MSP430F5223 Device Erratasheet

The revision of the device can be identified by the revision letter on the Package Markings or by the HW_ID located inside the TLV structure of the device

1 Functional Errata Revision History

Errata impacting device's operation, function or parametrics.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev B
ADC39	✓
ADC42	✓
ADC69	✓
COMP10	✓
CPU47	✓
DMA4	✓
DMA7	✓
DMA10	✓
PMAP1	✓
PMM9	✓
PMM11	✓
PMM12	✓
PMM14	✓
PMM15	✓
PMM18	✓
PMM20	✓
PORT15	✓
PORT19	✓
PORT33	✓
RTC3	✓
RTC6	✓
SYS12	✓
SYS16	✓
UCS7	✓
UCS9	✓
UCS11	✓
USCI26	✓
USCI35	✓
USCI39	✓
USCI40	✓

2 Preprogrammed Software Errata Revision History

Errata impacting pre-programmed software into the silicon by Texas Instruments.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev B
BSL7	✓
BSL11	✓

3 Debug only Errata Revision History

Errata only impacting debug operation.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev B
EEM17	✓
EEM19	✓
EEM21	✓
EEM23	✓
JTAG26	✓
JTAG27	✓

4 Fixed by Compiler Errata Revision History

Errata completely resolved by compiler workaround. Refer to specific erratum for IDE and compiler versions with workaround.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev B
CPU21	✓
CPU22	✓
CPU40	✓

Refer to the following MSP430 compiler documentation for more details about the CPU bugs workarounds.

TI MSP430 Compiler Tools (Code Composer Studio IDE)
- MSP430 Optimizing C/C++ Compiler: Check the --silicon_errata option
- MSP430 Assembly Language Tools

MSP430 GNU Compiler (MSP430-GCC)
- MSP430 GCC Options: Check -msilicon-errata= and -msilicon-errata-warn= options
- MSP430 GCC User's Guide

IAR Embedded Workbench
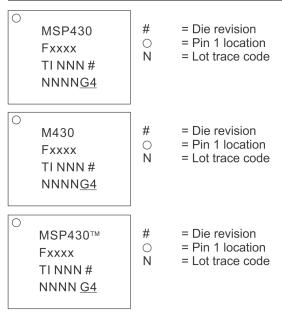- IAR workarounds for msp430 hardware issues

5   Package Markings

RGZ48   *QFN (RGZ), 48 Pin*

○ MSP430 Fxxxx TI NNN # NNNN<u>G4</u>	# = Die revision ○ = Pin 1 location N = Lot trace code
○ M430 Fxxxx TI NNN # NNNN<u>G4</u>	# = Die revision ○ = Pin 1 location N = Lot trace code
○ MSP430™ Fxxxx TI NNN # NNNN <u>G4</u>	# = Die revision ○ = Pin 1 location N = Lot trace code

NOTE: Package marking with "TM" applies only to devices released after 2011.

6   Memory-Mapped Hardware Revision (TLV Structure)

Die Revision	TLV Hardware Revision
Rev B	11h

Further guidance on how to locate the TLV structure and read out the HW_ID can be found in the device User's Guide.

7 Detailed Bug Description

ADC39	*ADC10_A Module*

Category	Functional
Function	Erroneous ADC10 results in extended sample mode
Description	If the extended sample mode is selected (ADC10SHP = 0) and the ADC10CLK is asynchronous to the SHI signal, the ADC10 may generate erroneous results.
Workaround	1) Use the pulse sample mode (ADC10SHP=1)
	OR
	2) Use a synchronous clock for ADC10 and the SHI signal.

ADC42	*ADC10_A Module*

Category	Functional
Function	ADC stops converting when successive ADC is triggered before the previous conversion ends
Description	Subsequent ADC conversions are halted if a new ADC conversion is triggered while ADC is busy. ADC conversions are triggered manually or by a timer. The affected ADC modes are:
	- sequence-of-channels
	- repeat-single-channel
	- repeat-sequence-of-channels (ADC12CTL1.ADC12CONSEQx)
	In addition, the timer overflow flag cannot be used to detect an overflow (ADC12IFGR2.ADC12TOVIFG).
Workaround	1. For manual trigger mode (ADC12CTL0.ADC12SC), ensure each ADC conversion is completed by first checking ADC12CTL1.ADC12BUSY bit before starting a new conversion.
	2. For timer trigger mode (ADC12CTL1.ADC12SHP), ensure the timer period is greater than the ADC sample and conversion time.
	To recover the conversion halt:
	1. Disable ADC module (ADC12CTL0.ADC12ENC = 0 and ADC12CTL0.ADC12ON = 0)
	2. Re-enable ADC module (ADC12CTL0.ADC12ON = 1 and ADC12CTL0.ADC12ENC = 1)
	3. Re-enable conversion

ADC69	*ADC10_A Module*

Category	Functional
Function	ADC stops operating if ADC clock source is changed from SMCLK to another source while SMCLKOFF = 1.
Description	When SMCLK is used as the clock source for the ADC (ADC12CTL1.ADC12SSELx = 11) and CSCTL4.SMCLKOFF = 1, the ADC will stop operating if the ADC clock source is changed by user software (e.g. in the ISR) from SMCLK to a different clock source. This

issue appears only for the ADC12CTL1.ADC12DIVx settings /3/5/7. The hang state can be recovered by PUC/POR/BOR/Power cycle.

Workaround   1. Set CSCTL4.SMCLKOFF = 0 before switch ADC clock source.

OR

2. Only use ADC12CTL1.ADC12DIVx as /1, /2, /4, /6, /8

BSL7   *BSL Module*

Category   Software in ROM

Function   BSL does not start after waking up from LPMx.5

Description   When waking up from LPMx.5 mode, the BSL does not start as it does not clear the Lock I/O bit (LOCKLPM5 bit in PM5CTL0 register) on start-up.

Workaround   1. Upgrade the device BSL to the latest version (see Creating a Custom Flash-Based Bootstrap Loader (BSL) Application Note - SLAA450 for more details)

OR

2. Do not use LOCKLPM5 bit (LPMx.5) if the BSL is used but cannot be upgraded.

BSL11   *BSL Module*

Category   Software in ROM

Function   P1.0 is set to output high after BSL starts.

Description   When the BSL is invoked, P1.0 is set to output driven high.

Workaround   Do not ground P1.0 if the BSL is used.

> **NOTE:** A high P1.0 during BSL invoke should not pose any risk to the circuit design.
>
> An updated version of the BSL can be programmed to circumvent this issue.

COMP10   *COMP_B Module*

Category   Functional

Function   Comparator port output toggles when entering or leaving LPM3/LPM4

Description   The comparator port pin output (CECTL1.CEOUT) erroneously toggles when device enters or leaves LPM3/LPM4 modes under the following conditions:

1) Comparator is disabled (CECTL1.CEON = 0)

AND

2) Output polarity is enabled (CECTL1.CEOUTPOL = 1)

AND

3) The port pin is configured to have CEOUT functionality.

For example, if the CEOUT pin is high when the device is in Active Mode, CEOUT pin becomes low when the device enters LPM3/LPM4 modes.

Workaround	When the comparator is disabled, ensure at least one of the following:
	1) Output inversion is disabled (CECTL.CEOUTPOL = 0)
	OR
	2) Change pin configuration from CEOUT to GPIO with output low.

CPU21   *CPUXv2 Module*

Category	Compiler-Fixed
Function	Using POPM instruction on Status register may result in device hang up
Description	When an active interrupt service request is pending and the POPM instruction is used to set the Status Register (SR) and initiate entry into a low power mode , the device may hang up.
Workaround	None. It is recommended not to use POPM instruction on the Status Register.
	Refer to the table below for compiler-specific fix implementation information.

IDE/Compiler	Version Number	Notes
IAR Embedded Workbench	Not affected	
TI MSP430 Compiler Tools (Code Composer Studio)	v4.0.x or later	User is required to add the compiler or assembler flag option below. --silicon_errata=CPU21
MSP430 GNU Compiler (MSP430-GCC)	MSP430-GCC 4.9 build 167 or later	

CPU22   *CPUXv2 Module*

Category	Compiler-Fixed
Function	Indirect addressing mode with the Program Counter as the source register may produce unexpected results
Description	When using the indirect addressing mode in an instruction with the Program Counter (PC) as the source operand, the instruction that follows immediately does not get executed.
	For example in the code below, the ADD instruction does not get executed.

```
mov @PC, R7
add #1h, R4
```

Workaround	Refer to the table below for compiler-specific fix implementation information.

IDE/Compiler	Version Number	Notes
IAR Embedded Workbench	Not affected	
TI MSP430 Compiler Tools (Code Composer Studio)	v4.0.x or later	User is required to add the compiler or assembler flag option below. --silicon_errata=CPU22
MSP430 GNU Compiler (MSP430-GCC)	MSP430-GCC 4.9 build 167 or later	

CPU40   *CPUXv2 Module*

Category   Compiler-Fixed

Function   PC is corrupted when executing jump/conditional jump instruction that is followed by instruction with PC as destination register or a data section

Description   If the value at the memory location immediately following a jump/conditional jump instruction is 0X40h or 0X50h (where X = don't care), which could either be an instruction opcode (for instructions like RRCM, RRAM, RLAM, RRUM) with PC as destination register or a data section (const data in flash memory or data variable in

RAM), then the PC value is auto-incremented by 2 after the jump instruction is executed; therefore, branching to a wrong address location in code and leading to wrong program execution.

For example, a conditional jump instruction followed by data section (0140h).

@0x8012 Loop DEC.W R6

@0x8014 DEC.W R7

@0x8016 JNZ Loop

@0x8018 Value1 DW 0140h

Workaround   In assembly, insert a NOP between the jump/conditional jump instruction and program code with instruction that contains PC as destination register or the data section.

Refer to the table below for compiler-specific fix implementation information.

IDE/Compiler	Version Number	Notes
IAR Embedded Workbench	IAR EW430 v5.51 or later	For the command line version add the following information Compiler: --hw_workaround=CPU40 Assembler:-v1
TI MSP430 Compiler Tools (Code Composer Studio)	v4.0.x or later	User is required to add the compiler or assembler flag option below. --silicon_errata=CPU40
MSP430 GNU Compiler (MSP430-GCC)	Not affected	

CPU47   *CPUXv2 Module*

Category   Functional

Function   An unexpected Vacant Memory Access Flag (VMAIFG) can be triggered

Description   An unexpected Vacant Memory Access Flag (VMAIFG) can be triggered, if a PC-modifying instruction (e.g. - ret, push, call, pop, jmp, br) is fetched from the last addresses (last 4 or 8 byte) of a memory (e.g.- FLASH, RAM, FRAM) that is not contiguous to a higher, valid section on the memory map.

In debug mode using breakpoints the last 8 bytes are affected.

In free running mode the last 4 bytes are affected.

Workaround   Edit the linker command file to make the last 4 or 8 bytes of affected memory sections unavailable, to avoid PC-modifying instructions on these locations.

Remaining instructions or data can still be stored on these locations.

DMA4   *DMA Module*

Category   Functional

Function   Corrupted write access to 20-bit DMA registers

Description   When a 20-bit wide write to a DMA address register (DMAxSA or DMAxDA) is interrupted by a DMA transfer, the register contents may be unpredictable.

Workaround   1. Design the application to guarantee that no DMA access interrupts 20-bit wide accesses to the DMA address registers.

OR

2. When accessing the DMA address registers, enable the Read Modify Write disable bit (DMARMWDIS = 1) or temporarily disable all active DMA channels (DMAEN = 0).

OR

3. Use word access for accessing the DMA address registers. Note that this limits the values that can be written to the address registers to 16-bit values (lower 64K of Flash).

DMA7   *DMA Module*

Category   Functional

Function   DMA request may cause the loss of interrupts

Description   If a DMA request starts executing during the time when a module register containing an interrupt flags is accessed with a read-modify-write instruction, a newly arriving interrupt from the same module can get lost. An interrupt flag set prior to DMA execution would not be affected and remain set.

Workaround   1. Use a read of Interrupt Vector registers to clear interrupt flags and do not use read-modify-write instruction.

OR

2. Disable all DMA channels during read-modify-write instruction of specific module registers containing interrupts flags while these interrupts are activated.

DMA10   *DMA Module*

Category   Functional

Function   DMA access may cause invalid module operation

Description   The peripheral modules MPY, CRC, USB, RF1A and FRAM controller in manual mode can stall the CPU by issuing wait states while in operation. If a DMA access to the module occurs while that module is issuing a wait state, the module may exhibit undefined behavior.

Workaround   Ensure that DMA accesses to the affected modules occur only when the modules are not in operation. For example with the MPY module, ensure that the MPY operation is completed before triggering a DMA access to the MPY module.

EEM17   *EEM Module*

Category   Debug

Function   Wrong Breakpoint halt after executing Flash Erase/Write instructions

Description   Hardware breakpoints or Conditional Address triggered breakpoints on instructions that
                          follow Flash Erase/Write instructions, stops the debugger at the actual Flash Erase/Write
                          instruction even though the flash erase/write operation has already been executed. The
                          hardware/conditional address triggered breakpoints that are placed on either the next
                          two single opcode instructions OR the next double opcode instruction that follows the
                          Flash Erase/Write instruction are affected by this erratum.

Workaround   None. Use other conditional/advanced triggered breakpoints to halt the debugger right
                          after Flash erase/write instructions.

> **NOTE:**   This erratum affects debug mode only.

EEM19   *EEM Module*

Category   Debug

Function   DMA may corrupt data in debug mode

Description   When the DMA is enabled and the device is in debug mode, the data written by the DMA
                          may be corrupted when a breakpoint is hit or when the debug session is halted.

Workaround   This erratum has been addressed in MSPDebugStack version 3.5.0.1. It is also available
                          in released IDE EW430 IAR version 6.30.3 and CCS version 6.1.1 or newer.

                          If using an earlier version of either IDE or MSPDebugStack, do not halt or use
                          breakpoints during a DMA transfer.

> **NOTE:**   This erratum applies to debug mode only.

EEM21   *EEM Module*

Category   Debug

Function   LPMx.5 debug limitations

Description   Debugging the device in LPMx.5 mode might wake the device up from LPMx.5 mode
                          inadvertently, and it is possible that the device enters a lock-up condition; that is, the
                          device cannot be accessed by the debugger any more.

Workaround   Follow the debugging steps in Debugging MSP430 LPM4.5 SLAA424 .

EEM23   *EEM Module*

Category   Debug

Function   EEM triggers incorrectly when modules using wait states are enabled

Description   When modules using wait states (USB, MPY, CRC and FRAM controller in manual
                          mode) are enabled, the EEM may trigger incorrectly. This can lead to an incorrect profile
                          counter value or cause issues with the EEMs data watch point, state storage, and
                          breakpoint functionality.

Workaround   None.

> **NOTE:** This erratum affects debug mode only.

JTAG26 *JTAG Module*

Category Debug

Function LPMx.5 Debug Support Limitations

Description The JTAG connection to the device might fail at device-dependent low or high supply voltage levels if the LPMx.5 debug support feature is enabled. To avoid a potentially unreliable debug session or general issues with JTAG device connectivity and the resulting bad customer experience Texas Instruments has chosen to remove the LPMx.5 debug support feature from common MSP430 IDEs including TIs Code Composer Studio 6.1.0 with msp430.emu updated to version 6.1.0.7 and IARs Embedded Workbench 6.30.2, which are based on the MSP430 debug stack MSP430.DLL 3.5.0.1 http://www.ti.com/tool/MSPDS

TI plans to re-introduce this feature in limited capacity in a future release of the debug stack by providing an IDE override option for customers to selectively re-activate LPMx.5 debug support if needed. Note that the limitations and supply voltage dependencies outlined in this erratum will continue to apply.

For additional information on how the LPMx.5 debug support is handled within the MSP430 IDEs including possible workarounds on how to debug applications using LPMx.5 without toolchain support refer to Code Composer Studio User's Guide for MSP430 chapter F.4 and IAR Embedded Workbench User's Guide for MSP430 chapter 2.2.5.

Workaround 1. If LPMx.5 debug support is deemed functional and required in a given scenario:

a) Do not update the IDE to continue using a previous version of the debug stack such as MSP430.DLL v3.4.3.4.

OR

b) Roll back the debug stack by either performing a clean re-installation of a previous version of the IDE or by manually replacing the debug stack with a prior version such as MSP430.DLL v3.4.3.4 that can be obtained from http://www.ti.com/tool/MSPDS.

2. In case JTAG connectivity fails during the LPMx.5 debug mode, the device supply voltage level needs to be raised or lowered until the connection is working.

Do not enable the LPMx.5 debug support feature during production programming.

JTAG27 *JTAG Module*

Category Debug

Function Unintentional code execution after programming via JTAG/SBW

Description The device can unintentionally start executing code from uninitialized RAM addresses 0x0006 or 0x0008 after being programming via the JTAG or SBW interface. This can result in unpredictable behavior depending on the contents of the address location.

Workaround 1. If using programming tools purchased from TI (MSP-FET, LaunchPad), update to CCS version 6.1.3 later or IAR version 6.30 or later to resolve the issue.

2. If using the MSP-GANG Production Programmer, use v1.2.3.0 or later.

3. For custom programming solutions refer to the specification on MSP430 Programming Via the JTAG Interface User's Guide (SLAU320) revision V or newer and use

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MSPDebugStack v3.7.0.12 or later.

For MSPDebugStack (MSP430.DLL) in CCS or IAR, download the latest version of the development environment or the latest version of the MSPDebugStack

NOTE: This only affects debug mode.

PMAP1   *PMAP Module*

Category   Functional

Function   Port Mapping Controller does not clear unselected inputs to mapped module.

Description   The Port Mapping Controller provides the logical OR of all port mapped inputs to a module (Timer, USCI, etc). If the PSEL bit (PxSEL.y) of a port mapped input is cleared, then the logic level of that port mapped input is latched to the current logic level of the input. If the input is in a logical high state, then this high state is latched into the input of the logical OR. In this case, the input to the module is always a logical 1 regardless of the state of the selected input.

Workaround   1. Drive input to the low state before clearing the PSEL bit of that input and switching to another input source.

or

2. Use the Port Mapping Controller reconfiguration feature, PMAPRECFG, to select inputs to a module and map only one input at a time.

PMM9   *PMM Module*

Category   Functional

Function   False SVSxIFG events

Description   The comparators of the SVS require a certain amount of time to stabilize and output a correct result once re-enabled; this time is different for the Full Performance versus the Normal mode. The time to stabilize the SVS comparators is intended to be accounted for by a built-in event-masking delay of 2 us when Full Performance mode is enabled.

However, the comparators of the SVS in Full Performance mode take longer than 2 us to stabilize so the possibility exists that a false positive will be triggered on the SVSH or SVSL. This results in the SVSxIFG flags being set and depending on the configuration of SVSxPE bit a POR can also be triggered.

Additionally when the SVSxIFGs are set, all GPIOs are tri-stated i.e. floating until the SVSx comparators are settled.

The SVS IFG's are falsely set under the following conditions:

1. Wakeup from LPM2/3/4 when SVSxMD = 0 (default setting) && SVSxFP=1. The SVSx comparators are disabled automatically in LPM2/3/4 and are then re-enabled on return to active mode.

2. SVSx is turned on in full performance mode (SVSxFP=1).

3. A PUC/POR occurs after SVSx is disabled. After a PUC or POR the SVSx are enabled automatically but the settling delay does not get triggered. Based on SVSxPE bit this may lead to POR events until the SVS comparator is fully settled.

Workaround   For each of the above listed conditions the following workarounds apply:

1. If the Full Performance mode is to be enabled for either the high- or low-side SVS comparators, the respective SVSxMD bits must be set (SVSxMD = 1) such that the SVS

comparators are not temporarily shut off in LPM2/3/4. Note that this is equivalent to a 2 uA (typical) adder to the low power mode current, per the device-specific datasheet, for each SVSx that remains enabled.

2. The SVSx must be turned on in normal mode (SVSxFP=0). It can be reconfigured to use full performance mode once the SVSx/SVMx delay has expired.

3. Ensure that SVSH and SVSL are always enabled.

PMM11   *PMM Module*

Category	Functional
Function	MCLK comes up fast on exit from LPM3 and LPM4
Description	The DCO exceeds the programmed frequency of operation on exit from LPM3 and LPM4 for up to 6 us. This behavior is masked from affecting code execution by default: SVSL and SVML run in normal-performance mode and mask CPU execution for 150 us on wakeup from LPM3 and LPM4. However, when the low-side SVS and the SVM are disabled or are operating in full-performance mode (SVMLE = 0 and SVSLE = 0, or SVMLFP = 1 and SVSLFP = 1) AND MCLK is sourced from the internal DCO running over 4 MHz, 7 MHz, 11 MHz, or 14 MHz at core voltage levels 0, 1, 2, and 3, respectively, the mask lasts only 2 us. MCLK is, therefore, susceptible to run out of spec for 4 us.
Workaround	Set the MCLK divide bits in the Unified Clock System Control 5 Register (UCSCTL5) to divide MCLK by two prior to entering LPM3 or LPM4 (set DIVMx = 001). This prevents MCLK from running out of spec when the CPU wakes from the low-power mode. Following the wakeup from the low-power mode, wait 32, 48, 80, or 100 cycles for core voltage levels 0, 1, 2, and 3, respectively, before resetting DIVMx to zero and running MCLK at full speed [for example, __delay_cycles(100)].

PMM12   *PMM Module*

Category	Functional
Function	SMCLK comes up fast on exit from LPM3 and LPM4
Description	The DCO exceeds the programmed frequency of operation on exit from LPM3 and LPM4 for up to 6 us. When SMCLK is sourced by the DCO, it is not masked on exit from LPM3 or LPM4. Therefore, SMCLK exceeds the programmed frequency of operation on exit from LPM3 and LPM4 for up to 6 us. The increased frequency has the potential to change the expected timing behavior of peripherals that select SMCLK as the clock source.
Workaround	- Use XT2 as the SMCLK oscillator source instead of the DCO.
	or
	- Do not disable the clock request bit for SMCLKREQEN in the Unified Clock System Control 8 Register (UCSCTL8). This means that all modules that depend on SMCLK to operate successfully should be halted or disabled before entering LPM3 or LPM4. If the increased frequency prevents the proper function of an affected module, wait 32, 48, 80, or 100 cycles for core voltage levels 0, 1, 2, or 3, respectively, before re-enabling the module [for example, __delay_cycles(100)].

PMM14   *PMM Module*

Category	Functional

Function	Increasing the core level when SVS/SVM low side is configured in full-performance mode causes device reset
Description	When the SVS/SVM low side is configured in full performance mode (SVSMLCTL.SVSLFP = 1), the setting time delay for the SVS comparators is ~2us. When increasing the core level in full-performance mode; the core voltage does not settle to the new level before the settling time delay of the SVS/SVM comparator expires. This results in a device reset.
Workaround	When increasing the core level; enable the SVS/SVM low side in normal mode (SVSMLCTL.SVSLFP=0). This provides a settling time delay of approximately 150us allowing the core sufficient time to increase to the expected voltage before the delay expires.

PMM15   *PMM Module*

Category	Functional
Function	Device may not wake up from LPM2, LPM3, or LPM4
Description	Device may not wake up from LPM2, LPM3 or LMP4 if an interrupt occurs within 1 us after the entry to the specified LPMx; entry can be caused either by user code or automatically (for example, after a previous ISR is completed). Device can be recovered with an external reset or a power cycle. Additionally, a PUC can also be used to reset the failing condition and bring the device back to normal operation (for example, a PUC caused by the WDT).

This effect is seen when:

- A write to the SVSMHCTL and SVSMLCTL registers is immediately followed by an LPM2, LPM3, LPM4 entry without waiting the requisite settling time ((PMMIFG.SVSMLDLYIFG = 0 and PMMIFG.SVSMHDLYIFG = 0)).

or

The following two conditions are met:

- The SVSL module is configured for a fast wake-up or when the SVSL/SVML module is turned off. The affected SVSMLCTL register settings are shaded in the following table.

	SVSLE	SVSLMD	SVSLFP	AM, LPM0/1 SVSL state	Manual SVSMLACE = 0 / LPM2/3/4 SVSL State	Automatic SVSMLACE = 1 / LPM2/3/4 SVSL State	Wakeup Time LPM2/3/4
SVSL	0	x	x	OFF	OFF	OFF	$t_{WAKE-UP\ FAST}$
	1	0	0	Normal	OFF	OFF	$t_{WAKE-UP\ SLOW}$
	1	0	1	Full Performance	OFF	OFF	$t_{WAKE-UP\ FAST}$
	1	1	0	Normal	Normal	OFF	$t_{WAKE-UP\ SLOW}$
	1	1	1	Full Performance	Full Performance	Normal	$t_{WAKE-UP\ FAST}$
		SVMLE	SVMLFP	AM, LPM0/1 SVML state	Manual SVSMLACE = 0 / LPM2/3/4 SVML State	Automatic SVSMLACE = 1 / LPM2/3/4 SVML State	Wakeup Time LPM2/3/4
SVML	0	x		OFF	OFF	OFF	$t_{WAKE-UP\ FAST}$
	1	0		Normal	Normal	OFF	$t_{WAKE-UP\ SLOW}$
	1	1		Full Performance	Full Performance	Normal	$t_{WAKE-UP\ FAST}$

and

-The SVSH/SVMH module is configured to transition from Normal mode to an OFF state when moving from Active/LPM0/LPM1 into LPM2/LPM3/LPM4 modes. The affected SVSMHCTL register settings are shaded in the following table.

| | SVSHE | SVSHMD | SVSHFP | AM, LPM0/1 SVSH state | Manual SVSMHACE = 0 | Automatic SVSMHACE = 1 |
					LPM2/3/4 SVSH State	LPM2/3/4 SVSH State
SVSH	0	x	x	OFF	OFF	OFF
	1	0	0	Normal	OFF	OFF
	1	0	1	Full Performance	OFF	OFF
	1	1	0	Normal	Normal	OFF
	1	1	1	Full Performance	Full Performance	Normal

| | SVMHE | SVMHFP | | AM, LPM0/1 SVMH state | Manual SVSMHACE = 0 | Automatic SVSMHACE = 1 |
					LPM2/3/4 SVMH State	LPM2/3/4 SVMH State
SVMH	0	x		OFF	OFF	OFF
	1	0		Normal	Normal	OFF
	1	1		Full Performance	Full Performance	Normal

Workaround
Any write to the SVSMxCTL register must be followed by a settling delay (PMMIFG.SVSMLDLYIFG = 0 and PMMIFG.SVSMHDLYIFG = 0) before entering LPM2, LPM3, LPM4.

and

1. Ensure the SVSx, SVMx are configured to prevent the issue from occurring by the following:

- Configure the SVSL module for slow wake up (SVSLFP = 0). Note that this will increase the wakeup time from LPM2/3/4 to twakeupslow (~150 us).

or

- Do not configure the SVSH/SVMH such that the modules transition from Normal mode to an OFF state on LPM entry and ensure SVSH/SVMH is in manual mode. Instead force the modules to remain ON even in LPMx. Note that this will cause increased power consumption when in LPMx.

Refer to the MSP430 Driver Library(MSPDRIVERLIB) for proper PMM configuration functions.

Use the following function, PMM15Check (void), to determine whether or not the existing PMM configuration is affected by the erratum. The return value of the function is 1 if the configuration is affected, and 0 if the configuration is not affected.

unsigned char PMM15Check (void)

{

// First check if SVSL/SVML is configured for fast wake-up

if ((!(SVSMLCTL & SVSLE)) || ((SVSMLCTL & SVSLE) && (SVSMLCTL & SVSLFP)) ||

(!(SVSMLCTL & SVMLE)) || ((SVSMLCTL & SVMLE) && (SVSMLCTL & SVMLFP)))

{ // Next Check SVSH/SVMH settings to see if settings are affected by PMM15

if ((SVSMHCTL & SVSHE) && (!(SVSMHCTL & SVSHFP)))

{

if ((!(SVSMHCTL & SVSHMD)) || ((SVSMHCTL & SVSHMD) &&

(SVSMHCTL & SVSMHACE)))

return 1; // SVSH affected configurations

}

if ((SVSMHCTL & SVMHE) && (!(SVSMHCTL & SVMHFP)) && (SVSMHCTL & SVSMHACE))

return 1; // SVMH affected configurations

}

return 0; // SVS/M settings not affected by PMM15

}

}

2. If fast servicing of interrupts is required, add a 150us delay either in the interrupt service routine or before entry into LPM3/LPM4.

PMM18   *PMM Module*

Category   Functional

Function   PMM supply overvoltage protection falsely triggers POR

Description   The PMM Supply Voltage Monitor (SVM) high side can be configured as overvoltage protection (OVP) using the SVMHOVPE bit of SVSMHCTL register. In this mode a POR should typically be triggered when DVCC reaches ~3.75V.

If the OVP feature of SVM high side is enabled going into LPM234, the SVM might trigger at DVCC voltages below 3.6V (~3.5V) within a few ns after wake-up. This can falsely cause an OVP-triggered POR. The OVP level is temperature sensitive during fail scenario and decreases with higher temperature (85 degC ~3.2V).

Workaround   Use automatic control mode for high-side SVS & SVM (SVSMHCTL.SVSMHACE=1). The SVM high side is inactive in LPM2, LPM3, and LPM4.

PMM20   *PMM Module*

Category   Functional

Function   Unexpected SVSL/SVML event during wakeup from LPM2/3/4 in fast wakeup mode

Description   If PMM low side is configured to operate in fast wakeup mode, during wakeup from LPM2/3/4 the internal VCORE voltage can experience voltage drop below the corresponding SVSL and SVML threshold (recommendation according to User's Guide) leading to an unexpected SVSL/SVML event. Depending on PMM configuration, this event triggers a POR or an interrupt.

> **NOTE:**   As soon the SVSL or the SVML is enabled in Normal performance mode the device is in slow wakeup mode and this erratum does not apply.
>
> In addition, this erratum has sporadic characteristic due to an internal asynchronous circuit. The drop of Vcore does not have an impact on specified device performance.

Workaround   If SVSL or SVML is required for application (to observe external disruptive events at Vcore pin) the slow wakeup mode has to be used to avoid unexpected SVSL/SVML events. This is achieved if the SVSL or the SVML is configured in "Normal" performance mode (not disabled and not in "Full" Performance Mode).

PORT15 *PORT Module*

Category Functional

Function In-system debugging causes the PMALOCKED bit to be always set

Description The port mapping controller registers cannot be modified when single-stepping or halting at break points between a valid password write to the PMAPWD register and the expected lock of the port mapping (PMAP) registers. This causes the PMAPLOCKED bit to remain set and not clear as expected.

Note: This erratum only applies to in-system debugging and is not applicable when operating in free-running mode.

Workaround Do not single step through or place break points in the port mapping configuration section of code.

PORT19 *PORT Module*

Category Functional

Function Port interrupt may be missed on entry to LPMx.5

Description If a port interrupt occurs within a small timing window (~1MCLK cycle) of the device entry into LPM3.5 or LPM4.5, it is possible that the interrupt is lost. Hence this interrupt will not trigger a wakeup from LPMx.5.

Workaround None

PORT33 *PORT Module*

Category Functional

Function P4.6 is not set to input floating if device is in RESET state

Description P4.6 is driven active low while the MSP430 device is held in a reset state. This can influence components connected externally that are expecting the pin to act as a floating input during MSP430 reset.

Workaround Use any other GPIO if input floating state is required while the device is in a reset state.

RTC3 *RTC Module*

Category Functional

Function Unreliable write to RTC register

Description A write access to the RTC registers (SEC, MIN, HOUR, DATE, MON, YEAR, DOW) may result in unexpected results. As a consequence the addressed register might not contain the written data, or some data can be accidentally written to other RTC registers.

Workaround Use the RTC library routines, available as F541x/F543x code examples on the MSP430 Code Examples page (www.ti.com/msp430 > Software > Code Examples), which use carefully aligned MOV instructions. Library is listed as RTC_Workaround.zip and includes both CCE and IAR example projects that show proper usage. Using this library, full access to RTC registers is possible.

RTC6	**RTC Module**
Category	Functional
Function	the step size of the RTC frequency adjustment is twice the specified size.
Description	In BCD mode of operation, the step size of the RTC frequency adjustment is =+8ppm/-4ppm. This is twice the size specified in the User's Guide.
	In BCD mode, for up calibration this results in a step size per step of 8ppm (1024 cycles) instead of 4ppm (512 cycles). For down calibration this results in a step size per step of 4ppm (512 cycles) instead of 2ppm (256 cycles).
	In Binary mode, the step size = +4ppm/-2ppm as per the spec.
Workaround	In BCD mode of operation, half the calibration value could be written into RTCCAL register to compensate the doubled step size.

SYS12	**SYS Module**
Category	Functional
Function	Invalid ACCVIFG when DVcc in the range of 2.4 to 2.6V
Description	A Flash Access Violation Interrupt Flag (ACCVIFG) may be triggered by the Voltage Changed During Program Error bit (VPE) when DVcc is in the range of 2.4 to 2.6V. However the VPE does not signify an invalid flash operation has occurred.
	If the ACCVIE bit is set and a flash operation is executed in the affected voltage range, an unnecessary interrupt is requested. The bootstrap loader also cannot be used to execute write/erase flash operations in this voltage range, because it exits the flash operation and returns an error on an ACCVIFG event.
Workaround	None

SYS16	**SYS Module**
Category	Functional
Function	Fast Vcc ramp after device power up may cause a reset
Description	At initial power-up, after Vcc crosses the brownout threshold and reaches a constant level, an abrupt ramp of Vcc at a rate dV/dT > 1V/100us can cause a brownout condition to be incorrectly detected even though Vcc does not fall below the brownout threshold. This causes the device to undergo a reset.
Workaround	Use a controlled Vcc ramp to power up the device.

UCS7	**UCS Module**
Category	Functional
Function	DCO drifts when servicing short ISRs when in LPM0 or exiting active from ISRs for short periods of time
Description	The FLL uses two rising edges of the reference clock to compare against the DCO frequency and decide on the required modifications to the DCOx and MODx bits. If the device is in a low power mode with FLL disabled (LPM0 with DCO not sourcing

ACLK/SMCLK or LPM2, LPM3, LPM4 where SCG1 bit is set) and enters a state which enables FLL (enter ISR from LPM0/LPM2 or exit active from ISRs) for a period less than 3x reference clock cycles, then the FLL will cause the DCO to drift.

This occurs because the FLL immediately begins comparing an active DCO with its reference clock and making the respective modifications to the DCOx and MODx bits. If the FLL is not given sufficient time to capture a full reference clock cycle (2 x reference clock periods) and adjust accordingly (1 x reference clock period), then the DCO will keep drifting each time the FLL is enabled.

Workaround   (1) If DCO is not sourcing ACLK or SMCLK in the application, use LPM1 instead of LPM0 to make sure FLL is disabled when interrupt service routine is serviced.

(2) When exiting active from ISRs, insert a delay of at least 3 x reference clock periods. To save on power budget, the 3 x reference clock periods could also be spent in LPM0 with TimerA or TimerB using ACLK/SMCLK sourced from DCO. This way, the FLL and DCO are still active in LPM0.

UCS9   *UCS Module*

Category   Functional

Function   Digital Bypass mode prevents entry into LPM4

Description   When entering LPM4, if an external digital input applied to XT1 in HF mode or XT2 is not turned off, the PMM does not switch to low-current mode causing higher than expected power consumption.

Workaround   Before entering LPM4:

(1) Switch to a clock source other than external bypass digital input.

OR

(2) Turn off external bypass mode (UCSCTL6.XT1BYPASS = 0).

UCS11   *UCS Module*

Category   Functional

Function   Modifying UCSCTL4 clock control register triggers an additional erroneous clock request

Description   Changing the SELM/SELS/SELA bits in the UCSCTL4 register will correctly configure the respective clock to use the intended clock source but might also erroneously set XT1/XT2 fault flag if the crystals are not present at XT1/XT2 or not configured in the application firmware. If the NMI interrupt for the OFIFG is enabled, an unintentional NMI interrupt will be triggered and needs to be handled.

> **NOTE:**   The XT1/XT2 fault flag can be set regardless of which SELM/SELS/SELA bit combinations are being changed.

Workaround   Clear all the fault flags in UCSCTL7 register once after changing any of the SELM/SELS/SELA bits in the UCSCTL4 register.

If OFIFG-NMI is enabled during clock switching, disable OFIFG-NMI interrupt during changing the SELM/SELS/SELA bits in the UCSCTL4 register to prevent unintended NMI.

Alternatively it can be handled accordingly (clear falsely set fault flags) in the Interrupt

Service Routine to ensure proper OFIFG clearing.

USCI26   *USCI Module*

Category   Functional

Function   Tbuf parameter violation in I2C multi-master mode

Description   In multi-master I2C systems the timing parameter Tbuf (bus free time between a stop condition and the following start) is not guaranteed to match the I2C specification of 4.7us in standard mode and 1.3us in fast mode. If the UCTXSTT bit is set during a running I2C transaction, the USCI module waits and issues the start condition on bus release causing the violation to occur.

Note: It is recommended to check if UCBBUSY bit is cleared before setting UCTXSTT=1.

Workaround   None

USCI35   *USCI Module*

Category   Functional

Function   Violation of setup and hold times for (repeated) start in I2C master mode

Description   In I2C master mode, the setup and hold times for a (repeated) START, $t_{SU,STA}$ and $t_{HD,STA}$ respectively, can be violated if SCL clock frequency is greater than 50kHz in standard mode (100kbps). As a result, a slave can receive incorrect data or the I2C bus can be stalled due to clock stretching by the slave.

Workaround   If using repeated start, ensure SCL clock frequencies is < 50kHz in I2C standard mode (100 kbps).

USCI39   *USCI Module*

Category   Functional

Function   USCI I2C IFGs UCSTTIFG, UCSTPIFG, UCNACKIFG

Description   Unpredictable code execution can occur if one of the hardware-clear-able IFGs UCSTTIFG, UCSTPIFG or UCNACKIFG is set while the global interrupt enable is set by software (GIE=1). This erratum is triggered if ALL of the following events occur in following order:

1. Pending Interrupt: One of the UCxIFG=1 AND UCxIE=1 while GIE=0

2. The GIE is set by software (e.g. EINT)

3. The pending interrupt is cleared by hardware (external I2C event) in a time window of 1 MCLK clock cycle after the "EINT" instruction is executed.

Workaround   Disable the UCSTTIE, UCSTPIE and UCNACKIE before the GIE is set. After GIE is set, the local interrupt enable flags can be set again.

Assembly example:

bic #UCNACKIE+UCSTPIE+UCSTTIE, UCBxIE ; disable all self-clearing interrupts

NOP

EINT

bis #UCNACKIE+UCSTPIE+UCSTTIE, UCBxIE ; enable all self-clearing interrupts

USCI40	***USCI Module***

Category Functional

Function SPI Slave Transmit with clock phase select = 1

Description In SPI slave mode with clock phase select set to 1 (UCAxCTLW0.UCCKPH=1), after the first TX byte, all following bytes are shifted by one bit with shift direction dependent on UCMSB. This is due to the internal shift register getting pre-loaded asynchronously when writing to the USCIA TXBUF register. TX data in the internal buffer is shifted by one bit after the RX data is received.

Workaround Reinitialize TXBUF before using SPI and after each transmission.

If transmit data needs to be repeated with the next transmission, then write back previously read value:

```
UCAxTXBUF = UCAxTXBUF;
```

8   Document Revision History

Changes from device specific erratasheet to document Revision A.

1. Errata PMM15 was added to the errata documentation.

Changes from document Revision A to Revision B.

1. Errata DMA10 was added to the errata documentation.
2. Errata BSL7 was added to the errata documentation.
3. Errata RTC3 was added to the errata documentation.

Changes from document Revision B to Revision C.

1. DMA10 Description was updated.
2. DMA10 Function was updated.

Changes from document Revision C to Revision D.

1. DMA10 Description was updated.
2. Errata EEM23 was added to the errata documentation.

Changes from document Revision D to Revision E.

1. SYS16 Description was updated.
2. Errata PMM15 was removed from the errata documentation.
3. Device TLV Hardware Revision information added to erratasheet.

Changes from document Revision E to Revision F.

1. Errata PMM20 was added to the errata documentation.
2. Errata USCI35 was added to the errata documentation.

Changes from document Revision F to Revision G.

1. BSL7 Workaround was updated.
2. BSL7 Function was updated.
3. Errata SYS12 was added to the errata documentation.

Changes from document Revision G to Revision H.

1. EEM19 Workaround was updated.
2. EEM17 Workaround was updated.
3. EEM23 Workaround was updated.
4. EEM17 Description was updated.
5. Errata BSL11 was added to the errata documentation.
6. EEM23 Description was updated.
7. Errata ADC39 was added to the errata documentation.
8. EEM19 Description was updated.

Changes from document Revision H to Revision I.

1. DMA10 Workaround was updated.
2. DMA10 Description was updated.
3. DMA10 Function was updated.

Changes from document Revision I to Revision J.

1. CPU40 Workaround was updated.
2. EEM19 Workaround was updated.
3. Errata USCI39 was added to the errata documentation.
4. Package Markings section was updated.
5. EEM23 Workaround was updated.
6. EEM23 Description was updated.

7. Errata ADC42 was added to the errata documentation.

8. EEM23 Function was updated.

9. EEM19 Description was updated.

Changes from document Revision J to Revision K.

1. Errata USCI40 was added to the errata documentation.

2. Errata DMA7 was added to the errata documentation.

3. PMM18 Workaround was updated.

Changes from document Revision K to Revision L.

1. DMA7 Workaround was updated.

2. EEM23 Description was updated.

3. DMA7 Description was updated.

Changes from document Revision L to Revision M.

1. USCI39 Description was updated.

Changes from document Revision M to Revision N.

1. Errata JTAG26 was added to the errata documentation.

Changes from document Revision N to Revision O.

1. EEM19 Workaround was updated.

Changes from document Revision O to Revision P.

1. RTC6 Description was updated.

2. UCS11 Workaround was updated.

3. UCS11 Description was updated.

4. UCS11 Function was updated.

Changes from document Revision P to Revision Q.

1. Errata SYS12 was removed from the errata documentation.

2. Errata JTAG27 was added to the errata documentation.

3. Errata COMP10 was added to the errata documentation.

Changes from document Revision Q to Revision R.

1. Errata SYS12 was added to the errata documentation.

2. USCI39 Workaround was updated.

Changes from document Revision R to Revision S.

1. CPU21 was added to the errata documentation.

2. CPU22 was added to the errata documentation.

3. PMM15 was added to the errata documentation.

4. Workaround for CPU40 was updated.

Changes from document Revision S to Revision T.

1. Workaround for PMM15 was updated.

Changes from document Revision T to Revision U.

1. PORT33 was added to the errata documentation.

Changes from document Revision U to Revision V.

1. Description for RTC6 was updated.

2. Workaround for RTC6 was updated.

Changes from document Revision V to Revision W.

1. Erratasheet format update.

2. Added errata category field to "Detailed bug description" section

Changes from document Revision W to Revision X.

1. Workaround for CPU40 was updated.

Changes from document Revision X to Revision Y.

1. CPU47 was added to the errata documentation.

2. ADC69 was added to the errata documentation.