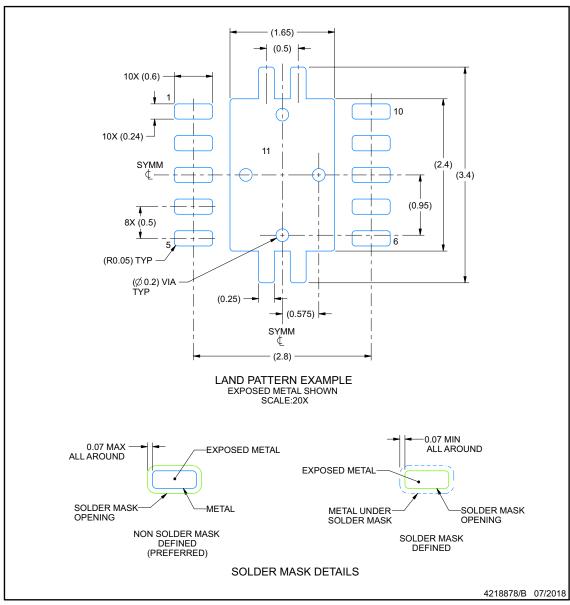
DRC0010J



EXAMPLE BOARD LAYOUT

VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



NOTES: (continued)

 This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).

5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.



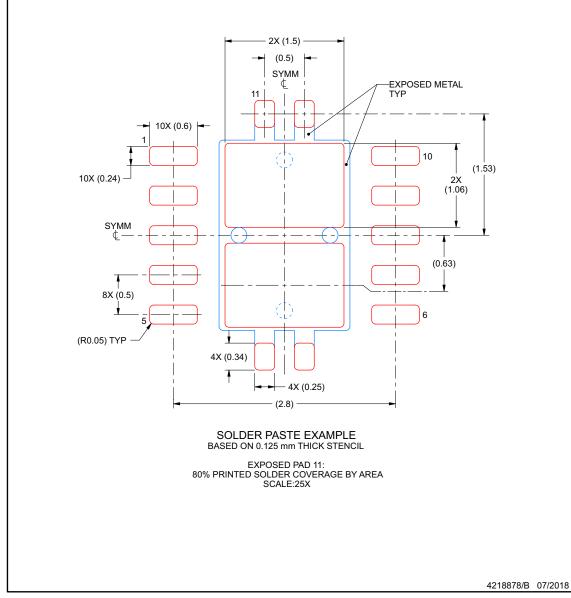


EXAMPLE STENCIL DESIGN

DRC0010J

VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



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