Errata

MSP430F1111A Microcontroller



ABSTRACT

This document describes the known exceptions to the functional specifications (advisories).

Table of Contents

1 Functional Advisories	2
2 Preprogrammed Software Advisories	2
3 Debug Only Advisories	
4 Fixed by Compiler Advisories	
5 Nomenclature, Package Symbolization, and Revision Identification	
5.1 Device Nomenclature	
5.2 Package Markings	3
5.3 Memory-Mapped Hardware Revision (TLV Structure)	
6 Advisory Descriptions	
7 Revision History	

1 Functional Advisories

Advisories that affect the device's operation, function, or parametrics.

√ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev J	Rev I	Rev H
BCL5	✓	✓	✓
PORT3	✓	✓	✓
RES4	✓	✓	✓
TA12	✓	✓	✓
TA16	✓	✓	✓
TA21	✓	✓	✓
TAB22	✓	✓	✓
WDG2	✓	✓	✓

2 Preprogrammed Software Advisories

Advisories that affect factory-programmed software.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev J	Rev I	Rev H
BSL5	✓	✓	✓

3 Debug Only Advisories

Advisories that affect only debug operation.

✓ The check mark indicates that the issue is present in the specified revision.

The device does not have any errata for this category.

4 Fixed by Compiler Advisories

Advisories that are resolved by compiler workaround. Refer to each advisory for the IDE and compiler versions with a workaround.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev J	Rev I	Rev H
CPU4	1	✓	✓

Refer to the following MSP430 compiler documentation for more details about the CPU bugs workarounds.

TI MSP430 Compiler Tools (Code Composer Studio IDE)

- MSP430 Optimizing C/C++ Compiler: Check the --silicon_errata option
- MSP430 Assembly Language Tools

MSP430 GNU Compiler (MSP430-GCC)

- MSP430 GCC Options: Check -msilicon-errata= and -msilicon-errata-warn= options
- MSP430 GCC User's Guide

IAR Embedded Workbench

IAR workarounds for msp430 hardware issues



5 Nomenclature, Package Symbolization, and Revision Identification

The revision of the device can be identified by the revision letter on the Package Markings or by the HW_ID located inside the TLV structure of the device.

5.1 Device Nomenclature

To designate the stages in the product development cycle, TI assigns prefixes to the part numbers of all MSP MCU devices. Each MSP MCU commercial family member has one of two prefixes: MSP or XMS. These prefixes represent evolutionary stages of product development from engineering prototypes (XMS) through fully qualified production devices (MSP).

XMS – Experimental device that is not necessarily representative of the final device's electrical specifications

MSP - Fully qualified production device

Support tool naming prefixes:

X: Development-support product that has not yet completed Texas Instruments internal qualification testing.

null: Fully-qualified development-support product.

XMS devices and X development-support tools are shipped against the following disclaimer:

"Developmental product is intended for internal evaluation purposes."

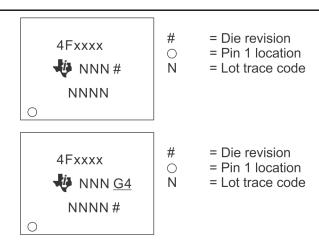
MSP devices have been characterized fully, and the quality and reliability of the device have been demonstrated fully. Tl's standard warranty applies.

Predictions show that prototype devices (XMS) have a greater failure rate than the standard production devices. TI recommends that these devices not be used in any production system because their expected end-use failure rate still is undefined. Only qualified production devices are to be used.

TI device nomenclature also includes a suffix with the device family name. This suffix indicates the temperature range, package type, and distribution format.

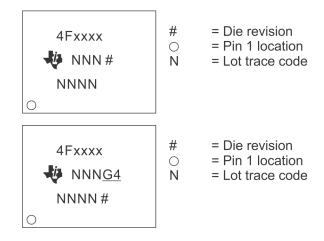
5.2 Package Markings

DGV20 TVSOP (DGV), 20 Pin



PW20 TSSOP (PW), 20 Pin

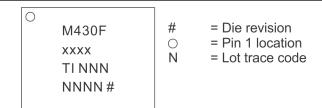




DW20 SOP (DW), 20 Pin



RGE24 QFN (RGE), 24 Pin



5.3 Memory-Mapped Hardware Revision (TLV Structure)

This device does not support reading the hardware revision from memory.

Further guidance on how to locate the TLV structure and read out the HW_ID can be found in the device User's Guide.



6 Advisory Descriptions

BCL5 BCL Module

Category Functional

Function RSELx bit modifications can generate high frequency spikes on MCLK

Description When DIVMx = 00 or 01 the RSELx bits of the Basic Clock Module are incremented or

decremented in steps of 2 or greater, the DCO output may momentarily generate high frequency spikes on MCLK, which may corrupt CPU operation. This is not an issue when

DIVMx = 10 or 11.

Workaround Set DIVMx = 10 or 11 to divide the MCLK input prior to modifying RSELx. After the RSELx

bits are configured as desired, the DIVMx setting can be changed back to the original

selection.

BSL5 BSL Module

Category Software in ROM

Function BSL might not start if RST/NMI pin is configured as NMI input

Description If the RST/NMI pin is configured to NMI, the bootstrap loader may not be started.

Unpredictable operations will result.

Workaround None

CPU4 CPU Module

Category Compiler-Fixed

Function PUSH #4, PUSH #8

Description The single operand instruction PUSH cannot use the internal constants (CG) 4 and 8. The

other internal constants (0, 1, 2, -1) can be used. The number of clock cycles is different:

PUSH #CG uses address mode 00, requiring 3 cycles, 1 word instruction PUSH #4/#8 uses address mode 11, requiring 5 cycles, 2 word instruction

Workaround Refer to the table below for compiler-specific fix implementation information.

IDE/Compiler	Version Number	Notes
IAR Embedded Workbench	IAR EW430 v2.x until v6.20	User is required to add the compiler flag option below hw_workaround=CPU4
IAR Embedded Workbench	IAR EW430 v6.20 or later	Workaround is automatically enabled
TI MSP430 Compiler Tools (Code Composer Studio)	v1.1 or later	
MSP430 GNU Compiler (MSP430-GCC)	MSP430-GCC 4.9 build 167 or later	



PORT3 PORT Module

Category Functional

Function Port interrupts can get lost

Description Port interrupts can get lost if they occur during CPU

access of the P1IFG and P2IFG registers.

Workaround None

RES4 RES Module

Category Functional

Function No reset if external resistor exceeds certain value

DescriptionNo reset of the device is performed if the external pull down resistor on RST/NMI pin is

above a certain limit. The limits are:

Vcc = 1.8V: maximum pull down resistor = 12 kohm Vcc = 3.0V: maximum pull down resistor = 5 kohm Vcc = 3.6V: maximum pull down resistor = 2.5 kohm

In addition, a higher current consumption occurs during high/low RST/NMI signal

transition when using improper resistors.

Workaround Use external pulldown resistors below the listed values or directly drive RST/NMI low to

generate a reset.

TA12 TA Module

Category Functional

Function Interrupt is lost (slow ACLK)

Description Timer A counter is running with slow clock (external TACLK or ACLK) compared to MCLK.

The compare mode is selected for the capture/compare channel and the CCRx register is incremented by one with the occurring compare interrupt (if TAR = CCRx). Due to the fast MCLK the CCRx register increment (CCRx = CCRx+1) happens before the Timer_A counter has incremented again. Therefore the next compare interrupt should happen at once with the next Timer_A counter increment (if TAR = CCRx + 1). This interrupt gets

lost.

Workaround Switch capture/compare mode to capture mode before the CCRx register increment.

Switch back to compare mode afterwards.

TA16 TA Module

Category Functional

Function First increment of TAR erroneous when IDx > 00

Description The first increment of TAR after any timer clear event (POR/TACLR) happens immediately

following the first positive edge of the selected clock source (INCLK, SMCLK, ACLK or TACLK). This is independent of the clock input divider settings (ID0, ID1). All following

TAR increments are performed correctly with the selected IDx settings.

Workaround None

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TA21 TA Module

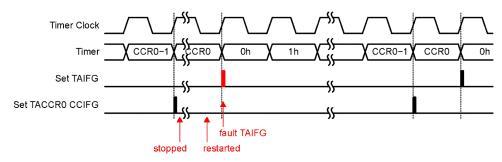
Category Functional

Function TAIFG Flag is erroneously set after Timer A restarts in Up Mode

Description In Up Mode, the TAIFG flag should only be set when the timer counts from TACCR0 to

zero. However, if the Timer A is stopped at TAR = TACCR0, then cleared (TAR=0) by setting the TACLR bit, and finally restarted in Up Mode, the next rising edge of the TACLK

will erroneously set the TAIFG flag.



Workaround None.

TAB22 TAB Module

Category Functional

Function Timer_A/Timer_B register modification after Watchdog Timer PUC

Description Unwanted modification of the Timer_A/Timer_B registers TACTL/TBCTL and TAIV/TBIV

can occur when a PUC is generated by the Watchdog Timer(WDT) in Watchdog mode and any Timer_A/Timer_B counter register TACCRx/TBCCRx is incremented/

decremented (Timer_A/Timer_B does not need to be running).

Workaround Initialize TACTL/TBCTL register after the reset occurs using a MOV instruction (BIS/BIC

may not fully initialize the register). TAIV/TBIV is automatically cleared following this

initialization.

Example code:

MOV.W #VAL, &TACTL

or

MOV.W #VAL, &TBCTL

Where, VAL=0, if Timer is not used in application otherwise, user defined per desired

function.

WDG2 WDG Module

Category Functional

Function Incorrectly accessing a flash control register

Description If a key violation is caused by incorrectly accessing a flash control register, the watchdog

interrupt flag is set in addition to the expected PUC.

Workaround None



Revision History www.ti.com

7 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from May 29, 2018 to May 11, 2021

Page

Changed the document format and structure; updated the numbering format for tables, figures, and cross references throughout the document......5

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