Design Considerations for TIDA-00356

CC2541:

Versatile, well documented, low power, easy implementation, Automotive qualified

- This design utilizes the SAT0016 BLE module which is a complete design including crystals and PCB antenna, which greatly simplifies layout and design considerations. Primary layout considerations for the main board include minimizing distance to power capacitors and avoiding any excess metal or ground planes within close proximity to the module antenna.
- To prolong battery life, each input is configured to operate as an interrupt input rather than polling the switches periodically.
- The I2C pins are configurable as GPIOs, but interrupts are not available on the I2C pins. As such these pins were allocated to the two outputs in the design PWM and module LED.
- Pins 0 and 1 on Port 1 of the CC2541 do not have internal pull-downs, requiring external $10k\Omega$ resistors for this design.
- Each switch has a debounce capacitor, and for the debugging lines these capacitors can interfere with programming and debugging. For this design, the switches and debounce capacitors can be isolated from the module when the debugger is present via jumpers J5 and J7.

TPS79801Q:

Wide voltage input, connects directly to car battery, reverse input protection

The LDO is configured for 3V output via resistors R5 and R6.

TPS92638Q:

Wide voltage input, connects directly to car battery, 8 Channel output, low component count.

- For this application all PWM channels are tied together to a single GPIO. The LED driver is not operational off the Li-Ion battery, and the current in each channel is limited to 20mA via the reference resistor R11.
- Running the LED driver at the limited current for extended periods of time can generate significant amounts of heat, and as such special layout considerations should be observed to ensure appropriate thermal dissipation.

TPD4E001Q:

Multiple channels with small footprint, simple integration

• These TPD devices require very little configuration and are capable of protecting the CC2541 from Level 4 Contact Discharge on each of the tactile switches.

Design Improvements:

This design utilizes all GPIOs available on the SAT0016 module. Multiplexing GPIOs or using a matrix keypad for user input would greatly simplify the design. Placing PWM on the I2C line requires software PWM to operate, should be moved to a pin with a hardware timer as per Table 7-1 in the CC2541 user guide:

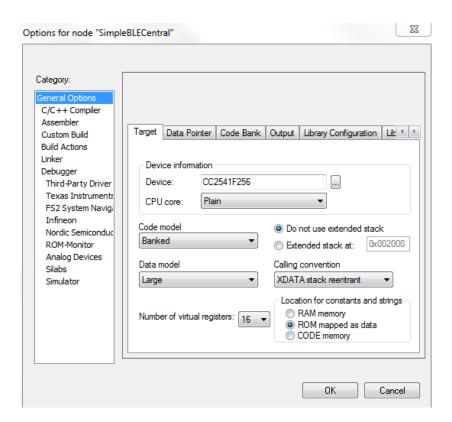
Table 7-1. Peripheral I/O Pin Mapping

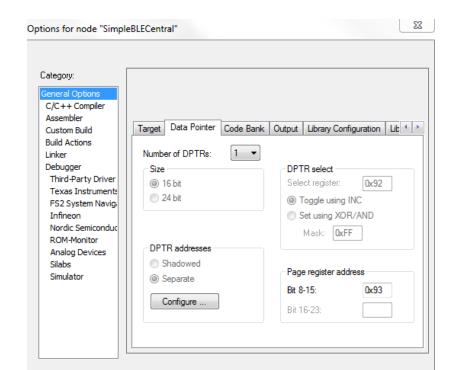
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|-----------|----------------|--|--------------|---|--|---|-------------------------------|------------------------------------|---|---|--|---|---|---|---|--|---|--|--|---|---|
| | P0 | | | | | | | | P1 | | | | | | | | P2 | | | | |
| | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | 4 | 3 | 2 | 1 | 0 |
| | Α7 | A6 | A5 | A4 | A3 | A2 | A1 | A0 | | | | | | | | | | | | | Т |
| | | | | | | 0 | - | + | | | | | | | | | | | | | |
| | | | + | - | | | | | | | | | | | | | | | | | |
| 1 | | | С | SS | MO | MI | | | | | | | | | | | | | | | |
| . 2 | | | | | | | | | | | M0 | MI | С | SS | | | | | | | |
| | | | RT | СТ | TX | RX | | | | | | | | | | | | | | | |
| . 2 | | | | | | | | | | | TX | RX | RT | CT | | | | | | | |
| 1 | | | MI | M0 | С | SS | | | | | | | | | | | | | | | |
| . 2 | | | | | | | | | MI | M0 | С | SS | | | | | | | | | |
| | | | RX | TX | RT | СТ | | | | | | | | | | | | | | | |
| . 2 | | | | | | | | | RX | TX | RT | CT | | | | | | | | | |
| | | 4 | 3 | 2 | 1 | 0 | | | | | | | | | | | | | | | |
| . 2 | 3 | 4 | | | | | | | | | | | | 0 | 1 | 2 | | | | | |
| | | | | | | | | | | | | 1 | 0 | | | | | | | | |
| . 2 | | | | | | | | | 1 | 0 | | | | | | | | | | | |
| | | | | | | | | | | | | | | | 1 | 0 | | | | | |
| . 2 | | | | | | | | | | | | | | | | | | 1 | | | 0 |
| 2 | | | | | | | | | | | | | | | | | Q1 | Q2 | | | |
| \exists | | | | | | | | | | | | | | | | | | | DC | DD | |
| \dashv | | | | | | | | | | | 5 | 4 | 3 | 2 | 1 | 0 | | | | | |
| | .2 .2 .2 .2 .2 | 7 A7 | 7 6 A7 A6 | 7 6 5 A7 A6 A5 + C C 2 RT RT .2 RX .2 A4 3 .2 3 4 .2 | 7 6 5 4 A7 A6 A5 A4 + - C SS 2 RT CT .2 RX TX .2 RX TX .2 .2 .3 4 3 2 .2 .2 | 7 6 5 4 3 A7 A6 A5 A4 A3 + - C SS MO 2 RT CT TX RX TX RT RX TX RT 2 A 3 2 1 2 3 4 3 2 1 2 3 4 3 2 1 | 7 6 5 4 3 2 A7 A6 A5 A4 A3 A2 | 7 6 5 4 3 2 1 A7 A6 A5 A4 A3 A2 A1 | 7 6 5 4 3 2 1 0 A7 A6 A5 A4 A3 A2 A1 A0 | 7 6 5 4 3 2 1 0 7 A7 A6 A5 A4 A3 A2 A1 A0 + + + + | 7 6 5 4 3 2 1 0 7 6 A7 A6 A5 A4 A3 A2 A1 A0 + | 7 6 5 4 3 2 1 0 7 6 5 A7 A6 A5 A4 A3 A2 A1 A0 + - C SS MO MI RT CT TX RX RX TX RT CT RX TX RT CT RX TX RT CT A3 A2 A1 A0 MO C SS RX TX RT CT A4 A3 A2 A1 A0 MO C SS A4 A3 A2 A1 A0 A4 A3 A2 A1 A1 A0 A4 A3 A2 A1 A0 A4 A3 A2 A1 A1 A1 A0 A4 A3 A2 A1 | 7 6 5 4 3 2 1 0 7 6 5 4 A7 A6 A5 A4 A3 A2 A1 A0 + - | 7 6 5 4 3 2 1 0 7 6 5 4 3 A7 A6 A5 A4 A3 A2 A1 A0 + - | 7 6 5 4 3 2 1 0 7 6 5 4 3 2 1 0 7 6 5 4 3 2 1 0 7 6 7 6 7 6 7 7 6 7 7 7 7 7 7 7 7 7 7 | 7 6 5 4 3 2 1 0 7 6 5 4 3 2 1 A7 A6 A5 A4 A3 A2 A1 A0 | 7 6 5 4 3 2 1 0 7 6 5 4 3 2 1 0 A7 A6 A5 A4 A3 A2 A1 A0 + | 7 6 5 4 3 2 1 0 7 6 5 4 3 2 1 0 4 A7 A6 A5 A4 A3 A2 A1 A0 | 7 6 5 4 3 2 1 0 7 6 5 4 3 2 1 0 4 3 A7 A6 A5 A4 A3 A2 A1 A0 | 7 6 5 4 3 2 1 0 7 6 5 4 3 2 1 0 4 3 2 1 0 4 3 2 1 0 4 3 2 4 1 0 4 3 2 4 1 0 4 3 2 4 1 0 4 3 2 4 1 0 4 3 2 4 1 0 4 1 0 4 1 1 0 1 1 1 0 1 1 1 0 1 1 1 0 1 1 1 0 1 1 1 0 1 1 1 0 1 1 1 1 0 1 | 7 6 5 4 3 2 1 0 7 6 5 4 3 2 1 A7 A6 A5 A4 A3 A2 A1 A0 U |

SOFTWARE DESIGN CONSIDERATIONS:

Shunts present on jumpers J5 and J7 can cause errors and warnings during programming. Removing these shunts disconnects debounce capacitors from the Debug Data and Debug Clock lines and should eliminate many errors that only occur when attempting to debug or program the device.

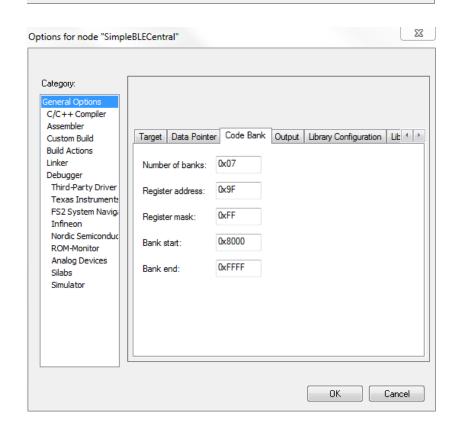
General IAR compiler warnings and errors: As this code had been built off of existing workspaces, many of the compiler options and settings have been pre-set. If however the code is being utilized as a reference, then special care should be taken to ensure that proper workspace options have been set. The following contains the full list of settings as of this document for **IAR version 8.20**, and serves only as a point of reference for future development and debugging. Some of these settings have been modified for debugging purposes and may not be required, and using these settings does not guarantee correct operation of the IAR compiler or software. For use with IAR version 8.30, know issues can arise with association to the linker file configuration.

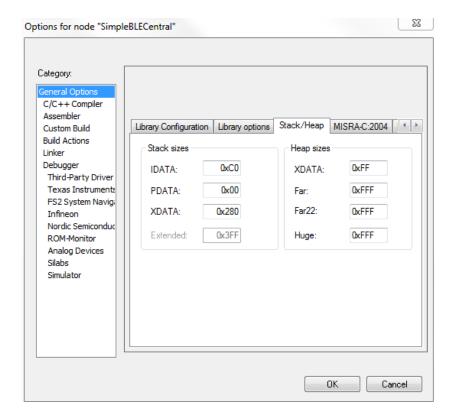


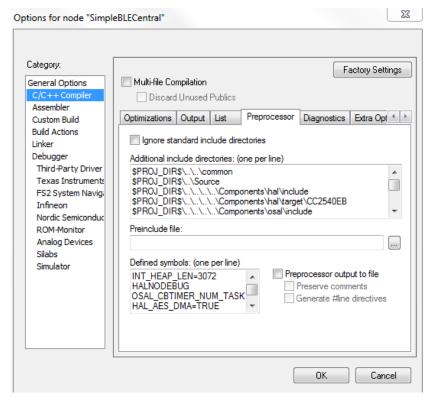


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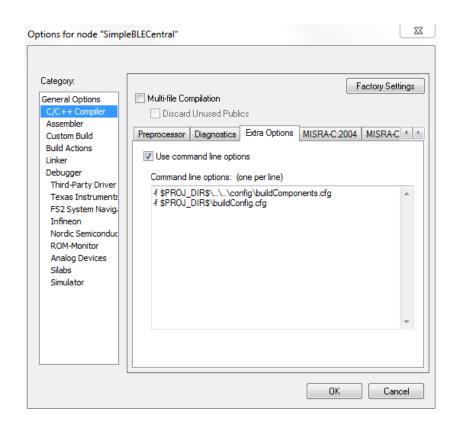
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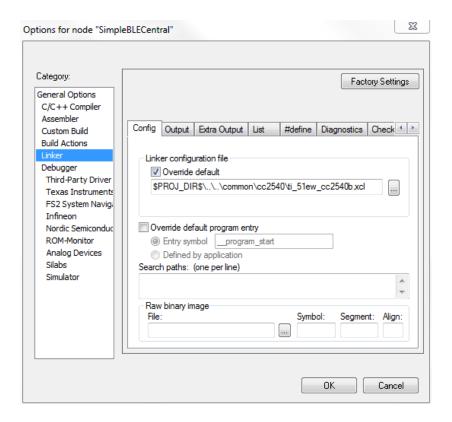






Additional Directories \$PROJ DIR\$\..\..\common \$PROJ DIR\$\..\Source $PROJ_DIR \ Components \ hal \ include$ \$PROJ_DIR\$\..\..\Components\hal\target\CC2540EB \$PROJ_DIR\$\..\..\Components\osal\include \$PROJ_DIR\$\..\..\Components\services\saddr \$PROJ_DIR\$\..\..\Components\ble\include \$PROJ_DIR\$\..\..\Components\ble\controller\phy \$PROJ_DIR\$\..\..\Components\ble\hci $\proj_DIR \host$ \$PROJ_DIR\$\..\..\common\cc2540 \$PROJ DIR\$\..\..\common\npi\npi np \$PROJ_DIR\$\..\..\Include \$PROJ DIR\$\..\..\Profiles\Roles \$PROJ_DIR\$\..\..\Profiles\SimpleProfile **Defined Symbols** INT HEAP LEN=3072 **HALNODEBUG** OSAL CBTIMER NUM TASKS=1 HAL_AES_DMA=TRUE HAL DMA=TRUE POWER SAVING HAL LCD=FALSE HAL LED=FALSE





If there are linker issues while using IAR version 8.30:

- Go to C:\Texas Instruments\BLE-CC254x 1.4.0\Projects\ble\common\cc2540\ti_51ew_cc2540b.xcl
- Change the line "-Z(DATA)VREG+_NR_OF_VIRTUAL_REGISTERS=08-7F" to "-Z(DATA)VREG=08-7F"

Note: IAR changed the way virtual registers are handled and placed. Therefore the linker configuration files must be updated

For more information on software development, including estimating memory size and debugging in IAR, please refer to document SWRU271 on the Texas Instruments website.

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