OPT8241 Evaluation Module

User's Guide



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OPT8241 Evaluation Module

This document explains the details of the hardware and its usage and provides a basic introduction to the accompanying software. Throughout this document, camera development kit, evaluation module, and the abbreviations CDK and EVM are used interchangeably and are synonymous with the term OPT8241-CDK-EVM.

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Introduction www.ti.com

2 Introduction

The OPT8241-CDK-EVM showcases TI's high-performance 3D Time-of-Flight (ToF) sensor OPT8241 and the ToF controller OPT9221 (TFC). The EVM is designed to be reconfigurable and modular in order to enable evaluation at a wide range of operating points and is not optimized for any specific application, by default. The accompanying software is designed to enable evaluation of the TI 3D ToF technology at various levels of detail.

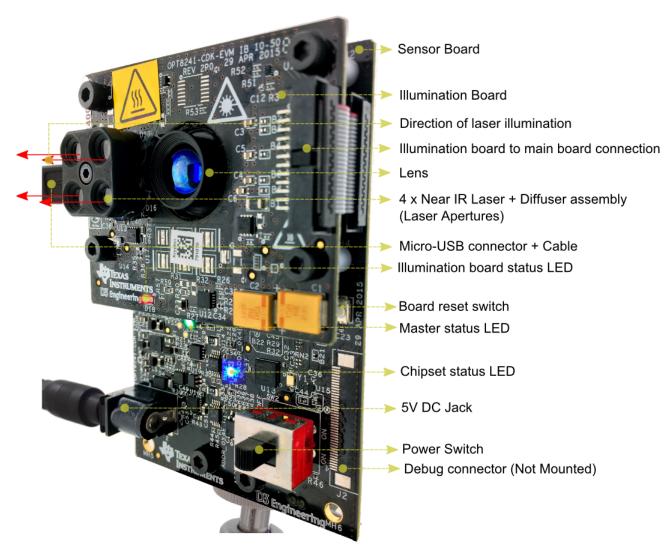


Figure 1. Components of the EVM



www.ti.com Safety

3 Safety

This Laser Device is designed at Class 1 during normal operation. While the OPT8241-CDK-EVM development boards meet the Class 1 classification requirements under EN/IEC60825-1 2007, users are advised to take the necessary safety caution when using the OPT8241-CDK-EVM. First, examine the board for any damage before the board is powered. Check that the diffusers and diffuser mounts are properly secured on the laser diodes. If there is any damage, stop operating by removing power from the CDK immediately. Opening the laser diffuser assembly may lead to hazardous radiation exposure. Any kind of circuit modification to the board or use of software or firmware other than the recommended EVM tools and firmware provided by TI may lead to violation of class 1 safety limits. Due to the small size and unsuitability for labeling, laser safety related labels are included herein, rather than on the product. Additional safety and manufacturer labels are included in the safety section of the OPT8241-EVM Quick Start Guide.

WARNING

Use of controls or adjustments or performance of procedures other than those specified herein may result in hazardous radiation exposure.

This is a class A product as defined by standard EN 61326-1:2013. This product is not intended to be used in domestic establishments and also in establishments that are directly connected to a low-voltage power-supply network that supplies buildings used for domestic purposes. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.

There is no scheduled maintenance required for the OPT8241-CDK-EVM; any servicing and maintenance of this EVM shall be performed only by trained Texas Instruments or TI-appointed trained personnel. Any modification or significant damage to the CDK could potentially cause the CDK to operate outside of the EN/IEC60825 2007 Class 1 classification limits.

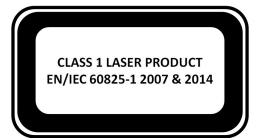


Figure 2. Explanatory Label

Complies with US FDA performance standards for laser products except for deviations pursuant to Laser Notice No. 50, dated June 24, 2007

Figure 3. Certification Label

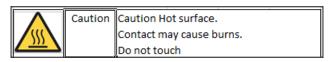


Figure 4. Hot To Touch



Hardware www.ti.com

4 Hardware

4.1 Block Diagram

The OPT8241 sensor provides the modulation for the internal pixel array as well as for the external illumination drivers. The illumination drivers in-turn drive the laser illumination on the illumination board. The receiver light is focused using a lens on to the OPT8241 sensor. The depth correlation data obtained by the OPT8241 sensor is digitized and provided to the OPT9221 ToF Controller (TFC), the TFC then processes and provides the distance output for each pixel. A Cypress FX2 chip is used as a USB transceiver to enable PC-based acquisition of data and to control the configuration of the CDK dynamically.

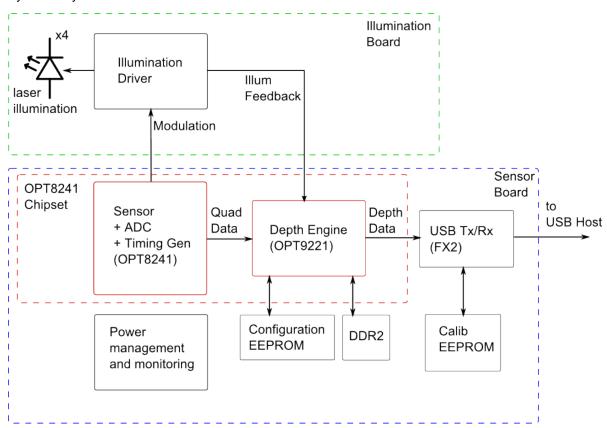


Figure 5. CDK Diagram

4.2 Design Specifications

The hardware consists of an assembly of customizable boards. The hardware comes assembled by default and it is not recommended to disassemble the hardware. The individual boards are listed below with their main constituents:

- · Sensor board
 - Sensor, lens holder, lens
 - TFC, DDR2 memory
 - USB transceiver
- Illumination board
 - Lasers, diffuser, diffuser holder
 - Laser driver

The overall specifications of the CDK hardware are listed in Table 1.



www.ti.com Hardware

Table 1. Specifications

| Item | Specification | |
|--------------------------------|--|--|
| Time of Flight Sensor | OPT8241 | |
| Time of Flight Controller | OPT9221 | |
| Sensor resolution | 320 x 240 (QVGA) | |
| Field of view | 74.4 (H) x 59.3 (V) | |
| Frame-rate | 12 60 fps | |
| Illumination source wavelength | 850 nm | |
| Operating range | Up to 4 m | |
| Connectivity | USB 2.0, micro connector | |
| Cable | 1.8 m, Micro USB B-type and standard Male A type | |
| Operating Conditions | 0°C to 40°C (Ambient) | |
| CDK Power supply max power | 15 Watt | |
| Size | 88.8 mm (L) x 60 mm (W) x 24.3 mm (H) | |

4.3 Sensor Board

The sensor board consists of all interconnects and the corresponding connectors. The illumination board is mechanically held to the sensor board using spacers. The electrical connections between illumination board and sensor board are achieved using a flex cable. The sensor board also provides an extension connector for connecting the boards to an external connector.



Figure 6. Sensor Board

The specifications for the sensor board are listed in Table 2.

Table 2. Sensor Board Specifications

| Item | Specification(*) | |
|----------------------|---------------------------------------|--|
| Size | 88.8 mm (L) x 60 mm (W) x 18.9 mm (H) | |
| Modulation frequency | up to 100 MHz | |



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4.3.1 Indicator LEDs

The sensor board has 2 LEDs for indicating various operating states of the board. The master LED indicates the overall status of the board and the TFC LED indicates the status of the Time-of-Flight chipset. The various states of the board are listed in Table 3.

| State | Master LED | TFC LED | Status Type |
|-------------------------------|--------------------|---------|-------------|
| All OK, Streaming OFF | Bright Green | Blue | Info |
| All OK, Streaming On | Cyan | Х | Info |
| TFC Test Mode Enabled | X | Off | Info |
| Firmware Upgrade in progress | Blink (Magenta) | Х | Info |
| Firmware Upgrade done | Magenta | X | Info |
| DC Jack unplugged | Dimmed colors | X | Info |
| Overtemperature | X | Magenta | Warning |
| TFC booted, but status failed | X | Red | Error |

Blink (Red)

Off

Error

Table 3. LED Indicator States

In usual operating conditions, the master LED should be green/cyan and the TFC LED should be blue.

TFC did not boot

4.3.2 Power Switch

The power switch controls the power to both the sensor and the illumination board. The switch controls are shown in Figure 7.

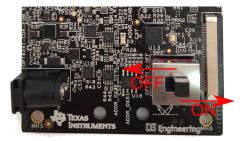


Figure 7. Power Switch

4.3.3 Reset Switch

The reset switch resets the entire board without the need to power-cycle the board. As part of the reset process, the reset triggers a USB connect and disconnect on the USB and output data streaming will stop. This may cause the evaluation software on the PC to misbehave if the software is in connected state. Disconnect and connect operations on the software should restore the CDK operation with reset parameters. Figure 8 shows the location of the reset switch.



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Figure 8. Reset Switch

4.3.4 Lens Assembly

The lens and the lens mount are both custom parts. To allow the use of standard off-the-shelf lenses, a standard M12 lens mount footprint has been provided.

4.3.5 Tripod Mount

A tripod mount comes assembled with the hardware. The tripod mount can be unscrewed from the assembly, if necessary. Figure 9 shows the tripod mount location and the screws that hold the tripod mount to the rest of the assembly.



Figure 9. Tripod Mount



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4.4 Illumination Board

The illumination board consists of 4 IR lasers mounted with diffusers and the laser driver ckt. The optical output power of the illumination board is controlled using an I²C interface-based digital potentiometer. The voxel viewer software can be used to configure the digital potentiometer. The modulation control of the illumination is done by the OPT8241 sensor and the corresponding signals from the sensor board to the Illumination board via a flex cable.

Table 4 lists the specifications of the illumination boards.

Table 4. Illumination Board Specifications

| Item | Specification ⁽¹⁾ |
|---------------------------|--|
| Size | 60 mm (W) x 48.5 mm (L) x 12.1 mm (H) |
| Illumination type | 4 x Near IR Laser |
| Average Output Power(^) | 1.5 W |
| Peak optical output power | 10 W |
| Modulation frequency | 12-MHz to 80-MHz square wave at 50% duty cycle |
| Pulse train width | 18 μs–28 ms |
| Wavelength | 850 nm |
| Laser Beam Divergence | 80° at 90% power relative to the center |
| Laser Beam Shape | Circular |
| Transverse Beam Mode | Diffused |
| Diffuser Material | EDC-80, RPC photonics |

⁽¹⁾ All values are typical.

The illumination power can be changed only between 40% to 100% of the total power. Values below 40% of the maximum power are not supported. Since each board's maximum power is individually tuned to make sure that the 100% power setting meets the laser safety requirements, the valid steps between 40% to 100% power can differ across CDKs.

4.5 Power Supply

The image of the power supply recommended for use with the CDK along with all the blade options is shown in Figure 10.



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Figure 10. Power Supply

The power supply specifications are shown in Table 5.

Table 5. Power Supply Specifications

| Item | Specification ⁽¹⁾ | |
|----------------|----------------------------------|--|
| Part Number | EMSA050300-P5RP-SZ | |
| Output Voltage | 5 V | |
| Output Current | Up to 3 A | |
| Input Voltage | 90 ≈ 264 VAC | |
| Frequency | 47 to 63 Hz | |
| Efficiency | Level V | |
| Blade options | US, UK, Europe, Australia, China | |

All values are typical.

NOTE: TI recommends using an external power supply that complies with applicable regional safety standards such as (by example) UL, CSA, VDE, CCC, PSE, and so forth.



Calibration www.ti.com

5 Calibration

The CDK is factory-calibrated. The calibration on the CDK is for demonstration purposes only and is not meant to be treated as the most accurate calibration possible. Since the CDK can be configured dynamically using the software, the CDK goes out of calibration whenever a critical parameter is changed. Three default profiles are provided in the hardware to serve as templates. Table 6 lists the default calibration profiles.

Table 6. Calibration Profiles

| Parameter | Long Range | Short Range | High Ambient |
|-----------------------------|--|------------------------------------|------------------------------------|
| Parent Profile | Lens Only | Long Range | Long Range |
| Frame rate (fps) | 30 | 60 | 30 |
| Sub-Frames | 4 | 2 | 4 |
| Quads | 6 | 6 | 6 |
| Integration Duty Cycle (%) | 30 | 10 | 5 |
| De-aliasing | Enabled | Enabled | Enabled |
| Illumination Power (%) | 100 | 40 | 100 |
| Unambiguous Range (m) | 10 | 5 | 5 |
| Base Frequency (MHz) | 60 | 60 | 60 |
| De-aliasing Frequency (MHz) | 40 | 40 | 40 |
| Usable Range | 4 m | 1.5 m | 1.5 m |
| Calibrations performed | Temperature, Common phase offset, Pixel to Pixel, Pixel cross-talk (1) | Common phase offset ⁽²⁾ | Common phase offset ⁽²⁾ |

⁽¹⁾ Since Long range profile derives from lens calibration profile, lens calibration is not redone in long range profile.

Calibration is very sensitive to system parameter changes. Any change in a parameter value could put the CDK in a non-calibrated state. The most common parameter changes that mandate re-calibration are listed in Table 7.

Table 7. Calibration Sensitivity Table

| | Re-Calibration Required? | | | |
|---|----------------------------|-------------------------------|---|--|
| Parameter Changed | Common phase offset | Pixel-to-Pixel Differences | Non-Linearity Calibration, Pixel Cross-Talk Calibration | |
| Unambiguous range (any change in modulation frequency) | Yes | Yes | Yes | |
| Frame rate, number of quads, number of sub-frames (any change in quad timing) | Yes, but to a small extent | No | No | |
| Integration duty cycle | Yes, but to a small extent | No | No | |
| Illumination power | Yes | No | No | |

⁽²⁾ Profiles that have a parent derive all the calibrations from the parent. Calibrations in a child override the calibrations derived from the parent.



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6 Software

The CDK is supported by the open source 3D Camera software development kit – Voxel-SDK. To make the evaluation easier, Voxel Viewer, a closed source viewer built on top of Voxel SDK is provided by TI. The viewer supports the following functionality:

- · View the following streamed data real-time:
 - Phase
 - Amplitude
 - Ambient
 - Distance
 - Depth
 - Point cloud
- · Configure the camera settings
- Basic statistics:
 - Temporal and spatial averaging
 - Temporal and spatial standard deviation
 - Histogram
- Filters (Spatial and temporal):
 - Filter addition/deletion/insertion
 - Configuration of filter coefficients
- Calibrate the camera
- OPT9221 firmware update

The details of the viewer are covered in the Voxel Viewer User's Guide.

6.1 Firmware upgrade

The CDK has two firmware. The FX2 firmware and the TFC (OPT9221) firmware. Both the firmware are stored in separate EEPROMs. Firmware upgrade is a critical activity and the following precautions must be adhered to:

- The CDK should be adequately powered using the recommended power adapter.
- Only the recommended software should be used for firmware upgrade.
- Loading firmware other than the firmware provided by TI is not recommended and could lead to hardware failure.

6.1.1 FX2 Firmware upgrade

FX2 firmware upgrade is accomplished using the Cypress Control Center tool. The procedure follows:

- Launch the cypress control center tool. If the CDK is connected, the CDK is listed in the control center tool.
- Choose "TI 3DTOF CDK OPT8241" among the devices listed.
- Click on the menu option Program \rightarrow FX2 \rightarrow 64KB EEPROM.
- Choose the provided firmware file and click on open to start the programming.
- If the programming goes through, the status bar shows "Programming Succeeded".



Software www.ti.com

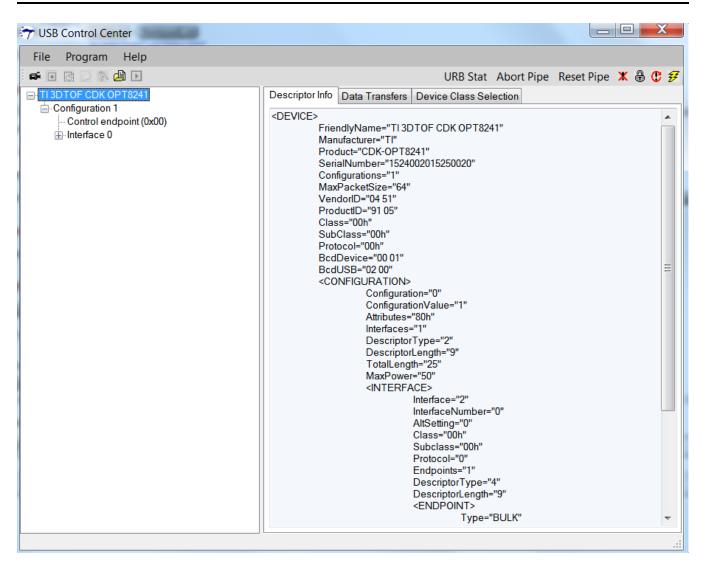


Figure 11. Cypress Control Center



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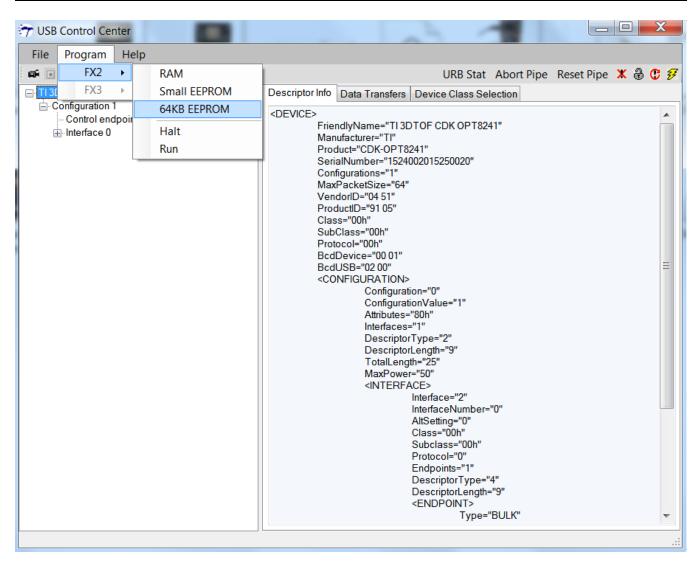


Figure 12. Program Menu

6.1.2 TFC (OPT9221) Firmware Upgrade

The OPT9221 firmware can be updated using the Voxel-Viewer tool. The procedure follows:

- If the Voxel Viewer application is already running and connected to the CDK, launch the "Voxel Programmer" utility from the menu – File → Open Programmer
- If the Voxel Viewer application is not running, the "Voxel Programmer" utility can be directly launched from the start menu in Microsoft® Windows® or from a terminal in Linux®.
- Once the programmer is open and is connected to the CDK, choose the provided OPT9221 firmware file and click on the download button.



Software www.ti.com

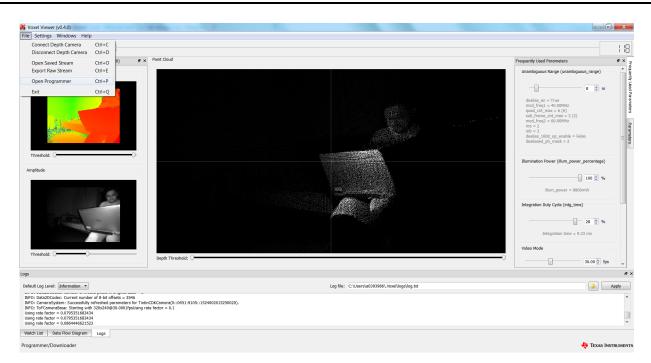


Figure 13. Launching the Programmer From the Voxel Viewer

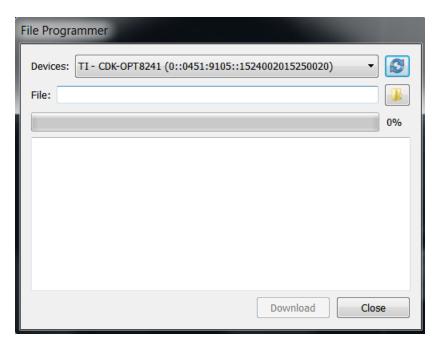


Figure 14. OPT9221 Firmware Download



www.ti.com Known Issues

7 **Known Issues**

List of known issues for the hardware revision Rev2P0:

- Hardware issues:
 - When the USB cable is connected, the red LED on the illumination board turns on even when the power switch is in the off position. This is behavior is not harmful and the rest of the circuit is indeed powered off. Occasional blinking may also be observed.
 - The lens mount has no alignment tabs. This results into incorrect centering and hence noticeable vignetting near the corners of the image.
 - Hot unplug of power supply DC jack may lead to power failure and board reset.
 - The OPT8241 LVDS data capture on the TFC has latency issues and will be fixed in a future OPT9221 firmware. As of firmware version 0.23, the latency issue is not resolved. The issue manifests itself as a 1-in-8 column pattern both in phase and amplitude images and disappears when "data latency" parameter is adjusted by ±1.
- Calibration issues:
 - Frequency calibration is not performed on the boards. This may lead to gain errors in distance measurement.
 - Non-linearity calibration is not performed on the boards. This may lead to varying phase slopes versus distance.

8 **Related Documentation From Texas Instruments**

Related documentation regarding the EVM is available here: http://www.ti.com/tool/opt8241-cdk-evm. The documentation related to the ToF chipset used in the EVM is available in the following:

- Sensor http://www.ti.com/product/OPT8241
- Time-of-Flight Controller http://www.ti.com/product/OPT9221

Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from A Revision (February 2016) to B Revision

Page

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