

Establishing a Precise Current Limiter Over Wide Operation Voltages in Buck-Boost Converters



Stefan Schimonsky, Hassan Jamal

Introduction

The [LM5177 buck-boost controller](#) uses two cascaded control loops to regulate the output voltage and current of the converter to the desired value. The outer loop is the voltage regulation loop, and the inner loop is the current regulation loop. [Figure 1](#) illustrates the control loops for the buck-boost controller.

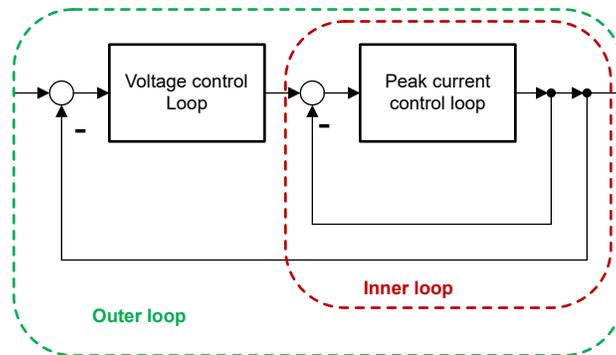


Figure 1. Overview of Cascaded Control Loops

The inductor current is an essential element in the voltage regulation loop to produce the required PWM for the power stage. Thus, to measure the inductor peak current, shunt resistance (R_{CS}) is used. The differential voltage across the R_{CS} is fed to the differential amplifier to generate a corresponding voltage ramp (V_{sense}). There is a default maximum threshold for differential peak voltage for every buck-boost controller. In case, the differential peak voltage exceeds this voltage threshold the inductor current will limit to the corresponding peak current value. The peak current limit can be changed by selecting different values for the R_{CS} resistance. The block diagram for the peak current limit is shown in [Figure 2](#).

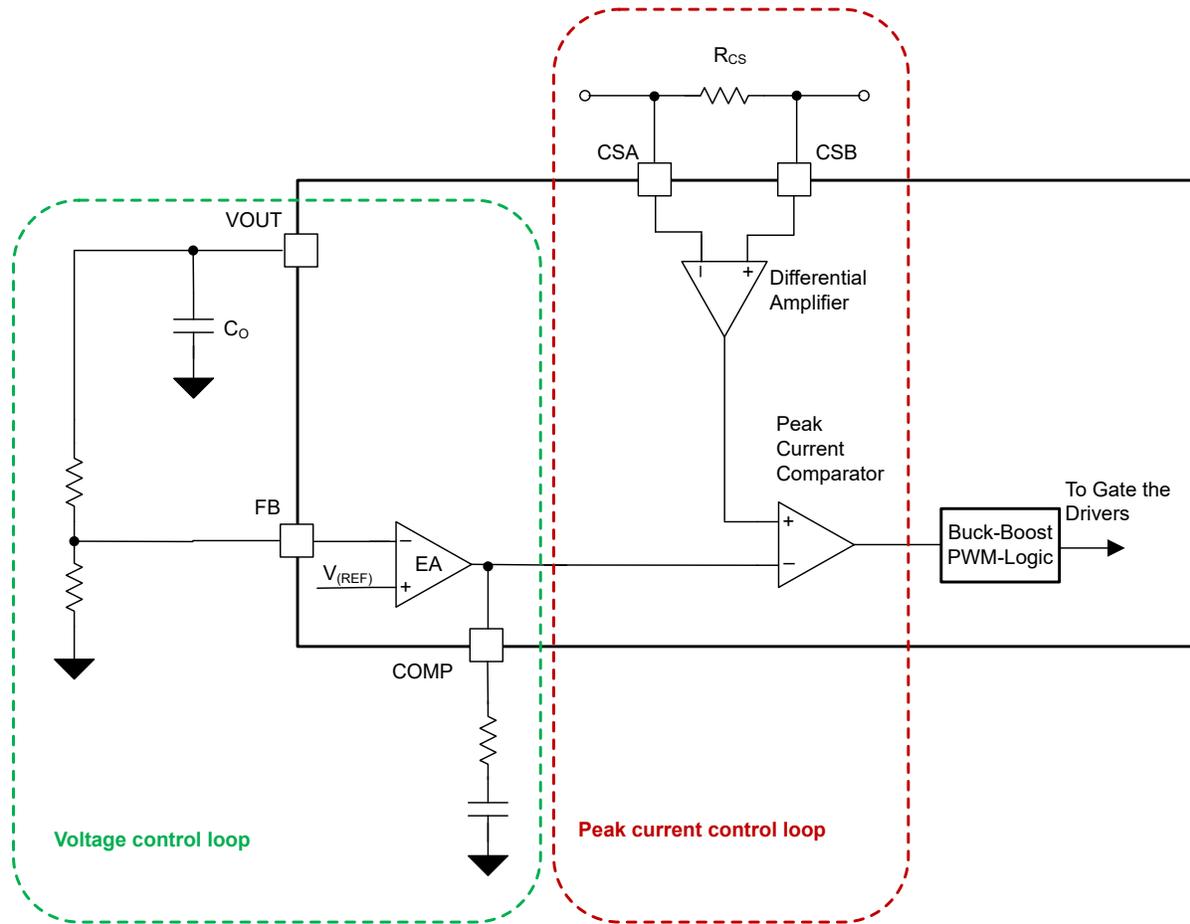


Figure 2. Block Diagram for Inductor Peak Current Loop

The peak current limit feature uses the inductor peak current to regulate the output load current for the power supply. Hence, it has numerous limitations in contrast to the average current limit feature. The bandwidth of the peak current limit comparator is the highest among other control loops in the controller, but due to the compensation limitations of the voltage loop, the overall bandwidth of the voltage regulation loop is less. Apart from this, it is a function of many applicative parameters such as switching frequency, inductor value, modes (buck, boost, and buck-boost), and so on. Thence, these dependencies restrict the operative range of the peak current limit and cause inaccuracy in its current protection threshold, thereby the average current limit feature will expand as a beneficial alternative to a sole peak current limit.

The average current limit has a control loop in the buck-boost controller, and it has a default priority over other control loops. If an average current limit loop is active, the current sense amplifier for the average current limit monitors the differential voltage across the sense resistor R_{ISNS} and compares this value with an internal reference voltage. If the drop across the R_{ISNS} is greater than the reference threshold, the average current limit loop will overwrite the output value of the g_m stage in the voltage loop. This is done by regulating the peak current clamp value for the inductor peak current until the differential voltage is equal to the reference voltage. In such a way, the average current limit loop regulates and reduces the peak current capability of the DC/DC converter. The schematic of the average current limit loop is illustrated in [Figure 3](#).

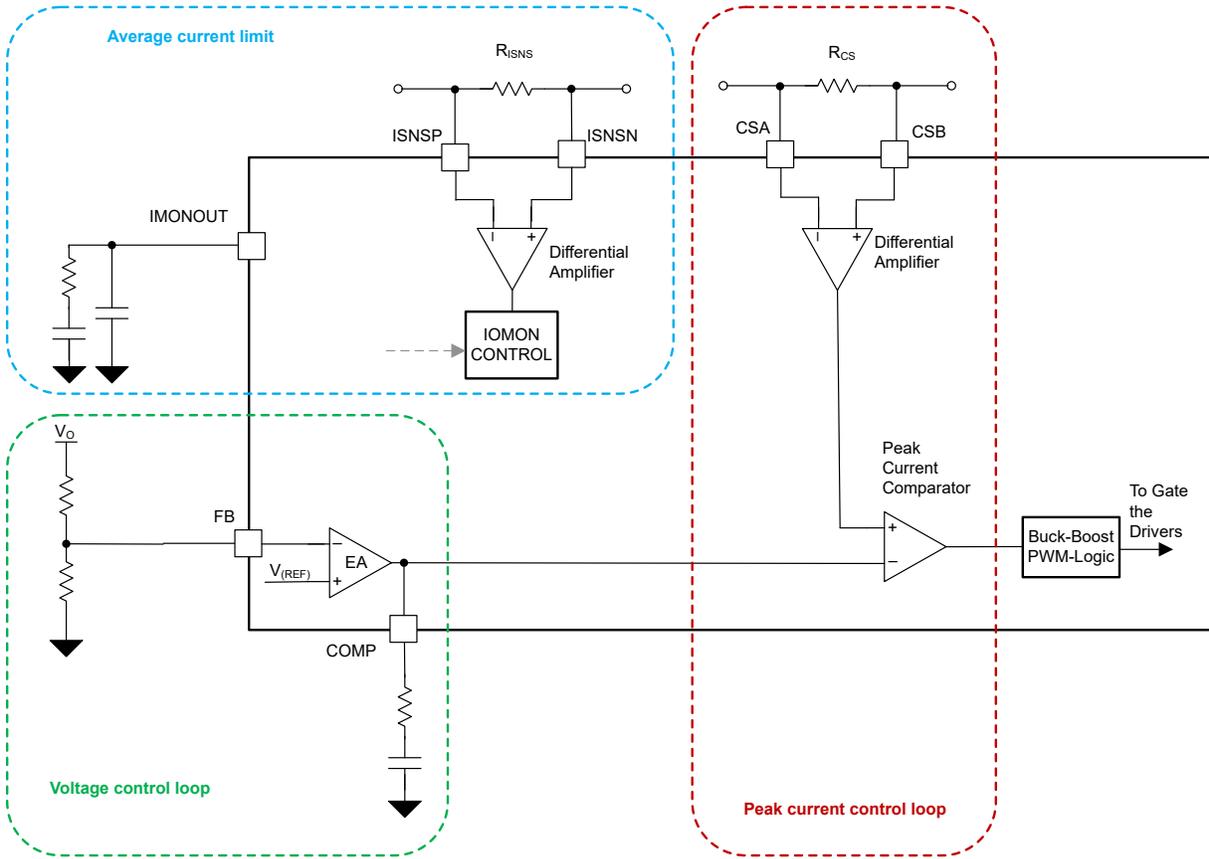


Figure 3. Block Diagram for Average Current Limit Loop

To enable the wide range of the average current limit of the power supply, an external shunt resistance R_{ISNS} is used for the average current limit loop. In addition to this, compensation is added at the IMONOUT- pin to enhance the stability of the average current limit loop with optimal performance for a wide range of applications or operating points. For most applications, a compensation bandwidth with a factor of 3 to 5 times faster than the compensation of the output voltage loop has given good results.

Application Demonstration

To validate the operation of the average current limit, a hardware test is conducted on the [LM5177 Buck-Boost Controller Evaluation Module](#). For this test, the buck-boost controller is set to operate the converter in boost mode with an output voltage of 12 V, and the applied input supply voltage is 6 V. To set a desired output voltage value, the voltage divider ratio at the feedback pin of the [LM5177 Buck-Boost Controller](#) needs to be changed accordingly. The first test is run without the average current limit, and this is the normal operation of the controller. The result in [Figure 4](#) shows that the inductor peak current increases with the load current, but the output voltage regulates around 12 V.

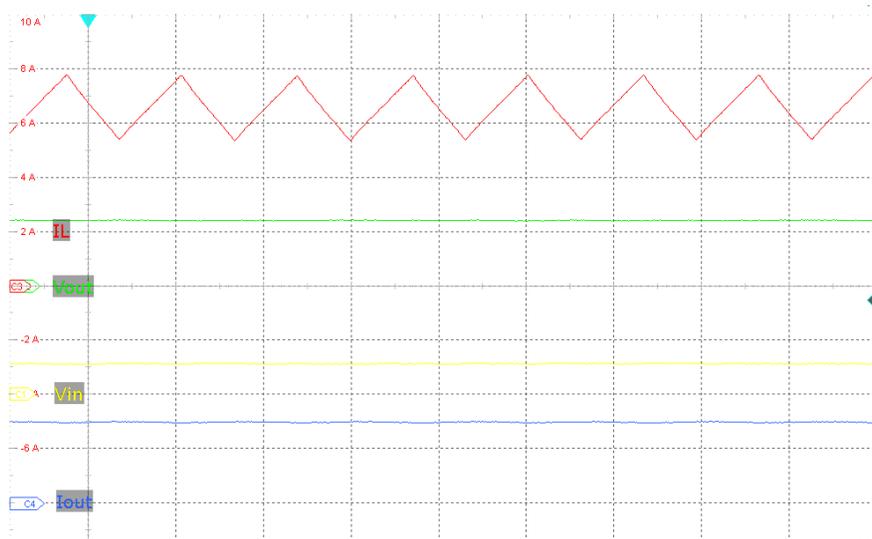


Figure 4. Boost Mode Without ILIM Operation

On the contrary, the test results shown in [Figure 5](#) depict the average current limit operation. The value set for the average current limiter is 3 A. Hence, the result confirms that the inductor peak current is clamped around 3 A, and the supply has a constant output current of 3 A. To regulate the supply output current, the supply output voltage can decrease down to 0 V with a further increase in the load current.

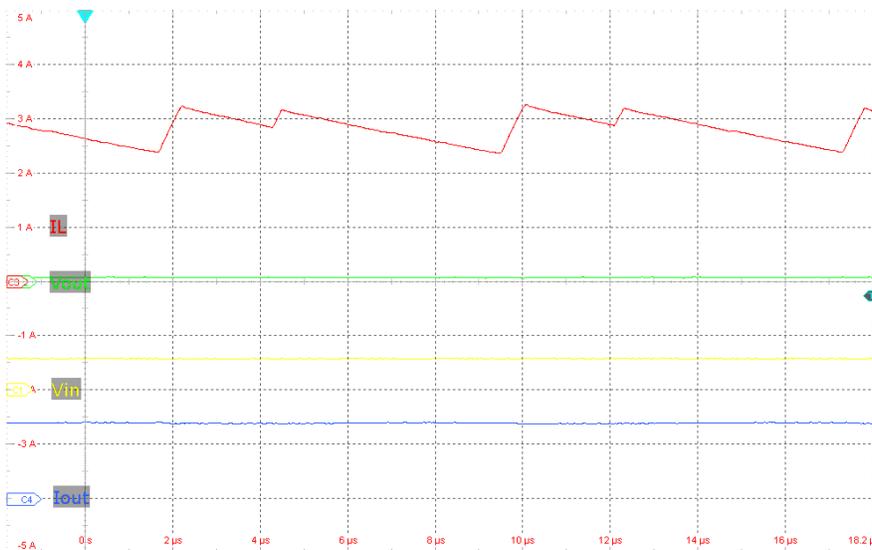


Figure 5. Boost Mode with ILIM Operation

The tests for peak and average current limiters were conducted for different topologies (buck, boost, and buck-boost) of the converter. The current regulation limit set for the average and peak current limiter is 3 A and 9 A, respectively. [Figure 6](#), [Figure 7](#), and [fontoxml-text-placeholder text="Type the link text"](#) demonstrate the results collected from these tests. It is evident from the results that the average current limit precisely and accurately regulates the output supply current at 3 A in the buck and buck-boost modes, but gives a slight inaccuracy in the value for the boost mode. On the contrary, a considerable deviation from the desired current regulation limit is observed for the peak current limit, in all three topologies. These deviations and inaccuracies in the peak current limit regulation is because of its dependency on many control parameters of the buck-boost controller (such as input voltage, switching frequency, and so on).

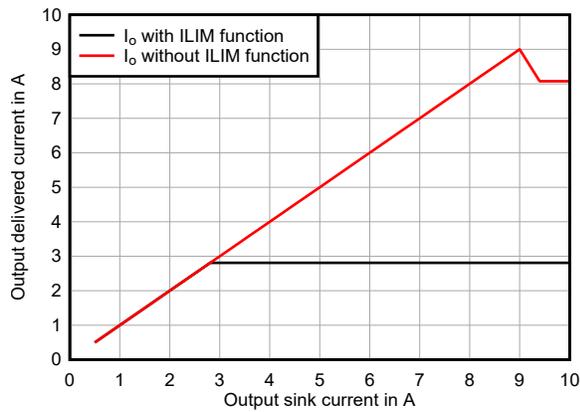


Figure 6. ILIM Boost Mode V_{IN} 6 V

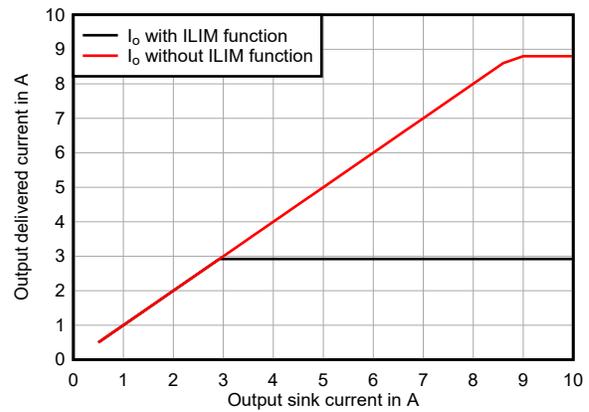


Figure 7. ILIM Buck Mode V_{IN} 24 V

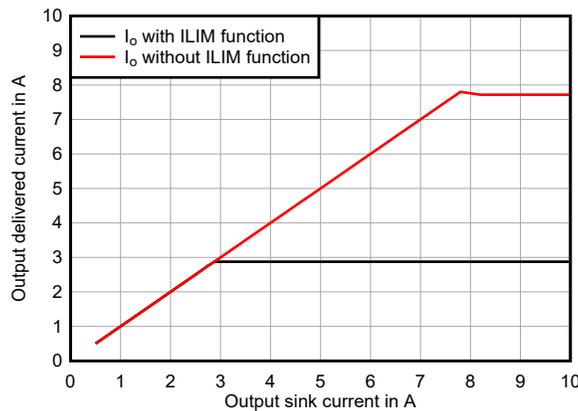


Figure 8. ILIM Buck Boost Mode V_{IN} 12 V

Summary

It is evident from the results that the average current limit feature of the buck-boost controller has a high response, accuracy, and precision compared to the peak current limit. Therefore, it is recommended to use this feature for systems that are critical to over-currents and short circuits. Further, the operational independence of the average current limiter from the control parameters of the buck-boost controller makes this feature a reliable constant current source for numerous applications.

References

- Texas Instruments, [LM5177 80-V Wide VIN Bidirectional 4-Switch Buck-Boost Controller](#), data sheet
- Texas Instruments, [LM5177 Buck-Boost Controller Evaluation Module](#), user's guide.

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to [TI's Terms of Sale](#) or other applicable terms available either on [ti.com](https://www.ti.com) or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2023, Texas Instruments Incorporated