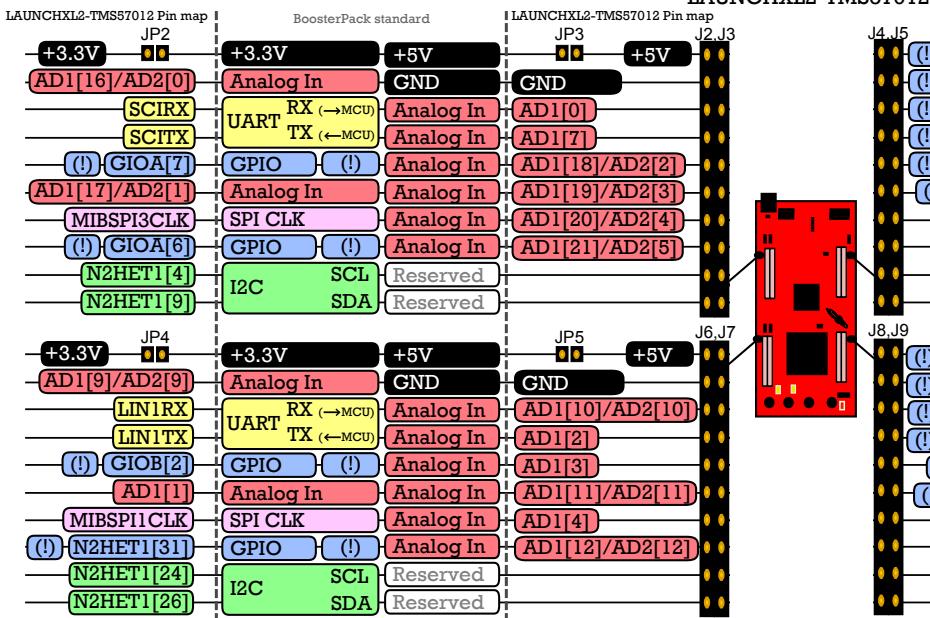


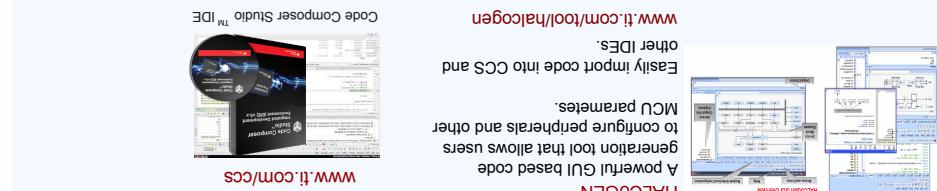


Resources
ti.com/launchpad



When using some BoosterPacks, JP2, 3, 4, or 5 may need to be removed. For example, using this LaunchPad with BoosterPack BOOSTXL-DRV8301 that includes a 3.3V regulator. To avoid conflict between the LaunchPad's 3.3V regulator and the regulator on the BoosterPack, JP2 (or JP4) should be removed.

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Software Tools

» See them all @ ti.com/boosterpacks



BoosterPack Ecosystem

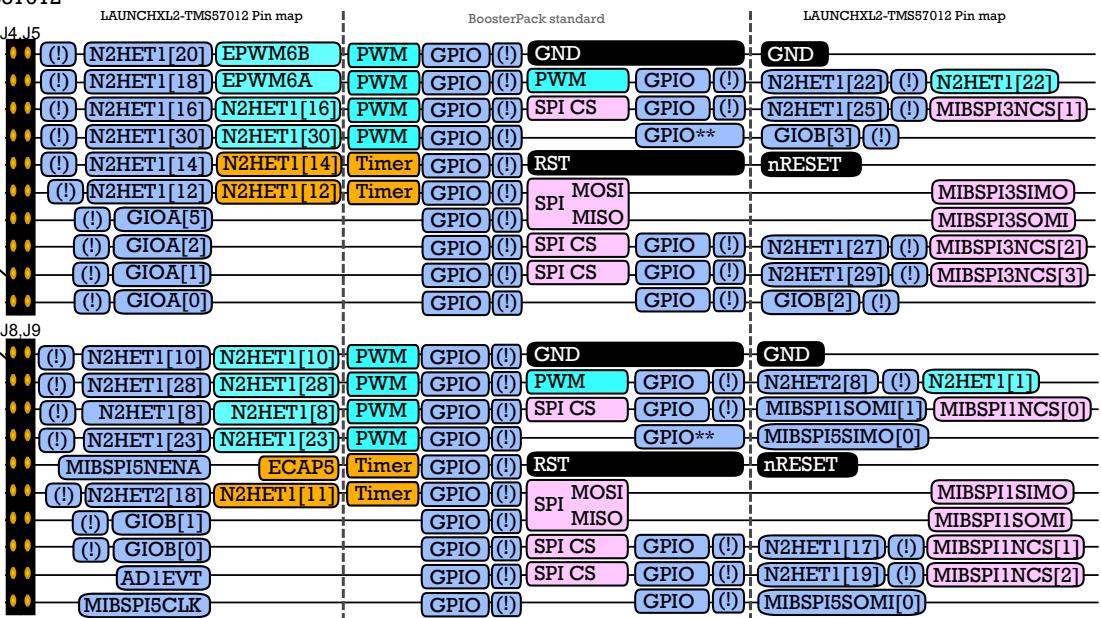
- Sensor Hub BoosterPack
- Invensense MPU-150 9-axis MEMS motion sensor
- 3-axis gyroscope
- 3-axis compass
- Bosch Sensorsic BMP180
- 3-axis Accelerometer
- 6-24V Supply Input
- Spin Any Three Phase Motor
- DRV8301 Motor Driver
- BoostPack
- 10A Continuous 14A Peak
- 10A Current Sensor
- Pressure Sensor
- Sensirion STTH23 humidity & ambient temperature sensor
- IR Ambient Light Sensor
- ISL29023 light & IR ambient light sensor



Below are the pins exposed @ the 2x BoosterPack connector sites.

Mapping to the booster pack standard is shown. In some cases a function can be either a GIO or another function, and may be listed twice (color coded as both GIO and again as the function). Additional functions beyond the booster pack standard may be available. For details consult the launchpad schematic.

(!!) Denotes I/O pins that are interrupt-capable.



Disclaimers: www.ti.com/lit/ssp2202

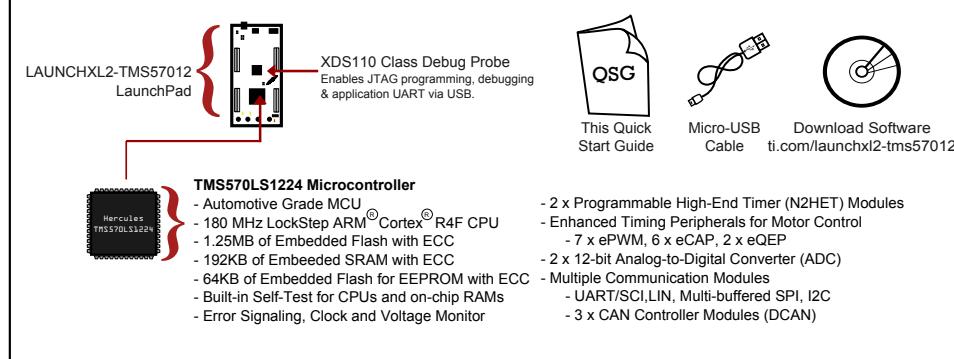
A closer look at your new LaunchPad Development Kit

Featured microcontroller: Hercules TMS570LS1224

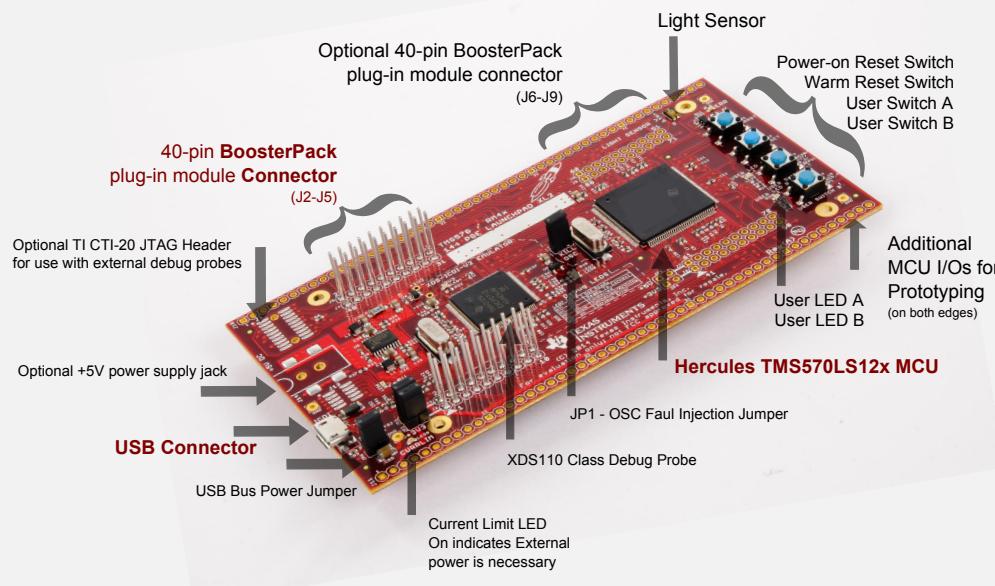
This LaunchPad is great for...

- Starting evaluation with Hercules TMS570 MCUs designed for ISO26262 and IEC61508 functional safety automotive and transportation applications.
- Getting hands-on experience with the MCU's hardware integrated safety and diagnostic features.
- Getting familiar with SafeTI software and development tools that ease development of functional safety applications.

What comes in the box?



LAUNCHXL2-TMS57012 Overview



Out-of-box Demo

Find more information @
ti.com/launchxl2-tms57012

1. (Optional) Installing Code Composer Studio (CCS)

The virtual COM port drivers that are required to see the console output of the out of box demo are bundled with CCS. If you wish to see this part of the demo, install CCS v6.0.1 or later before connecting the LaunchPad to the PC.

2. Connecting to a Computer and Powering the LaunchPad

The LaunchPad is configured by default to be USB powered (JP6 must be installed), which can be done by connecting the LaunchPad to a computer using the included USB cable. If you skipped the optional step 1, ignore any error/warning messages about missing drivers during this step.

3. (Optional) Opening a Terminal Program

If you completed step 1 and wish to see the console output of the demo, this is the time to configure the terminal program of your choice:

- > Select COM port identified as "XDS Class Application/User UART" from your computer's device manager.
- > Configure Baud Rate: 19200, Data Bits: 8, Stop Bits: 2 and Parity: None.

4. Running the Out-of-box Demo

This LaunchPad comes pre-programmed with a demo set that highlights several of MCU's safety features. When powered to the LaunchPad will start blinking USER LEDs.

Demo 1: An on-board Ambient Light Sensor is connected to the MCU's Analog Input 1. The USER LED B blinks according to the light intensity and a change in light intensity will cause it to blink faster or slower.

Demo 2: Shorting jumper JP1 will short the OSC to GND and cause an Oscillator Fault in the MCU. The on-chip monitor will detect and trigger an error signal causing the ERR LED to light up. **Note:** JP1 should be open during normal operation.

Demo 3: The push-button USER SWITCH B will inject a core compare error (CPU mismatch). An on-chip monitor will detect the fault and trigger an error signal causing the ERR LED to light up.

Demo 4: The push-button USER SWITCH A will inject a single bit error in the MCU's flash on every push. ECC logic corrects single bit errors in flash and counts them. The USER LED A blinks faster with every error detected. When a pre-programmed limit (6) is reached, the error signal is triggered and the ERR LED lights up.

When you are ready to take the next step, complete Project 0. For more information go to www.ti.com/launchpad and click on the Project 0 link for Hercules TMS570LS12x LaunchPad.



SafeTI™ Design Packages for Functional Safety

Find more information @
ti.com/safeti

SafeTI™ design packages help designers meet industry standard functional safety requirements while managing both systematic and random failures. Using SafeTI components helps make it easier for designers to achieve applicable end-product certification and get to market quickly with their safety critical systems which are pervasive in our world today.

- Complementary embedded processing and analog products that work together to help designer meet safety standards
- Safety development process certified suitable for use in development of IEC61508 and ISO26262 compliant semiconductors
- Safety related documentation: *Safety Analysis Report*, *Safety Manual* and *Safety Report*
- Safety Tools and Software (See below)

SafeTI Diagnostic Library

Software library of functions and response handlers for various safety features of the Hercules Safety MCUs.
Download: ti.com/tool/safeti_diag_lib

SafeTI Compiler Qualification Kit

Assists developers in qualifying their use of the TI ARM Compiler to functional safety standards such as IEC 61508 and ISO 26262.

Learn more: ti.com/tool/safeti_cqkit

SafeTI Compliance Support Packages

SafeTI Compliance Support Packages for HALCoGen and SafeTI Diagnostic Library provide the necessary documentation, reports and unit test capability to assist developers who need to comply with functional safety standards such as ISO 26262 and IEC 61508.



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